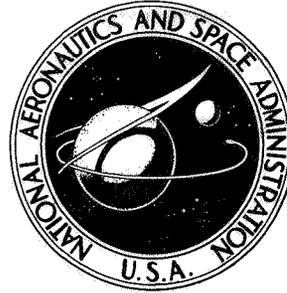


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DESIGN AND PERFORMANCE AT  
A LOCAL MACH NUMBER OF 6 OF AN INLET  
FOR AN INTEGRATED SCRAMJET CONCEPT

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16. Abstract <p>A research program on hypersonic propulsion at the NASA Langley Research Center is focused on the development of a concept for a modular supersonic combustion ramjet (Langley Scramjet Module), which is designed to integrate with the airframe of a hypersonic vehicle. The present paper reports the design philosophy and results of experiments at Mach 6 to evaluate the performance of the scramjet inlet. The inlet was designed with modest contraction ratio, fixed geometry, and three fuel injection struts which contribute to the inlet flow compression and provide a short combustor design that results in low internal cooling requirements. The baseline inlet configuration is rectangular in cross-sectional shape, has planar compression surfaces swept at 48°, and has an opening upstream of the cowl leading edge through which spillage occurs for starting. The inlet model has a projected geometric capture area measuring 19.05 cm high by 15.24 cm wide. The average throat Mach number was 3.1. The kinetic energy efficiency was 97.7 percent, and the average inlet aerodynamic contraction ratio was 7.0, which does not include the compression expected from the vehicle bow shock. The inlet captured 94 percent of the flow at its face; and, overall, the inlet performance was well within the acceptable range for high engine performance.</p>					
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DESIGN AND PERFORMANCE AT A LOCAL MACH NUMBER OF 6  
OF AN INLET FOR AN INTEGRATED SCRAMJET CONCEPT

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SUMMARY

A research program on hypersonic propulsion at the NASA Langley Research Center is focused on the development of a concept for a modular supersonic combustion ramjet (Langley Scramjet Module). The modular engine concept is designed to integrate with the airframe; precompression of the engine airflow will be produced by the vehicle bow shock and additional expansion of the nozzle exhaust will be produced by the vehicle afterbody. As part of this research program, component investigations are in progress on the baseline inlet configuration and the present paper reports the design philosophy and results of experiments at Mach 6 to evaluate the performance of the inlet.

With the integration advantages, the inlet was designed with modest contraction ratios and fixed geometry. Three fuel injection struts contribute to the inlet flow compression and provide a short combustor design that results in low internal cooling requirements. The baseline inlet configuration is rectangular in cross-sectional shape, has sweptback sidewall planar compression surfaces, has an opening upstream of the cowl leading edge through which spillage occurs for starting and normal operation, and has the external cowl surface aligned with the local flow to provide a minimal external drag. The inlet model had a projected geometric capture area measuring 19.05 cm high by 15.24 cm wide. The sidewalls and struts had  $48^\circ$  swept leading edges and nominal compression surface angles of  $6^\circ$ .

Tests were conducted in the Langley 20-inch Mach 6 tunnel and the inlet model was instrumented to obtain both wall and survey pressure measurements which were used in computing performance and capture flow. The data-reduction system provided integrated performance data as well as contour maps of parameters such as total-pressure recovery and Mach number in the inlet throat. The difficulty and importance of properly positioning the shock waves in the throats of hypersonic inlets were demonstrated, but no adverse effects were noted as a result of the inlet ingesting a boundary layer on the top surface which simulated the boundary layer that would be ingested from the vehicle forebody.

The average throat Mach number was 3.1 compared with the predicted value of 3.4. The kinetic energy efficiency was 97.7 percent (0.59 recovery) compared with prediction

of 98.3 percent (0.67 recovery), which did not account for all sources of total-pressure loss. The average inlet aerodynamic contraction ratio was 7.0, which does not include the compression expected from the vehicle bow shock. The inlet captured 94 percent of the flow at its face; and, overall, the inlet performance was well within the acceptable range for high engine performance.

## INTRODUCTION

The attractive potential of hypersonic flight with air-breathing propulsion has been recognized for the past 15 years; however, major advances in technology are required. Exploratory research on concepts for hypersonic air-breathing engines has been pursued in substantial research and development programs and a broad technology base has been established. See, for example, references 1 to 4. The investigation of several small-scale, hydrogen fueled, supersonic combustion ramjet (scramjet) engine designs has shown that the scramjet is a feasible engine concept and practical levels of thrust have been demonstrated (ref. 5). Hypersonic research and technology programs have been conducted (refs. 6 and 7) which illustrate the next logical step in scramjet evolution, which is the development of engine concepts which will integrate with the airframe. Integration includes the use of the vehicle forebody to precompress the engine airflow before it enters the inlet and the use of the vehicle afterbody for additional expansion and thrust vectoring of the nozzle exhaust gas. Other principal design criteria for hypersonic systems are minimum engine cooling requirements to make part of the heat sink of the hydrogen fuel available for active cooling of the airframe, fixed geometry to reduce weight and system complexity, and minimum external drag.

Detailed analytical and experimental studies at the Langley Research Center have resulted in the definition of the Langley Scramjet Module, with design features in both the inlet and combustor which will satisfy the engine design criteria, when the benefits of vehicle and propulsion system integration are included. This report deals primarily with the design and performance evaluation for the hypersonic inlet concept for the Langley Scramjet Module. The design criteria were met with the use of swept compression surfaces, which produced oblique shock waves, and a matching swept throat and combustor. Because of the complexity of the flow, it was necessary to optimize the selected inlet configuration from the experimental results of several earlier configuration studies. Once the concept was derived, computer programs aided in locating shock waves within the inlet, determined boundary-layer corrections to the interior walls, provided theoretical performance results, and reduced experimental test data.

A model of the inlet portion of the Langley Scramjet Module, 19.05 cm high by 15.24 cm wide, was tested in the Langley 20-inch Mach 6 wind tunnel. This test

condition represents local inlet face conditions for a flight Mach number of approximately 7.6 after compression from the vehicle forebody. The tunnel free-stream total temperature and pressure were 467 K and 11.9 atm (1 atm = 101.3 KN/m<sup>2</sup>), respectively, and provided a Reynolds number per meter of approximately  $9.8 \times 10^6$ . One run was made at a reduced Reynolds number per meter of  $3.3 \times 10^6$ .

### SYMBOLS

When two symbols are given for the same concept, the second one is that used for the computer data.

A	cross-sectional area of a stream tube
A*	cross-sectional area of a stream tube with sonic velocity
A/A <sub>1</sub>	aerodynamic contraction ratio, $\frac{A_1}{A_1^*} \frac{P_t}{P_{t,1}} \frac{A^*}{A}$
c,C	distance from cowl tip (fig. 13(d))
c',C'	distance from cowl leading edge (fig. 13(d))
H	inlet height, 19.05 cm (7.5 in.)
M	Mach number
p,P	static pressure
p <sub>1</sub> ,P <sub>1</sub>	static pressure in front of inlet
p <sub>t</sub>	total pressure
p <sub>pitot</sub> ,PITOT	pitot pressure
R	Reynolds number
s	distance from foreplate leading edge (fig. 13(a))

$s'$	distance from sidewall leading edge (fig. 13(c))
$s''$	distance from strut leading edge (figs. 13(e) to 13(g))
$T$	temperature
$T_{aw}$	adiabatic wall temperature
$T_t$	total temperature
$V$	velocity vector
$v$	velocity
$W$	throat gap or width of capture measurement station, cm (figs. 11 and 25)
$X$	distance downstream of intersection of sidewall with foreplate (fig. 13(b))
$x$	axis parallel to free-stream flow (fig. 57)
$Y$	distance from foreplate (fig. 13(c))
$y$	axis perpendicular to free-stream flow (fig. 57)
$Z$	distance away from model center line (figs. 13(a) and 13(d))
$Z'$	distance across throat or across duct (fig. 11)
$z$	axis perpendicular to free-stream flow and $y$ -axis (figs. 4 and 57)
$\delta$	boundary-layer thickness
$\delta_n$	flow turning angle normal to leading edge of swept wedge (fig. 57)
$\delta_{xy}$	cross-flow angle (fig. 57)
$\delta_{xz}$	wedge angle or flow turning angle in $xz$ -plane (fig. 57)

$\epsilon_{xz}$	shock-wave angle in xz-plane (fig. 57)
$\eta_k$	kinetic energy efficiency
$\Lambda$	sweep angle measured in xy-plane, deg
$\lambda$	distance around capture measurement station (fig. 62)
$\rho$	density
$\phi$	dihedral angle measured perpendicular to ridge line, deg
$\psi$	dihedral parameter

Subscripts:

1	conditions at inlet face or ahead of a shock wave
2,3,4	conditions behind 1st, 2d, and 3d shock waves, respectively
n	normal to leading edge (fig. 57)
t	tangential to leading edge (fig. 57)
$\infty$	free stream (in front of vehicle)

## INLET DESIGN CRITERIA AND CONCEPT

### Airframe-Engine Integration

The advantages of integrating the airframe and engine of a hypersonic vehicle are well known. The parametric analysis of reference 8 indicates that the contributions of the vehicle forebody and afterbody are responsible for up to 70 percent of the thrust. At hypersonic speeds very large engine airflows are required for adequate thrust in spite of the high-energy potential of the hydrogen fuel. These engine airflow requirements are best met by utilizing the precompression obtained from the vehicle forebody and locating the engine on the underside of the vehicle toward the aft end. (See fig. 1.) A method of designing the forebody is discussed in reference 6. The propulsion system inlet area is therefore restricted to the space between the vehicle undersurface and the bow shock and is several times wider than it is high, as shown in the cross section of figure 1. This

geometry concept suggests the arrangement of a number of adjacent rectangular engine modules, and the use of modules also permits development in ground test facilities of reasonable size. The relatively thick turbulent boundary layer generated on the vehicle forebody is an unfavorable characteristic which must be considered in the inlet design. The design of the vehicle afterbody, discussed in reference 7, is also important because of the large gross-thrust and moment forces involved, which can generate large trim drag penalties if not correctly considered.

### The Scramjet Engine

The primary objectives of the scramjet engine design are: to provide a high level of thrust and specific impulse with efficient capture over the flight Mach number range from 3.5 to 10, to have low cooling requirements in order to make a portion of the fuel heat sink available for active cooling of the vehicle structure at high Mach numbers, to have satisfactory operating characteristics over the Mach number range including the establishment of supersonic flow (starting) within the inlet at the low end of the Mach number range, to have fixed geometry in order to reduce system complexity as well as joint and seal problems, to ingest successfully the vehicle-forebody boundary layer, and to produce low external drag. Many of these objectives are interrelated and trade-offs discussed in reference 7 indicate that a fixed geometry inlet with moderate contraction for starting at a low Mach number is desirable. A moderate contraction and low internal pressure will not only mean a reduction in engine weight and cooling requirements but also an increased ability for the engine to ingest the vehicle-forebody boundary layer.

Because the use of only fuel injection from the sidewalls would produce very long mixing lengths for this type of modular design, the scramjet engine concept of figure 2 has three struts to provide six planes of instream fuel injection. This feature not only reduces cooling and shortens the combustor but also the inlet, since the struts provide a significant part of the inlet flow compression. The sidewalls are the main inlet compression surfaces, whereas the top surface partially eliminates expansions produced by the downflow created by the swept shock-wave system, which is a unique characteristic of the swept inlet design. The cowl is kept nearly parallel to the vehicle underbody to minimize external drag.

### The Inlet Concept

The inlet must efficiently compress the airflow captured for the combustor. Reference 7 indicates that a contraction ratio between 6 and 10 would be satisfactory for a fixed geometry inlet at a flight Mach number of about  $7\frac{1}{2}$ , and several inlet configurations were investigated which would fit into the area provided beneath the vehicle. Inlet interior walls consisting of swept planar surfaces were assumed; this assumption simplifies the analysis and avoids the need for three-dimensional characteristic computer programs.

Compression angles between  $6^\circ$  and  $8^\circ$  were employed; these angles are a compromise between high angles which contribute to high total-pressure losses from shock waves and increase the possibility of shock-induced boundary-layer separation and low compression angles which make the inlet long.

Prior to the development of the inlet shown in figure 2, a design utilizing swept compression surfaces in which the top surface was the primary compression surface was considered and is discussed in reference 9. Disadvantages to this design were: a corner flow problem originating at the top surface and covering much of the inlet throat; difficulty in obtaining good capture characteristics over the Mach number range; and no effective way of dealing with the vehicle-forebody boundary layer. Therefore sidewalls with swept leading edges were made the primary compression surface for the inlet in figure 2. Because planes of constant flow properties tend to be parallel to the sweep lines, the fuel injection struts and all downstream stations are also swept at the same angle. This design generates a system of swept shock waves which turns the flow away from the top surface and thus reduces the corner flow and boundary-layer problems on that surface. A cowl design which would provide 100-percent capture at high Mach numbers was tested on a preliminary design, and those results indicated that better starting and operating performance could be obtained with the pointed cowl leading edge located near the struts as shown in figure 2. Good capture characteristics can be obtained over the Mach number range with the fixed geometry design; and spillage, produced by the flow being turned toward the opening in front of the cowl by a transient shock system, permits starting at a low Mach number. The downflow produced by the sweep during normal operation tends to reduce the static-pressure rise near the top surface and should make possible the ingestion of the vehicle-forebody boundary layer without separation.

#### Inlet Starting

Inlet starting at the low end of the Mach number range is primarily a function of contraction ratio, which is influenced by the amount of sweep, the strut design, and the cowl leading-edge location. From simple one-dimensional considerations at an entrance Mach number of 3.0, an area contraction of less than 30 percent is necessary downstream of the plane of closure corresponding to the cowl leading edge. However, in figure 3 the normal plane B-B having the minimum cross-sectional flow area is shown to be located at the cowl leading edge; therefore, on the average there is no contraction downstream of the cowl leading edge. This is a strong indication that the inlet will have no starting problem, and early investigations of similar designs substantiate this conclusion.

The frontal height-width ratio also contributes to the starting characteristics of the inlet. If the width is greater than the height, the inlet is longer and end effects from the top surface and cowl begin to dominate the throat. If the width is much less than the height, the struts become slender and structural problems can appear. Based on

preliminary investigations, a width-height ratio of 0.8 was selected for the inlet design to reduce end effects and to permit a reasonable flight weight structure.

## INLET MODEL DESIGN

### Sweep Angle

In order to develop the swept shock-wave system for these inlet configurations, it was necessary to understand the process that the supersonic flow undergoes as it strikes a swept wedge. A detailed discussion of the calculation procedure for obtaining the shock-wave angle  $\epsilon_{xz}$ , downflow  $\delta_{xy}$ , and the flow properties behind the shock wave is given in reference 9, and a method for predicting the complete shock-wave train for the inlet is developed in appendix A.

A shock wave may be attached or detached depending on the sweep angle and Mach number; consequently, the sweep angle determines the lowest Mach number at which the shock waves can be attached at the strut leading edges. If the sweep is too high, low Mach number operation will result in shock waves being detached well upstream in the inlet ahead of the struts. These detached shock waves may create a situation where disturbances originating in the combustor may extend upstream of the struts locally and produce an undesirable inlet combustor interaction. Too little sweep means the internal contraction is high and no mechanism is provided for sufficient flow spillage for inlet starting at low Mach numbers. Because of the difficulty in analyzing inlet performance at low Mach numbers when the shock waves become detached, two models with struts were built and tested over the Mach number range of 2.3 to 6.0. These models had sweep angles of  $60^\circ$  and  $56^\circ$ . Several smaller models without struts but with sweeps of  $50^\circ$  and  $0^\circ$  were also tested at Mach 4. The results of these tests indicated that a sweep angle lower than  $50^\circ$  could be obtained with adequate starting capability and a sweep angle of  $48^\circ$  was selected.

### Mach 6 Shock-Wave System

The theoretical shock diagram for a Mach number of 6 is shown in figure 4 with tables for the various flow passages and struts within the inlet. Section A-A is a horizontal plane parallel to the vehicle underbody and cowl. The sidewall compression angle was kept low to prevent the possibility of boundary-layer separation due to boundary-layer—shock interactions. (See ref. 10.) A detail of the predicted shock-wave structure in the vicinity of the struts is given in figure 5, and the properties of each numbered bay are listed in table I. The struts provide approximately 75 percent of the inlet static-pressure rise (46-percent decrease in throat area measured in the xz-plane). The side struts were positioned within the inlet so that two-thirds of the flow area available was in front of the center passages. This flow division permits the fuel to be injected equally from the surfaces of both the center strut and side struts (only six injection planes).

Boundary-layer transition on the sidewalls is expected to occur ahead of the struts, and the correction of  $0.4^\circ$  (based on flat-plate predictions) in conjunction with the sidewall angle provides a nominal turning of  $6^\circ$ . Because the chords of the struts are small, the thin boundary layer of the struts is expected to be largely laminar in front of the throats, and separation of this thin boundary layer is expected to be of little consequence. Although it is impossible to prevent the sidewall shocks from merging with the strut shocks at some flight Mach number, the situation is relieved for the Mach 6 shock-wave system by changing the wall slope of the struts at appropriate locations and either canceling or reducing the shock strength.

### Inlet Design Performance

As previously mentioned, cooling requirements are a major consideration in combustor design and tend to limit the inlet contraction ratio. The inviscid design aerodynamic contraction ratio (which is computed from Mach number at the face of the inlet, throat Mach number, and total-pressure recovery) for the inlet at Mach 6 was 6.85 for the side passage (bay 6) and 7.57 for the center passage (bay 10) and yielded a mass flow weighted average theoretical contraction of 7.3. The geometric throat gaps between the struts are greater than those for a two-dimensional inlet of the same contraction, because a portion of the contraction is produced when the flow is turned toward the cowl ( $\delta_{xy}$  in table I). In this inlet design the ratio of throat gap to inlet height is 0.042 for each center passage and 0.041 for each boundary-layer-corrected side passage. The width ratio measured in the xz-plane sidewall leading edges to the throats is 5.74 for the inviscid side passages and 6.17 for the center passages when the predicted flow split of 67 percent for the center passage and 33 percent for the side passage is assumed.

In the inviscid flow the average throat Mach number is 3.4 and the total-pressure recovery is 0.88; as a result, there is an adiabatic kinetic energy efficiency of 99.5 percent. The inclusion of the estimated boundary-layer losses on the struts, sidewalls, and top surface reduces the total-pressure recovery to approximately 0.67 ( $\eta_k = 98.3$  percent); but this value still does not include corner effects. Inlet capture at Mach 6 was predicted to be 93 percent for the cowl location discussed in the next section. This predicted capture is based on the spillage generated when the flow is turned toward the opening in front of the cowl which is computed from matching pressure and flow direction between the external and internal streams.

### End Effects

Although no attempt was made to analyze viscous corner boundary-layer interaction regions in the inlet throat, inviscid calculations of the flow near the top surface and cowl were made. Because the flow is turned away from the top surface as it proceeds through the inlet, a fillet was added as shown in figure 6(a). To match precisely the downflow, the

top-surface contour must vary with local Mach number, but to avoid this complication, a single contour angle and position was selected. The angle was kept small ( $4^\circ$ ) to avoid shock interactions which could lead to separation of the thick, top-surface boundary layer. The leading edge of the top-surface fillet coincides with the location of the sidewall shocks with a Mach number of 5 in front of the inlet. With Mach 6 in front of the inlet, the top-surface fillet is upstream of the sidewall shock wave, and a  $4^\circ$  shock wave is produced as illustrated in section B-B of figure 6(a). At the throat the fillet displaces approximately the same amount of cross-sectional area as it would have if it had been on design for each bay, the Mach number in front of the inlet being equal to 6. The corrected values of flow parameters near the top surface for this constant-angle fillet are given in table II(a), where the angle of flow  $\delta_{xy}$  in each bay has been corrected to match the  $4^\circ$  slope.

When the internal flow strikes the cowl, the flow must be turned back parallel to the cowl internal surface; as a result, a cowl shock wave and a high-pressure region are produced. The results of this flow turning are given in table II(b) where  $\delta_{xy} = 0^\circ$ . To compensate partially for this high pressure, the throat area next to the cowl was opened by relieving the struts and sidewalls. (See fig. 6(b).) This relief area begins where the shock wave from the cowl leading edge strikes the struts and sidewalls, and because the center strut is located downstream of the cowl leading edge, the strut does not extend to the cowl surface. For the inlet model, this cantilevered center strut was secured to the cowl with a pin located behind the strut maximum thickness.

Selection of the proper cowl leading-edge shape was based upon previous model testing. Cowls which enclosed the area behind the sidewall shock waves providing 100-percent capture made the model difficult to start, produced a cowl shock covering most of the inlet throat, and generated a very large corner interaction region between the sidewalls and cowl. A partial cowl whose leading edges were swept back at  $50^\circ$  (fig. 6(c)) was selected, which provided an open area near the inlet throats. This open area permits spillage for low Mach number inlet starting and provides for some sidewall boundary-layer bleed. The exact location of the cowl relative to the struts was determined from additional model testing as described in a later section.

#### Off-Design Performance

Although the inlet is not a point design at a local Mach 6 in the conventional sense, it is designed to give the highest relative performance at this Mach number. As the Mach number is decreased as shown in figure 7, the shock-wave system shifts forward, and experimental observations on previous models indicate an increased spillage and lower aerodynamic contraction. For this design at a Mach number of about 3.5, the shock waves become detached from the strut leading edges. With this swept inlet concept, the aerodynamic contraction will increase with increasing Mach number until the shock waves are fully attached in the throat region. At still higher Mach numbers the number of shock

waves in the inlet decreases as they pass through the throat and the contraction begins to decrease slightly.

The combination of detached shock waves, with resulting spillage and variable contraction with Mach number, permits the inlet to have fixed geometry, to start at a low Mach number, and to provide enough contraction for successful operation at a high Mach number.

## APPARATUS AND TEST PROCEDURE

### The Inlet Model

A photograph of the inlet model designed with regard to the aforementioned concepts appears in figure 8. One sidewall has been removed in figure 8(a) and several pressure rakes can be seen. The model is shown upside down, and the 45.72-cm (18-in.) plate extending ahead of the sidewalls generates a simulated vehicle-forebody boundary layer. The boundary layer from this plate encounters early transition by trips located near the leading edge and the resulting boundary-layer profile entering the inlet is measured by a three-prong adjustable rake.

The model is 90.2 cm (35.5 in.) long not including the foreplate, and inlet frontal dimensions are 19.05 cm (7.5 in.) high by 15.24 cm (6.0 in.) wide. The aluminum top surface was machined in one piece, the foreplate being detachable. Assembly consisted of pinning and bolting the aluminum sidewalls to the top surface and then the stainless-steel cowl to the sidewalls in any one of three possible positions. Three stainless-steel struts were bolted in slots machined in the top surface which were then sealed. The struts were attached to the cowl by pins instead of bolts to reduce thermal stresses created by changes in the lengths of the struts and heights of the sidewalls. The normal to the leading-edge radii of the sidewalls, cowl, and struts was about 0.01 cm (0.004 in.), whereas the foreplate leading-edge radius was 0.06 cm (0.023 in.). Partially visible in the upper left of figure 8(b) is the actuator mechanism which moved pressure survey rakes inside the model.

Schematic drawings of the model are given in figure 9. Stainless-steel cheeks attached to the exterior of the sidewalls simulated adjacent inlet modules up to the inlet closeoff station next to the cowl. A survey station for measuring inlet capture was provided by a swept flat section of sidewall located downstream of the struts. A sidewall relief area next to the cowl is also illustrated, along with the footprint of the side struts on the cowl in section D-D. Detailed strut dimensions (fig. 10) and the relative positions of the struts and cowl (fig. 11) are measured in any xz-plane parallel to the foreplate and away from the relieved area near the cowl. The "station" positions are relative to the sidewall leading edges in the same xz-plane. A second center strut, which provides an

increase in contraction, is also described in figure 10. The difference in contour for this second center strut is similarly shown by the dashed lines on some subsequent figures in the report.

### Boundary-Layer Trips

To insure a turbulent boundary layer entering the throat passages, boundary-layer trips were attached to the sidewalls as well as to the foreplate. (See fig. 12.) The diameter of the steel balls (0.159 cm) was approximately equal to the estimated, flat-plate, boundary-layer thickness measured 7.6 cm downstream from the foreplate leading edge. The balls were spotwelded to steel strips which were in turn fastened with epoxy to the aluminum surfaces. The trips on the foreplate were utilized to increase the thickness of the boundary layer which would be entering the inlet, to determine whether there were any adverse effects associated with ingesting the boundary layer of a vehicle forebody.

### Model Instrumentation

Figure 13 locates the 116 static-pressure orifices distributed throughout the inlet model. The orifices were strategically located to determine inlet starting, pinpoint shock-wave position, and aid in evaluating inlet contraction. Because of the variety of locations, the position reference varies for each group of orifices. Iron-constantan thermocouples were installed in the right sidewall as shown in figure 14. Each thermocouple lead was spotwelded to the aluminum surface instead of the leads being welded together, in order to determine more precisely the surface temperature.

### Pressure Survey Rakes

The three-pronged foreplate boundary-layer probe is described in figure 15. This probe, aligned with the sidewall leading edge at  $Y/H = 0$  and  $Z/H = 0.133$ , was adjusted in height between tests to obtain detailed inlet entrance conditions near the top surface. The remaining survey probes were positioned laterally, by an electric motor and actuator attached to the model (fig. 16), in one of five access locations. Locations 1 to 4 provided for probe surveys across the inlet's throats, whereas location 5 provided access to the capture measurement station downstream of the struts. Tubing for the throat survey probes (fig. 17) was routed through the hollow actuator shaft, whereas capture measurement probe (fig. 18) tubes were carried out the rear of the model as illustrated in figure 8(a). The throat pitot probes were designed to survey one side and one center passage simultaneously, and the static survey probe surveyed only one center passage. It was necessary to rely on wall static data for the side passage. The capture measurement station 6.35 cm (2.5 in.) downstream from the struts was surveyed by the seven-prong

pitot and static probes of figure 18(a). A single, stationary tube (0.102 cm I.D.) extended through the top surface and was bent toward the flow to obtain pitot pressure data in the front of a center passage near the top surface. This tube was bent to different locations across the passage between test runs.

Because of the static-pressure gradients in the small throat area to be surveyed, a conventional static-pressure probe, with the orifices located 10 to 20 diameters downstream from the tip, was found to be unsatisfactory. Therefore, a new static probe design (ref. 11), with the orifices approximately 3 tube diameters downstream from the probe tip and on a  $3^\circ$  conical shoulder, was used for both the throat and capture measurement surveys. These static-pressure probes were calibrated at a Mach number of 4.0, and the recorded pressures were found to be in error by less than 5 percent.

### Mach 6 Test Facility

Figure 19 is a sketch of the Langley 20-inch Mach 6 tunnel. Tunnel test-section characteristics and flow calibrations can be found in the appendix of reference 12. The tunnel total temperature and pressure were normally 467 K and 11.9 atm, respectively, and provided a Reynolds number per meter of  $9.8 \times 10^6$ . One run was made at a reduced Reynolds number per meter of  $3.3 \times 10^6$  at a pressure of 4.4 atm, and all runs in the blowdown tunnel were restricted to less than 2 min. The model was mounted upside down in the center of the 50.8-cm-square test section with two 15.24-cm steel channels bolted to the tunnel floor as shown in figure 20.

### Facility Instrumentation

Tunnel pressure was recorded with strain-gage pressure transducers, and model static pressures were divided between six 48-port scanivalves. Pitot pressures and all survey data were measured by either strain-gage pressure transducers or multirange capacitance-type pressure transducers. Pitot position was determined with an electronic bridge circuit, and all data were processed by an electronic data processing system.

Because of the short time in which data could be taken (less than  $1\frac{1}{2}$  min), the scanivalve stepping mechanism was used to trigger the recording system, once each second, while the survey probe was moved continuously across the flow. Before the test the speed of the throat probes was selected by varying the voltage to the dc motor until the probe would span the flow in one test run. At the capture measurement station two test runs were required to span the flow area with the probe. An analysis of the survey data also indicated that pressure lag was not significant even though the connecting tubing was up to  $\approx 3$  m in length.

## DATA-REDUCTION PROCEDURE

A curve-fitting interpolation procedure was utilized to expand the pitot and static survey data into a grid network. Mach number, total pressure, and unit mass flow were calculated for each grid point; and contour maps of each parameter were plotted by the computer's graphic system. Inserted into the program for each grid point was an upper limit on total-pressure recovery which was obtained from the inviscid shock diagram. (See fig. 5.) If the total pressure was greater than this limit, the measured pitot pressure and the limiting total pressure were used to compute the flow parameters including the static pressure. The measured static pressure was discarded when the recovery limit was exceeded for any particular grid point because of the relative inaccuracy of the static-pressure measurements. After completing the grid, numerical integrations were performed to compute a mass-weighted Mach number and total-pressure recovery for the inlet throats and a value for a capture parameter  $\rho v / \rho_1 v_1$  at the capture measurement station.

## RESULTS AND DISCUSSION

### Initial Inlet Tests

The results of the first inlet tests at Mach 6 indicated the model was not operating as expected. Initial testing of the model at Mach 6 indicated too much compression and possible choking was occurring within the center passage as indicated in figure 21. Upon investigation, it was discovered that the  $6^\circ$  sidewall shock wave was striking the side strut too near the leading edge. This shock wave then combined with the  $4^\circ$  side-strut shock wave and produced a  $10^\circ$  wave which reflected between the side and center struts (fig. 22) unlike the expected pattern of figure 5. The location of this sidewall shock wave was also determined by removing the struts and observing the sidewall static-pressure distribution (fig. 23). The error in shock-wave position as measured in the xz-plane was only about 0.64 cm ( $\Delta/H = 0.033$ ) measured approximately 36 cm from the sidewall leading edge. The effect of the increased compression of the center passage extended across the inlet in the vicinity of the cowl to the sidewall, as indicated by the disturbance in the oil-streak photograph of figure 24(a). More detail concerning the oil study is provided in a later section, but proof that the sidewall disturbance was created by the center passage is illustrated in figure 24(b) with the center strut removed. This photograph shows no disturbance next to the cowl. The measured capture was only 81 percent with the choked cowl compared with 92 percent with the center strut removed.

### Modified Inlet Configuration

To deal with the miscalculated sidewall shock-wave location, the strut arrangement was altered to move the shock waves toward the center-passage throat. The three struts and cowl were moved forward  $\Delta X/H = 0.213$  ( $\Delta X = 4.06$  cm); and the side struts were moved toward the sidewalls  $\Delta Z/H = 0.022$  ( $\Delta Z = 0.43$  cm) to maintain the same contraction and percent of flow in the side passage. The resulting configuration is shown in figure 25. It was also observed that the experimentally determined location of the sidewall shock waves could be duplicated theoretically by the addition of  $0.83^\circ$  to the sidewall compression angle. This correction is necessary because of end effects from the top surface, or model misalignment, or the use of flat-plate boundary-layer calculations on the swept sidewalls and struts. There was some concern for the inlet operation at lower Mach numbers when the shock wave moved forward along the side strut. However, the shock waves become detached from the swept compression surfaces and should prevent boundary-layer separation and choking by spreading the static-pressure rise along the strut surfaces. In fact, unpublished data from low Mach number tests support this conclusion.

The shock waves were recomputed with the new strut locations and the corrected inviscid sidewall compression angle, and the results are given in figures 26, 27, and in tables III and IV. Compression in the side passage increased because of the stronger sidewall shock wave. Mach number, recovery, and aerodynamic contraction changed from 3.51, 87.9 percent, and 6.85 to 3.45, 86.2 percent, and 7.07, respectively. The center-passage throat is now divided between bays 10, 14, and 16. The predicted, inviscid, mass-weighted average Mach number, recovery, and aerodynamic contraction for the inlet changed from 3.44, 88 percent, and 7.3 to 3.37, 85 percent, and 7.6, respectively, for the modified design.

From the initial inlet tests, moving the cowl to the forward position (fig. 11) aggravated the choking situation next to the cowl; and the cowl at the most rearward position failed to help the design. Therefore, the center position of the cowl relative to the struts (fig. 25) was maintained for the new configuration. This movement of the cowl forward ( $\Delta X/H = 0.213$ ) relative to the sidewalls increased the theoretical capture by 2 percent to 95 percent.

The center-passage-throat gap was increased when the struts were moved forward, although the inlet aerodynamic contraction increased slightly. The purpose of center strut 2 was to decrease again the center-passage-throat gap and to determine operating sensitivity of the inlets on this parameter.

### Inlet Entrance Conditions

The foreplate static-pressure distribution and the Mach number profile for the flow entering the inlet are given in figure 28. The static pressure on the foreplate was above the free-stream value because no boundary-layer correction was applied; in addition, the boundary layer was thicker than predicted by the flat-plate calculations probably as a result of trip losses.

### Wall Static-Pressure Distribution

Figures 29 to 41 present the results of the static-pressure data throughout the model, which are compared with the predicted results of figures 26 and 27, and of tables III and IV. The solid symbols are data from orifices used to check flow symmetry with the two passages on the right side of the model. The round symbols are data obtained with the initial configuration and the x-position of this data has been shifted to correspond to the new strut locations. These data indicate in figures 29 to 33 that there was reasonable agreement between predicted and measured operation of the side passage away from the cowl. Some additional compression was observed on the cowl of the modified configuration (fig. 32) that was probably due to corner interaction phenomenon and blunt leading-edge effects. The static-pressure distribution along the side-passage throat is summarized in figure 33. The symbols of figure 33(b) were obtained from orifices located on the side strut; and, because no static surveys were made in the side passage, a linear pressure distribution was assumed across the throat between the strut and sidewall for data analysis. The data from the sidewall throat (squares in fig. 33(a)) of the new configuration were neglected because these orifices were no longer at the throat but downstream of the struts.

Data in the center passage are given in figures 34 to 41. The center passage of the initial design also operated as anticipated near the top surface (fig. 34), unlike the evidence of too much compression on the side strut at  $Y/H = 0.43$  (fig. 21 or 35). The cowl pressures were greatly reduced with the modified configuration (figs. 38 and 39), but no theoretical value is shown because of the complicated flow generated by the strut relief (fig. 6(b)). The hump in the center-passage-throat pressure distribution (fig. 40) is attributed to a corner effect from the top surface creating a relocation of the strut shock waves. In general the center-passage compression was slightly greater than that predicted because no boundary-layer correction was made on the struts. The diamond symbols of figures 33 to 41 correspond to the larger center strut. From figure 27 it is clear that the larger center strut reduces the gap between the struts and moves the throat downstream. None of the experimental measurements would be expected to be affected by the larger strut except wall statics on the side strut in the downstream portion of bay 16 (fig. 27). Figure 35 does, in fact, show a higher pressure on the most downstream

static orifice. In all other instances the larger strut had a negligible effect on the pressure measurements and it is concluded that the strut could be used successfully at Mach 6 to provide added contraction ratio. The static pressure on the small center strut (fig. 41) is lower because the orifices were located downstream of the strut shoulder. Appendix B presents pressure levels found within the model for a low-pressure test ( $R = 3.3 \times 10^6$  per meter) and also an unstarted condition.

### Oil-Flow Study

Although static pressures could be, and were, monitored to detect inlet starting, the most rapid and reliable method was to observe, by closed circuit television, the oil-flow pattern formed as the blackened oil droplets moved across the model's surface under the approaching flow. If the model did not start, all the oil on the sidewall moved in a curved path toward the bottom of the model. The only evidence of any shock wave was observed well upstream of the sidewall leading edges on the top surface. With the started inlet (fig. 42), the oil on the sidewall moves toward the throat along a line parallel to the line of intersection between the top surface and the sidewall. The exception was the oil near the bottom edge of the sidewall which followed the path of the flow spilled from the inlet. When the oil reached the high-pressure region formed by the side strut shock wave on the sidewall, it turned toward the cowl along a line approximately parallel to the swept leading edges. This oil accumulation line extended out the bottom of the inlet in front of the cowl with no interruptions, unlike the original strut configuration (fig. 24(a)).

### Wall Surface Temperature and Boundary-Layer Analysis

The inlet did not reach an equilibrium temperature (fig. 43) because of a test time limit; however, the temperature was fairly uniform because of the high thermal conductivity of the aluminum. The dashed lines of figure 43 represent the wall temperature distribution selected for the boundary-layer analysis conducted with a modified version of the boundary-layer program of reference 13. This integral method computer program provided a viscous correction to the top-surface sidewalls and struts and reduced the total-pressure recovery from 86.2 percent to 54 percent for the side passage. The center-passage recovery changed from 84 percent to 73 percent, and the inlet average recovery was decreased from 85 percent to 67 percent. Because the surface of the cowl was small, it was neglected in the analysis, but the computed boundary-layer thickness for the rest of the inlet was nondimensionalized by the inlet height and plotted in figure 44. Transition was forced on the top surface 7.62 cm from the foreplate leading edge because of the trips. Natural transition was assumed at  $s'/H \approx 0.8$  for the sidewall where the Reynolds number based on momentum thickness was equal to 1000. The sidewall boundary-layer trips had been removed prior to the modified configuration test when it was observed

that they had little effect on the side-passage experimental data. The boundary-layer flow over the struts was assumed to be turbulent from the swept leading edges.

### Throat Surveys

Pitot pressure distributions for both the side and center passage are presented in figure 45, where  $W$  is the throat gap and  $Z'$  is equal to zero at the sidewall for the side-passage throat and equal to zero at the side strut for the center-passage throat. At the top of the model ( $Y/H = 0.14$ ), the center throat data were obtained from the fixed tube, which was bent to a new  $Z'$  position for each test. The side-passage pitot profile ( $Y/H = 0.17$ ) was obtained from the theoretical boundary-layer profile at  $Z/W = 0.5$  and then assumed similarity with the profile at the adjacent side throat station of  $Y/H = 0.26$ . The solid symbols were not data points but depended on theoretical boundary layer calculations to extend each survey (dashed lines) to the wall static value for data reduction.

Data station  $Y/H = 0.43$  was considered the station least influenced by top-surface and cowl flow effects, and surveys for the low Reynolds number test and the large center strut test are presented for this station in figures 45(g) and 45(h). The dashed lines in these two figures were taken from the standard tests (fig. 45(c)) and indicate that neither the large center strut nor the low Reynolds number tests had any significant effect on inlet operation.

The static survey data (fig. 46), obtained for the center passage, were faired to the wall values as indicated by the solid symbols. As mentioned earlier, when the measured static pressure was low and the total-pressure recovery exceeded the set upper limit (88 percent), a new static pressure based on the upper recovery limit was computed as illustrated by the dashed lines. To check the effect of this restriction, it was determined that a 10-percent increase in the limit increased the mass-weighted total-pressure recovery by approximately 3 percent. The straight lines are the static-pressure distributions assumed for the side passage and are based on neighboring wall static values. Other static-pressure data estimated from neighborhood statics for both the center- and side-passage throats near the top surface and cowl are given in figure 47. These additional estimated distributions made possible an analysis of a greater part of the throat flow area as defined by the pitot surveys.

The throat stations at  $Y/H = 0.43$  were selected to be compared with the theoretical inviscid and boundary-layer calculations, and the resulting Mach number profiles are found in figure 48. The agreement is good for both passages; the dip next to the center-passage side strut may be caused by a probe-tip shock-wave interaction. The small hash marks indicate the pitot measurement closest to the sidewall or strut, and the remainder of the curve is the result of fairing the pitot pressure to the wall static-pressure level.

## Throat Contour Maps

Contour maps of the results of compiling the throat pitot and static data are given in figures 49 to 52. Figures 49 and 50 are maps of the data input used to compute the Mach number and recovery maps of figures 51 and 52. Each map is shown with the width scale seven times the height, which makes the relief area next to the cowl (illustrated in fig. 51) appear to be out of proportion. The side-passage Mach number contours (fig. 51) are relatively symmetrical, and the prediction of boundary-layer thickness  $\delta$  agrees well for the top and side surface. The top-surface boundary-layer thickness for the side passage had to agree because of the imposed boundary conditions. A nearly horizontal shock of about  $8^\circ$  turning was generated by the cowl leading edge and is still near the cowl surface at the throat. This discrete shock is smeared by the computer programs interpolation process; and consequently a vertical Mach number gradient extending well beyond the predicted  $\delta$  for the cowl is indicated. There is some rounding of the contours at the corners, but no flow separation is detected. The Mach number contours for the center passage are not as symmetrical because of the greater shock-wave concentration (fig. 51(b)); however, the Mach 3 (mass-weighted average equals 3.11) contour encloses the major portion of the total area. The mass-weighted total-pressure recovery recorded in figure 52 for both the throat passages was obtained by a computer program which averaged the values of approximately 1000 grid points, evenly spaced over the throat area. One case was also integrated by hand with negligible difference, and the results verified the computed results. The mass-weighted average recovery for the two passages is 59 percent when the losses on the foreplate are included and 61 percent when they are neglected. The central area of nearly constant total-pressure recovery in figure 52(b) is in part a result of the assumption of a total-pressure recovery limit in regions where the measured static-pressure level was too low (fig. 46); however, this assumption is considered to be justified on a phenomenological basis as well as by the similarity in shape between the measured and derived static-pressure profiles (fig. 46) and the reasonable agreement between theory and data (for example, fig. 48).

## Capture Measurement Results

The procedure for analyzing the flow at the capture measurement station was identical to that of the inlet throats. At this station static survey data were taken at each pitot survey location. Each rake had seven probe tips. The data from which the Mach number and capture parameter  $\rho v/\rho_1 v_1$  were derived for figures 53 and 54 are discussed in appendix C. The wakes of the three struts, which are about 7.5 cm upstream, are detectable in the Mach number map (fig. 53); in general, lines of constant Mach number are parallel to the sidewalls. Besides measuring inlet capture flow, the capture parameter (fig. 54) is a good indicator of flow gradient direction because it is less sensitive to static-pressure error than either Mach number or recovery. The average

value of  $\rho v / \rho_1 v_1$  was 3.18 for the inlet at the capture measurement station; before capture flow could be calculated, however, some estimate of flow direction to determine cross-sectional area had to be made. The assumptions in figure 55 are: flow parallel to the top surface in the top-surface boundary layer; flow parallel to the cowl below the estimated location of the cowl shock wave; and flow down at  $8^\circ$  for the remainder of the area. This  $8^\circ$  downflow was the flow turning which was computed from the rise in static pressure due to the cowl shock. The flow was also assumed to be parallel to the sidewalls at this station. With these restrictions a capture of about 94 percent was computed for the inlet at Mach 6.

### Performance Results

Because the struts were positioned within the inlet to provide two-thirds of the flow to the center passage, the captured flow (94 percent) was assumed to be split between the center and side passages in the ratio of 63/31. With this criteria the Mach 6 integrated performance parameters based on the tunnel free-stream conditions are tabulated for each passage, and the total inlet, in figure 56. The side-passage total-pressure recovery was lower than the center-passage recovery because of the relatively thicker boundary layer on the sidewalls. The average viscous total-pressure recovery was 0.59 compared with the predicted value of 0.67 for the initial inlet configuration, which did not include corner effects. The aerodynamic contraction ratio, which is based on the average throat Mach number and total pressure, is 7.0 instead of the design value of 7.3. This is because moving the struts upstream increased the throat width somewhat and because the measured total-pressure recovery was slightly lower. The larger center strut increased the contraction, but no data were taken at the new center-passage throat location. Included in figure 56 are curves from reference 7 predicting the inlet kinetic energy efficiency and capture over the flight Mach number range of 4 to 10. The Mach 6.0 inlet data have been entered in the figure for a flight Mach number of 7.6, which indicates a representative amount of vehicle forebody compression. The measured kinetic energy efficiency as determined by adiabatic process was 97.7 percent compared with the predicted tunnel value of 98.3 percent. The predicted curve is slightly high primarily because the cowl shock and viscous corner interactions were not included. The measured captured mass flow from in front of the inlet was 94 percent and matched the predicted value. The theory is expected to be less accurate at low Mach numbers because of the formation of detached shock waves. (See fig. 7.)

### CONCLUDING REMARKS

As part of a Langley research and technology program focused on the development of a concept for an airframe-integrated scramjet engine (Langley Scramjet Module), a

detailed performance evaluation of the baseline inlet configuration at Mach 6 (simulated flight Mach number of approximately 7.6) has been conducted.

Mach number profiles in the inlet throat agreed reasonably well with the predicted results both for the inviscid flow and the boundary-layer calculations on the struts and sidewall. The mass-weighted average throat Mach number was 3.0 for the side passage and 3.1 for the center passage. This value compares with the inviscid values of 3.4 for each of the two passages. This additional compression was produced by the boundary layer, viscous corner interactions, and other end effects (for example, the internal cowl shock).

An adiabatic kinetic energy efficiency of 97.7 percent (0.59 recovery) was measured and compared with a predicted value of 98.3 percent (0.67), which does not include corner or end effects.

The average inlet aerodynamic contraction ratio was 7.0 instead of the predicted value of 7.3 because of the slightly lower total-pressure recovery. However, the results indicated that the contraction ratio can be increased by the use of a larger center strut, which operated successfully but no survey data were taken.

The measured inlet capture flow was 94 percent which agrees with the predicted value of 95 percent.

The difficulty and importance of properly positioning the shock waves in the throats of hypersonic inlets were demonstrated, but no adverse effects were noted as a result of the inlet ingesting a boundary layer on the top surface which simulated the boundary layer that would be ingested from the vehicle forebody. Overall, the inlet performance is well within the acceptable range for high engine performance.

Langley Research Center,  
National Aeronautics and Space Administration,  
Hampton, Va., April 22, 1975.

## APPENDIX A

### ANALYTICAL CALCULATIONS OF SWEEP SHOCK WAVES

Shock-wave systems for swept inlet configurations require a three-dimensional coordinate system to locate the shock waves correctly and to compute the flow properties. A selected two-dimensional coordinate system (the  $xz$ -plane of fig. 4) is also helpful in maintaining visual contact with the problem. Figure 57 illustrates the flow striking a swept wedge (surface AGFED) and helps to describe the development of the swept shock wave. Points A, H, I, and D lie in the  $xy$ -plane and points A, H, G, and B lie in the  $xz$ -plane. The flow strikes the leading edge at point A; and if the wedge were not swept, the flow would only be turned away from the  $xy$ -plane by angle  $\delta_{xz}$  and would follow the path AC. However, sweeping the wedge requires the flow to traverse the surface along AF, the flow also being turned away from the  $xz$ -plane as shown by angle  $\delta_{xy}$  which is measured in the  $xy$ -plane. A swept shock wave (plane ABCD) attached to the leading edge is produced and is located with angle  $\epsilon_{xz}$  which is measured in the  $xz$ -plane. As long as the wedge is assumed to be of infinite length, no end effects are encountered; if the wedge is assumed to extend from the  $xz$ -plane, a reduced pressure, nonuniform flow region will exist in the proximity of the  $xz$ -plane. To eliminate this region, a fillet (AGFB) is added which extends out to the shock wave and fills the void left by the flow being turned away from the  $xz$ -plane.

A detailed discussion of the calculation procedure for obtaining the shock wave angle  $\epsilon_{xz}$ , downflow  $\delta_{xy}$ , and the flow properties behind the shock wave is given in reference 9, which describes the flow velocity being broken into vector components normal and tangential to the leading edge as shown in the sketch of figure 57. Although the velocity component tangential to the leading edge  $V_t$  remains unchanged ( $V_{t,1} = V_{t,2}$ ), the component perpendicular to the leading edge  $V_{n,1}$  is reduced because it is turned by when it encounters the wedge. The vectors on the wedge surface,  $V_{n,2}$ , and  $V_{t,2}$ , are then combined to obtain the velocity and direction of flow on the wedge surface. One limitation to the procedure occurs when either the sweep angle or the wedge angle is too great and the velocity component  $V_{n,2}$  becomes subsonic. The shock wave may become detached from the wedge leading edge, as illustrated in the sketch, and the downstream flow is not uniform.

#### The Swept Shock-Wave System

To determine the shock-wave orientation and flow properties for a train of shock waves as illustrated in figure 58, additional steps are required to compute the shock angle in the  $xz$ -plane. The computation must include the change in sweep angle and normal

## APPENDIX A - Continued

turning angle as the flow crosses each successive shock wave and is turned further from the xz-plane.

A computer program has been written to compute an inviscid shock wave system for an inlet, when the inlet geometry and the initial Mach number are specified. Inlet geometry consists of plane wedges defined by sweep angle measured in the xy-plane and flow turning angles which are measured in the xz-plane. The shock-wave computational procedure is described for the three shock waves of figure 58. The second shock wave reflects from a plane of symmetry along line AB, strikes the sidewall (line BB), and is again reflected. The flow vectors behind the three shock waves are labeled  $V_2$ ,  $V_3$ , and  $V_4$ , respectively. Because the flow angle with respect to the top surface (xz-plane) increases as the flow crosses each successive shock wave, a new fillet is required to eliminate three-dimensional end effects. The downstream fillets have complex orientations which are functions of Mach number; but, because they are small and considered to have minimal influence on the flow, these effects were neglected in the inlet design.

The sidewall is the generator of the first shock wave and may be considered to be a wedge or wing with sweep  $\Lambda_1$  measured in the xy-plane, angle of attack  $\delta_{xz}$  and dihedral as measured by the angle  $\phi_1$ . The second shock wave is reflected from the plane of symmetry along line AA and is illustrated in detail in figure 59. For this reflected wave the computer program solves the problem of flow across a wedge or wing with sweep  $\Lambda_2$ , angle of attack  $\delta_{(xz)'}^i$ , and zero dihedral ( $\phi_2 = 0$ ). The reference axes are  $x'$ ,  $y'$ , and  $z'$ . Because the flow has been turned toward the y-axis by the first shock wave, the sweep angle  $\Lambda_2$  increased from the value of  $\Lambda_1$ . Once  $V_3$  and the shock-wave angle  $\epsilon_{(xz)'}^i$  have been computed, the shock wave is defined in the original xz-plane with angle  $\epsilon_{xz}$ .

The third shock wave is illustrated in detail in figure 60, where the flow in front of the wave  $V_3$  approaches a swept wedge (sidewall) which is in the  $x''$ ,  $y''$ , and  $z''$  coordinate system. The sweep angle is  $\Lambda_3$ . The angle of attack is  $\delta_{(xz)''}$ , and the dihedral is  $\phi_3$ . The computer program treats this wave in the same manner as the first wave to compute  $\epsilon_{(xz)''}$ , and then defines the shock wave in the xz-plane with  $\epsilon_{xz}$ .

The first and third shock waves are coded "type A" waves by the program whereas waves reflected from the plane of symmetry are coded "type B." The flow turning across each wave, measured in the xz-plane, can be put into the program, which means the strength of the reflected wave (type B) may be made different from the strength of the incident (type A) wave. To compute a shock train, the program always begins with a wave of type A, but the wave types do not have to alternate as the wave type of each shock wave is input to the program. When two type B waves are together, the nomenclature must be reversed and the second type B wave considered to be type A; then this new orientation is continued.

## APPENDIX A - Continued

The program transfers all shock angles back to the xz-plane, where the angle is measured with respect to the flow direction in front of the wave for a type A wave; and the shock angle is measured with respect to the flow direction behind the wave for a type B wave. For a selected path of shock waves the sweep angle and dihedral for the first wave are input to the program. Subsequent sweep angles are internally computed, as is the dihedral, which is a function of the wave type. The number of shock waves in the train is input, and the program will continue to calculate across successive shock waves until shock-wave detachment occurs.

Because the flow properties in oblique shock-wave systems are path dependent, it may become necessary to iterate on pressure and flow direction, when waves of different turning strengths are encountered. Usually, however, the differences in shock-wave turning angles are small enough to insure that such effects can be neglected. If a correction is deemed to be necessary, an iteration can be done either by hand as the program computes across one wave at a time, or by following several flow paths with the program and averaging the results in the selected downstream flow bay.

### The Computer Program

The program is written in FORTRAN IV and is adapted to the CDC 6600 computer located at the Langley Research Center, Hampton, Virginia. Although the primary purpose of the program is to compute flow properties for swept, weak, oblique shock-wave systems, additional versatility is available as shown in the input listing attached to this appendix. Either perfect-gas or thermally perfect-gas (gas with caloric imperfections as defined in ref. 14) problems may be computed by the listed program. Also operational, but not included in the program listing, is a subroutine for real-air calculations. This real-air subroutine uses either thermodynamic tables or equations of air in thermochemical equilibrium to compute flow properties behind shock waves.

For the thermally perfect gas, the local total properties are computed; and the specific heat ratio  $\gamma$  is computed as a function of static temperature from equation (180) of reference 14. The gas characteristics that are assumed for air and are used currently in the program are:

Molecular vibrational-energy constant, $\theta_v$ . . . . .	3076 K
Perfect gas specific heat ratio, $\gamma_p$ . . . . .	1.4
Gas constant, $\bar{R}$ . . . . .	1545.31
Molecular weight . . . . .	28.9644

Both weak and strong shock waves and perfect-gas Prandtl-Meyer expansion calculations are possible. For the expansion fan, the angles of the leading, trailing, and average waves are printed.

## APPENDIX A -- Continued

The dihedral  $\phi$  is measured in a plane perpendicular to the wedge ridge line (line AG of fig. 57) and is defined in a parameter  $\psi$  where

$$\psi \equiv 1 - \frac{\cot \Lambda \tan \phi}{\sin \delta_{xz}}$$

This parameter is defined in reference 9 as the ratio of the lengths of two line segments (DE/AD) and is used to define the location of the wedge leading edge with respect to the xy-plane. For the first wave of a shock train, the wedge dihedral  $\phi$  does not have to be calculated because the leading edge is assumed to lie in the xy-plane and  $\psi$  has a value of zero. For a single-wave calculation the leading edge may be lifted out of the xy-plane; and when the dihedral is zero,  $\psi$  has a value of 1.

### Program Input

Card 1 - FORMAT(4F10.4,2F5.2,2F10.4,5I1)

OC	Number of successive waves (Maximum = 20) (cols. 1 to 10)
XM	Initial Mach number, M (cols. 11 to 20)
ALP	Sweep angle, $\Lambda$ , deg (cols. 21 to 30)
E1	Wedge ridge angle, $\delta_{xz}$ , deg (cols. 31 to 40)
DEADR	Dihedral parameter, $\psi \equiv 1 - \frac{\cot \Lambda \tan \phi}{\sin \delta_{xz}}$ (cols. 41 to 45)
GAM	Specific heat ratio, $\gamma$ , for perfect gas (cols. 46 to 50)
P1	Static pressure, $p_1$ , psia (cols. 51 to 60) Set equal to 1.0 if left blank
T1	Static temperature, $T_1$ , °R (cols. 61 to 70) Set equal to 500° R if left blank
K1	Type of gas calculation (col. 71) 0 perfect gas 2 thermally perfect gas
K2	Flag indicates value of turning angle for each shock wave to follow on card 2 (col. 72) 0 all waves will have $\delta_{xz} = E1$ 2 OC values of $\delta_{xz}$ will follow on card 2
K3	Flag indicates wave type for each shock wave to follow on card 3 (col. 73) 0 no card 3 necessary, waves will alternate Type A and Type B 2 OC wave types to follow on card 3

APPENDIX A - Continued

- K4 Flag indicates strength of shock wave (col. 74)  
 0 weak shock waves  
 2 strong shock wave (limited to OC = 1)
- K5 Special input case for dihedral (col. 75)  
 0 DEADR = Dihedral parameter,  $\psi$   
 2 DEADR = Dihedral angle, deg

Card 2 - FORMAT (16F5.3). Do not use if K2 = 0

- E11A Value of  $\delta_{xz}$  for each wave, deg  
 Expansion waves are entered as negative

Card 3 - FORMAT (16F5.3). Do not use if K3 = 0

- TYPE Wave types  
 1. Type A  
 -1. Type B

The first wave of a shock train must be type A.

A listing of the computer program follows:

```

PROGRAM INLET (INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE8) 100000
C 200000
C SWEEP SHOCK WAVE PROGRAM A1991 BY C.A. TREXLER 10/22/74 300000
C 400000
C INPUT FOR CARD 1 FORMAT(4F10.4,2F5.2,2F10.4,5I1) 500000
C NO. WAVES MACH NO. SWEEP DELTA DIH GAM P1 T1 KKKKK 600000
C DEG. DEG. DE/AD PSIA DEG.R 12345 700000
C 800000
C SWEEP= SWEEP ANGLE MEASURED IN XY PLANE 900000
C DELTA= FLOW TURNING ANGLE IN XZ PLANE 1000000
C DIH= DIHEDRAL PARAMETER (DE/AD) 1100000
C GAM= SPECIFIC HEAT RATIO ** SET EQUAL TO 1.4 IF LEFT BLANK 1200000
C P1= STATIC PRESSURE, PSIA ** SET EQUAL TO 1.0 IF LEFT BLANK 1300000
C T1= STAT TEMP., DEG R ** SET EQUAL TO 500. IF LEFT BLANK 1400000
C ADDITIONAL ENGLISH UNITS 1500000
C DENSITY -- LBM/FT**3 1600000
C VELOCITY - FT/SEC 1700000
C ENTHALPY - BTU/LBM 1800000
C 1900000
C K1= BLANK, PERFECT GAS /// K1= 2, THERMALLY PERFECT GAS 2000000
C K1= 4, REAL AIR - EQUATIONS (IF T1=0 P1= ALTITUDE, FT.) 2100000
C K1= 6, REAL AIR - TABLES (IF T1=0 P1= ALTITUDE, FT.) 2200000
C K2= BLANK, WAVE STRENGTHS NOT INPUT /// K2= 2, WAVE STRENGTHS INPUT 2300000
C K3= BLANK, WAVE TYPES NOT INPUT /// K3= 2, WAVE TYPES INPUT 2400000
C K4= BLANK, WEAK SHOCK WAVE /// K4= 2, STRONG SHOCK WAVE 2500000
C K5= BLANK, DIH = DE/AD /// K5= 2, SPECIAL CASE 2600000
C *SPECIAL CASE* DIHEDRAL (DIH) DEFINED BY AN ANGLE MEASURED
C IN A PLANE PERPENDICULAR TO RIDGE LINE. 2800000
C SWEEP MEASURED WITH LEADING EDGE IN XY PLANE,
C AND WEDGE AT ZERO ANGLE OF ATTACK. 3000000
C 3100000
C INPUT FOR CARD 2 FORMAT(16F5.2) NOT INPUT IF K2= BLANK 3200000
C D(1) D(2) D(3) D(4).....D(NW) 3300000
C D= FLOW TURNING ANGLE IN XZ PLANE (DEG) 3400000
C NW= NO. WAVES 3500000
C 3600000
C INPUT FOR CARD 3 FORMAT(16F5.2) NOT INPUT IF K3= BLANK 3700000
C T(1) T(2) T(3) T(4).....T(NW) 3800000
C T= WAVE TYPE ***** T= 1. FOR TYPE A /// T= -1. FOR TYPE B 3900000
C NW= NO. WAVES 4000000
C 4100000
000003 COMMON C,THV,GAMP,RBAR,XMWT,P1,T1,XM,XMNORM,TQ 4200000
    
```

APPENDIX A - Continued

00003	CJMMON P2,T2,DELTM,GAM,XM2N,EPD,RHOR	4300000
00003	COMMON EMAX,DELTM,N,KGAS,MC	4400000
00003	COMMON EPDF,TPKA,AR,XM1T,XM2T	4500000
00003	COMMON NDEBUB	4600000
00003	DIMENSION E11A(20),TYPE(20)	4700000
00003	C=3.14159265/180.0	4800000
00005	GAM=1.400	4900000
00006	THV=5537.0	5000000
00007	GAMP=1.4	5100000
00010	RBAR=1545.31	5200000
00012	XMWT=28.9644	5300000
00013	NDEBUB=0	5400000
00014	JJ=0	5500000
00016	5 READ(5,101)OC, XM,ALP,E1,DEADR,GAM,P1,T1,KGAS,NDELT,NORDER,N,KSP	5600000
00054	101 FORMAT(4F10.4,2F5.2,2F10.4,5I1)	5700000
00054	IF(EOF,516,70	5800000
00057	6 STOP	5900000
00061	70 CONTINUE	6000000
00061	T0=0.	6100000
00062	DIH=DEADR	6200000
00063	NSTR=N	6300000
00065	IF(GAM.LT..001)GAM=1.4	6400000
00071	IF(KGAS.GT.3)GO TO 400	6500000
00075	IF(P1.EQ.0.)P1=1.	6600000
00077	IF(T1.EQ.0.)T1=500.	6700000
00111	400 CONTINUE	6800000
00101	IF(KGAS.EQ.0)KGAS=0	6900000
00103	IF(NDELT.EQ.0)NDELT=0	7000000
00105	IF(NORDER.EQ.0)NORDER=0	7100000
00107	IF(NSTR.EQ.0)NSTR=0	7200000
00111	IF(KSP.EQ.0)KSP=0	7300000
00113	IF(ALP.EQ.0.)GO TO 700	7400000
00114	IF(E1.EQ.0.)GO TO 700	7500000
00115	IF(KSP.EQ.2)DEADR=1.-TAN(DEADR*C)/(SIN(E1*C)*TAN(ALP*C))	7600000
00136	700 CONTINUE	7700000
00136	XMINF=XM	7800000
00137	PINFR=1.0	7900000
00141	TINFR=1.0	8000000
00141	PINFR=1.0	8100000
00142	KKGAS=KGAS	8200000
00144	IF(KGAS.EQ.0)KGAS=1	8300000
00146	MC=OC	8400000
00150	D) 3 I=1,MC	8500000
00152	E11A(I)=E1	8600000
00154	TYPE(I)=0.	8700000
00155	3 CONTINUE	8800000
00157	IF(NDELT.EQ.0)GO TO 4	8900000
00160	READ(5,102)(E11A(NO),NO=1,MC)	9000000
00172	E1=E11A(1)	9100000
00174	102 FORMAT(16F5.3)	9200000
00174	4 CONTINUE	9300000
00174	IF(NORDER.EQ.2)READ(5,102)(TYPE(NO),NO=1,MC)	9400000
00211	OC=1.0	9500000
00212	I=1	9600000
00213	COI3PT=0.0	9700000
00214	ARCA=1.0	9800000
00215	TPRA=1.0	9900000
00216	K=1	10000000
00217	NN=0	10100000
00220	JJ=JJ+1	10200000
00222	AL1=ALP	10300000
00224	7 CONTINUE	10400000
00224	PRINT 106	10500000
00230	106 FORMAT(1H1)	10600000
00230	PRINT 126, JJ,K	10700000
00240	126 FORMAT(1X,7HCASE NO,I3,10X,7HWAVE NO,I3,3X2HK1,2X2HK2,2X2HK3,2X 1 2HK4,2X2HK5)	10800000
00240	IF(NSTR.EQ.2.AND.E1.GE..01)PRINT 121,KKGAS,NDELT,NORDER,NSTR,KSP	11000000
00267	IF(NSTR.NE.2.AND.E1.GE.0.)PRINT 122,KKGAS,NDELT,NORDER,NSTR,KSP	11100000
00315	IF(NSTR.NE.2.AND.E1.LT.0.)PRINT 123,KKGAS,NDELT,NORDER,NSTR,KSP	11200000
00343	IF(NSTR.EQ.2.AND.E1.LT..01)PRINT 124,KKGAS,NDELT,NORDER,NSTR,KSP	11300000
00372	IF(KSP.EQ.2)PRINT 125, DIH	11400000
00402	121 FORMAT(45X14H(STRONG SHOCK),9X6I4)	11500000
00402	122 FORMAT(45X14H(WEAK SHOCK),9X6I4)	11600000
00402	123 FORMAT(45X14H(EXPANSION),9X6I4)	11700000
00402	124 FORMAT(45X14H(NORMAL SHOCK),9X6I4)	11800000
00402	125 FORMAT(70X26H(DIHEDRAL = SPECIAL CASE =,F7.3,5H DEG))	11900000
00402	J=1	12000000

APPENDIX A - Continued

000403	600	CONTINUE	12100000
000403		ALPH=ALP*C	12200000
000405		E=E1*C	12300000
000406		IF (ALPH.GT..001)GO TO 9	12400000
000412		XMIN=XM	12500000
000412		XMIT=0.	12600000
000413		XMNORM=XM	12700000
000414		DELTN=E	12800000
000416		DELTP=DELTN	12900000
000420		GO TO 14	13000000
000420	9	CONTINUE	13100000
000420		ACOD=90.*C-ALPH	13200000
000423		CD=OC*TAN(ACOD)	13300000
000426		OD=OC/COS(ACOD)	13400000
000431		BC=OC*TAN(E)	13500000
000434		AD=BC	13600000
000436		DE=AD*DEADR	13700000
000437		PSI=ATAN2(DE,OD)	13800000
000442		OE=(OD**2+DE**2)**.5	13900000
000450		OB=(BC**2+OC**2)**.5	14000000
000456		AE=ABS(AD-DE)	14100000
000461		BE=(CD**2+AE**2)**.5	14200000
000467		THETA=ACOS(OC/OE)	14300000
000473		ABOE=ACOS((OB**2+OE**2-BE**2)/(2.0*OB*OE))	14400000
000504		XMIT=XM*OC/OE	14500000
000507		XMIN=XM*SIN(THETA)	14600000
000512		IF (XMIN-1.0)203,203,8	14700000
000515	8	CONTINUE	14800000
000515		OG=OC*OC/OE	14900000
000517		CG=OC*SIN(THETA)	15000000
000522		HG=OG*TAN(ABOE)	15100000
000525		OH=(HG**2+OG**2)**.5	15200000
000532		HC=(OH**2+OC**2-2.0*OH*OC*COS(E))**.5	15300000
000544		DELTN=ACOS((HG**2+CG**2-HC**2)/(2.0*HG*CG))	15400000
000554		IF (E11A(K).LT.0.)DELTP=-DELTN	15500000
000560		DELTP=DELTN	15600000
000561		XMNORM=XMIN	15700000
000563	14	CONTINUE	15800000
000563		GR=(GAM+1.)/(GAM-1.)	15900000
000567		EMAX=SQRT((GAM+1.)*(1.+(GAM-1.)/2.*XMIN**2+(GAM+1.)/16.*XMIN**4))	16000000
000605		EMAX=(1./(GAM*XMIN**2))*((GAM+1.)/4.*XMIN**2-1.+EMAX)	16100000
000620		EMAX=ASIN(SQRT(EMAX))	16200000
000624		DELTPM=(GAM+1.)*XMIN**2/(2.*(XMIN**2*(SIN(EMAX)**2)-1.))	16300000
000635		DELTPM=(DELTPM-1.)*TAN(EMAX)	16400000
000642		DELTPM=ATAN(1./DELTPM)	16500000
000645		DLIMIT=DELTPM*10.*C	16600000
000650		IF (XMIN.LT.2.)DLIMIT=DELTPM*2.*C	16700000
000656		IF (DLIMIT.GT.DELTP)GO TO 15	16800000
000662		KGAS=1	16900000
000663	15	CONTINUE	17000000
000663		IF (KGAS-1)10,10,11	17100000
000666	11	CONTINUE	17200000
000666		IF (KGAS.GT.3)CALL RAIR(ZFT,NSTR)	17300000
000673		IF (KGAS.GT.3)GO TO 15	17400000
000677		CALL REALG (NSTR)	17500000
000700		IF (N.LT.100)GO TO 16	17600000
000703		KGAS=1	17700000
000703		IF (DELTPM.LT.DELTP)GO TO 10	17800000
000706		IF (N.EQ.100)GO TO 5	17900000
000707	16	CONTINUE	18000000
000707		TR=T2/T1	18100000
000711		PR1=P2/P1	18200000
000713		RR=RHOR	18300000
000714		EP=EPD*C	18400000
000716		EPF=EPDF*C	18500000
000717		IF (ALPH.LT..001)GO TO 21	18600000
000722	10	CONTINUE	18700000
000722		IF (KGAS-1)12,12,25	18800000
000725	12	CALL PGAS	18900000
000726		IF (N.EQ.100)GO TO 5	19000000
000730		TR=T2/T1	19100000
000732		PR1=P2/P1	19200000
000734		RR=RHOR	19300000
000735		EP=EPD*C	19400000
000737		EPF=EPDF*C	19500000
000740		IF (ALPH.GT..001)GO TO 13	19600000
000744	21	CONTINUE	19700000
000744		ARCA=ARCA*AR	19800000

APPENDIX A - Continued

000746	DEL TN1=DEL TNP/C	19900000
000747	DEL TM=DEL TMN/C	20000000
000751	EMAX1=EMAX/C	20100000
000752	EEF=1.-(2./(GAM-1.)*((1./TPRA)**((GAM-1.)/GAM)-1.)/XM(INF**2)	20200000
000766	PINFR=PINFR*PR1	20300000
000770	TINFR=TINFR*TR	20400000
000771	RINFR=RINFR*RR	20500000
000773	PRINT 115	20600000
000777	115 FORMAT(/ / * SUMMARY OF FLOW PROPERTIES ACROSS UNSWEPT WEDGE	20700000
	1 *)	20800000
000777	PRINT 17, XM,ALP,DEL TN1,EPD,P1,T1	20900000
001017	17 FORMAT(/1X,3HM1=,F8.3,7X6HSWEEP=,F7.3,7X6HDELTA=,F7.3,12X4HEPS=,	21000000
	1 F7.3,7X3HP1=,F8.4,6X3HT1=,F8.2)	21100000
001017	PRINT 19, XM2N,PINFR,RINFR,TINFR,GAM	21200000
001035	19 FORMAT(/1X,3HM2=,F8.3,6X,7HP/PINF=,F8.4,5X7HR/RINF=,F8.4,9X7HT/TIN	21300000
	1 F=,F8.4,5X4HGAM=,F7.4)	21400000
001035	PRINT 120,TPRA,EEF	21500000
001045	120 FORMAT(/1X,22HRECOVERY (PI/PIINF) =,F8.4,7X22HKINETIC ENERGY EFF.	21600000
	1 =,F9.5)	21700000
001045	PRINT 18,ARCA,DEL TM,EMAX1	21800000
001057	18 FORMAT(/1X,22HCONTRACTION (AINF/AI) =, F8.4,27X10HDELTA MAX=,F8.4,	21900000
	14X8HEPS MAX=,F8.4)	22000000
001057	IF (DEL TN1.GT,DEL TM)PRINT 119	22100000
001065	119 FURMAT(60X28H***SHOCK WAVE IS DETACHED***)	22200000
001065	IF (DEL TN.GT,DEL TM)GO TO 5	22300000
001071	I=I+1	22400000
001072	IF (MC-I)5,20,20	22500000
001074	20 CONTINUE	22600000
001074	K=K+1	22700000
001076	P1=P2	22800000
001077	T1=T2	22900000
001100	XM=XM2N	23000000
001102	E1=E11A(K)	23100000
001104	GO TO 7	23200000
001104	13 CONTINUE	23300000
001104	XM2T= XM1T*(1./TR)**.5	23400000
001112	25 CONTINUE	23500000
001112	XM2=(XM2T**2+XM2N**2)**.5	23600000
001120	ARC=AR*XMNORM*XM2/(XM2N*XM)	23700000
001124	ARCA=ARCA*ARC	23800000
001126	ACHG=ACUS((HC**2+HG**2-CG**2)/(2.*HC*HG))	23900000
001136	AJHG=180.*C-ACHG	24000000
001141	IF (E11A(K).LT.0.)AJHG=ACHG	24100000
001145	AJGH = EP - DEL TN	24200000
001147	AHJG=180.*C-(AJHG+AJGH)	24300000
001153	GJ=HG*(SIN(AJHG)/SIN(AHJG))	24400000
001151	HJ=HG*(SIN(AJGH)/SIN(AHJG))	24500000
001157	CJ=HC+HJ	24600000
001171	IF (E11A(K).LT.0.)CJ=HJ-HC	24700000
001175	OJ=(GJ**2+OG**2)**.5	24800000
001203	EPXZP=ACUS((OJ**2+OC**2-CJ**2)/(2.*OJ*OC))	24900000
001214	EXZPF=EPXZP	25000000
001216	EXZAVG=0.0	25100000
001216	IF (E11A(K)11505,500,500	25200000
001221	505 AJGHF=EPF	25300000
001222	AHJGF=180.*C-(AJHG+AJGHF)	25400000
001226	GJF=HG*(SIN(ACHG)/SIN(AHJGF))	25500000
001234	HJF=HG*(SIN(AJGHF)/SIN(AHJGF))	25600000
001242	CJF=HJF-HC	25700000
001244	IF ((EPF+DEL TN).LT.0.)CJF=HC-HJF	25800000
001251	OJF=(GJF**2+OG**2)**.5	25900000
001257	EPXZPF =ACUS((OJF**2+OC**2-CJF**2)/(2.*OJF*OC))	26000000
001270	IF ((EPF+DEL TN).LT.0.)EXZPF=-EXZPF	26100000
001274	EXZAVG= EPXZP-.5*(EPXZP- EXZPF)	26200000
001300	500 CONTINUE	26300000
001300	300 FORMAT(10F10.5)	26400000
001300	AEO1P=ATAN2(XM2N, XM2T)	26500000
001302	ABO1P=ABQE-AEO1P	26600000
001304	ABEO=ASIN(0B*SIN(ABQE)/BE)	26700000
001312	AOBE=180.*C-(ABEO+ABQE)	26800000
001316	AB1P0=180.*C-(AOBE+ABO1P)	26900000
001321	IF (ABO1P)304,303,303	27000000
001322	304 AB1P0=AOBE- ABS(ABO1P)	27100000
001325	303 CONTINUE	27200000
001325	BI1P=0B*(SIN(ABO1P)/SIN(AB1P0))	27300000
001333	AABE=ATAN(AE/CD)	27400000
001337	TIP12P= BI1P*CUS(AABE)	27500000
001342	ACO13P = ATAN(TIP12P/OC)	27600000
001346	AFOC= ATAN2(DE,UC)	27700000

APPENDIX A - Continued

001351		ABUF= ABS(E-AFOC)	27800000
001354		BI2P=(BI1P**2-TIPI2P**2)**.5	27900000
001362		IF(DEADR-1.)200,200,201	28000000
001355	200	CI2P = BC -BI2P	28100000
001367		ACOI2P=ATAN(CI2P/OC)	28200000
001374		GO TO 203	28300000
001374	201	CI2P = BC +BI2P	28400000
001376		ACOI2P=ATAN(CI2P/OC)	28500000
001403	203	CONTINUE	28600000
001403		EQ=EP/C	28700000
001405		THET1=THETA/C	28800000
001406		DELTN1=DELTN/C	28900000
001410		EPX1=EPXP/C	29000000
001411		EPX1F=EXZPF/C	29100000
001413		EXZ1AV=EXZAVG/C	29200000
001415		COI3P= ACOI3P/C	29300000
001416		OUT2=COI3P	29400000
001420		COI2P=ACOI2P/C	29500000
001421		EOI1P= AEOI1P/C	29600000
001423		AABE1=AABE/C	29700000
001425		DELTM=DELTM/C	29800000
001426		EMAX1=EMAX/C	29900000
001430		ABQE1=ABQE/C	30000000
001431		ABEO1=ABEO/C	30100000
001433		DELTN1=DELTM/C	30200000
001435		EEF=1.-(2./GAM-1.)*((1./TPRA)**((GAM-1.)/GAM)-1./XMINF**2)	30300000
001451		PINFR=PINFR*PR1	30400000
001453		TINFR=TINFR*TR	30500000
001454		RINFR=RINFR*RR	30600000
001456		PRINT 114	30700000
001462	114	FORMAT(/ / * FLOW PROPERTIES REFERENCED TO SWEEP WEDGE*)	30800000
001462		PRINT 110	30900000
001466	110	FORMAT(/4X,3HM1N,7X3HM1T,7X3HM2N,7X3HM2T,8X2HM2,6X6HP/PINF,5X6HR/R 1INF,5X6HT/TINF,6X3HGAM)	31000000
001466		PRINT 111, XM1N, XM1T, XM2N, XM2T, XM2, PINFR, RINFR, TINFR, GAM	31200000
001514	111	FORMAT(1X,9F10.5)	31300000
001514		PRINT 112	31400000
001520	112	FORMAT(/3X6HDELTAN,5X4HEPSN,6X4HAJOC,5X6HACOIP,4X6HACOIP, 14X6HAEIOIP,5X5HTHETA,4X1JHDELTAN MAX,3X8HEPSN MAX,3X1HN)	31500000
001520		PRINT 113, DELTN1, EQ, EPX1, COI2P, COI3P, EOI1P, THET1, DELTM, EMAX1, N	31700000
001550	113	FORMAT(1X,9F10.5,17)	31800000
001550		IF(DELTN1.GT.0)PRINT 119	31900001
001556		PRINT 109, XM, ALP, EI, DEADR, P1, T1	32000000
001576	109	FORMAT(/1X,3HM1=,F8.3, 7X6HSWEEP=,F8.3, 7X12HR IIDGE ANGLE=,F8.3,7X6HDE/AD=,F6.3,7X3HP1=,F8.4,7X3HT1=,F8.2)	32100000
001576		PRINT 19, XM2, PINFR, RINFR, TINFR, GAM	32200000
001614		PRINT 120, TPRA, EEF	32300000
001624		PRINT 108, ARCA, EPX1, COI3P	32400000
001636	108	FORMAT(/1X,22HCNTRACTION (AINF/A) =, F8.4,7X4HEPS=,F8.3,7X11HCRD 1SS FLOW=,F8.3)	32600000
001636		IF(DELTN1.LT.0.)PRINT 508, EPX1, EPX1F, EXZ1AV	32700000
001651	508	FORMAT(/2X,14HEXPANSION FAN*,9X,10HLEAD WAVE=,F8.4,5X11HFINAL WAVE 1=,F8.4,5X9HAVG WAVE=,F8.4)	32800000
001651		PRINT 118	32900000
001655	118	FORMAT(/ / * FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDI NATE SYSTEM*)	33000000
001655		WR=ARCA*SIN((90.-AL1-COI3P)*C)/COS(AL1*C)	33300000
001671		IF(K.EQ.1)PRINT 117, XM2, E11A(K), EPX1	33400000
001705	117	FORMAT(/1X3HM2=,F8.3,3X9HDELTA XZ=,F8.3,10X7HEPS XZ=,F8.3)	33500000
001705		IF(K.EQ.1.AND.DELTN1.LT.0.)PRINT 508, EPX1, EPX1F, EXZ1AV	33600000
001727		IF(K.EQ.1)PRINT 116, COI3P, WR	33700000
001741	116	FORMAT(/1X29HTOTAL CROSS FLOW (DELTA XY)=,F8.3,10X 118HGAP RATIO (W1/W2)=,F8.3)	33800000
001741		IF(MC.EQ.1)GO TO 5	33900000
001743	274	IF(NN)276,606,275	34000000
001745	606	IF(TYPE(K+1))601,601,602	34100000
001750	276	CONTINUE	34200000
001750		XJOC2=EPXP	34300000
001751		ACOI2P=COI2P*C	34400000
001753		COI3P1=COI3PT*C	34500000
001755		ALP1=(90.-AL1)*C	34600000
001757		FXZP = TAN(XJOC2-ACOI2P)*TAN(ALP1)/(COS(COI3P1)*TAN(ALP1)-TAN(COI 13P1))	34700000
002000		EXZP=ATAN(EXZP)/C	34800000
002003		XJMUP = EXZPF-ACOI2P	34900000
002005		IF(EXZPF.LT.0.)XJMUP=EXZPF	35000000
002010		EXZPF=TAN( XJMUP )*TAN(ALP1)/(COS(COI3P1)*TAN(ALP1)-TAN(COI3 1P1))	35100000
			35200000
			35300000
			35400000
			35500000

APPENDIX A - Continued

002027	EXZPF=ATAN(EXZPF)/C	35600000
002032	EXZAVG=EXZP-.5*(EXZP-EXZPF)	35700000
002036	OUT2=(ABOE-AEOI1P)/C	35800000
002041	OUTT=COI3PT+OUT2	35900000
002043	WR = ARCA*SIN((90.-AL1-OUTT)*C)/COS(AL1*C)	36000000
002057	PRINT 117, XM2,E11A(K),EXZP	36100000
002070	IF(DELTN1.LT.0.)PRINT 508,EXZP,EXZPF,EXZAVG	36200000
002103	PRINT 116, OUTT,WR	36300000
002113	IF(DELTN.GT.DELTNM)GO TO 5	36400000
002117	I=I+1	36500000
002120	IF(MC-1)5,5,604	36600000
002122	604 IF(TYPE(K+1))601,602,602	36700000
002125	275 CONTINUE	36800000
002125	OFT=COI3PT*C	36900000
002127	XJOC3=EPXZP	37000000
002130	CAP1=(90.-AL1)*C	37100000
002133	EXZP=TAN(CAP1)*TAN(OFT)*TAN(XJOC3)/(SIN(OFT)*(TAN(CAP1)-TAN(OFT)))	37200000
002155	EXZP=ATAN(EXZP)/C	37300000
002160	EXZPF=TAN(CAP1)*TAN(OFT)*TAN(EXZPF)/(SIN(OFT)*(TAN(CAP1)-TAN(OFT)))	37400000
	1))	37500000
002202	EXZPF = ATAN(EXZPF)/C	37600000
002205	EXZAVG= EXZP - .5*(EXZP-EXZPF)	37700000
002211	OUTF=COI3PT+COI3P	37800000
002213	WR = ARCA*SIN((90.-AL1-OUTF)*C)/COS(AL1*C)	37900000
002230	PRINT 117, XM2,E11A(K),EXZP	38000000
002241	IF(DELTN1.LT.0.)PRINT 508,EXZP,EXZPF,EXZAVG	38100000
002254	PRINT 116, OUTF,WR	38200000
002264	IF(DELTN.GT.DELTNM)GO TO 5	38300000
002270	I=I+1	38400000
002271	IF(MC-1)5,5,605	38500000
002273	605 IF(TYPE(K+1))601,601,602	38600000
002275	601 CONTINUE	38700000
002275	NN=-1	38800000
002276	COI3PT=COI3PT+COI3P	38900000
002300	AIOI3P=ATAN(TAN(COI2P*C)*COS(COI3PT*C))/C	39000000
002313	ALP=ATAN((TAN((90.-AL1-COI3PT)*C))/COS(AIOI3P*C))	39100000
002330	ALP=90.-ALP/C	39200000
002333	K=K+1	39300000
002335	E11=E11A(K-1)	39400000
002336	TE1=(TAN(E11*C)-TAN(E11*C-E11A(K)*C))*TAN(AIOI3P*C)/TAN(E11*C)	39500000
002363	E1=ATAN(TE1)/C	39600000
002366	XM=XM2	39700000
002370	T1=T2	39800000
002371	P1=P2	39900000
002373	DEADR=ABS(TAN(AIOI3P*C)/TAN(E1*C))	40000000
002405	GO TO 7	40100000
002405	602 CONTINUE	40200000
002405	NN=1	40300000
002406	COI3PT=COI3PT+OUT2	40400000
002410	ALP=AL1+COI3PT	40500000
002411	SIGMA=(90.-AL1)*C	40600000
002414	SIGMA1=COI3PT*C	40700000
002415	K=K+1	40800000
002417	E12 = E11A(K)	40900000
002420	E1=ATAN(TAN(E12*C)*(TAN(SIGMA)-TAN(SIGMA1))*SIN(SIGMA1)/(TAN(SIGMA1)*TAN(SIGMA1)))	41000000
002446	E1=E1/C	41200000
002450	XM=XM2	41300000
002452	T1=T2	41400000
002453	P1=P2	41500000
002455	DEADR=.0	41600000
002456	GO TO 7	41700000
002456	END	41800000
	SUBROUTINE REALG (NSTR)	41900000
	C THIS SUBROUTINE COMPUTES WAVE PROPERTIES FOR A THERMALLY PERFECT GAS	42000000
000003	COMMON C,THV,GAMP,RBAR,XMW1,P1,T1,XM, XMNORM,TO	42100000
000003	COMMON P2,T2,DELTN,GAM, XM2N,EPD,RHOR	42200000
000003	COMMON EMAX,DELTM,N,KGAS,MC	42300000
000003	COMMON EPDF,TPRA,AR, XM1T, XM2T	42400000
000003	COMMON NDEBUB	42500000
000003	DIMENSION P(4),T(4),P2(4)	42600000
000003	FGA(T)=1.+(GAMP-1.)/(1.+(GAMP-1.)*(THETA/T)**2)*EXP(THETA/T)/(2*EXP(THETA/T)-1.)**2)	42700000
000035	FW(T2)=A**2-Q*(A**2-4.*R*T2)**.5-2.*R*T2-DD+GG*R*(T2-T1)+4.*R*1*THETA*(1./(EXP(THETA/T2)-1.)-E1)	42800000
000075	EPDF=0.	42900000
000076	EPDAVG=0.	43000000
000076	GC=32.1741	43100000
000100	GG=4.0*GAMP/(GAMP-1.)	43200000
		43300000
		43400000

APPENDIX A - Continued

000103		R=GC*PBAR/XMWT	43500000
000106		RI=P1*144./(RBAR/XMWT*T1)	43600000
000112		THETA=THV	43700000
000114		XMI=XMNORM	43800000
000115		ARA=1.0	43900000
000117		J=1	44000000
000120		I=N	44100000
000122	117	CONTINUE	44200000
000122		DELT=DELTN	44300000
000123		IF(DELTN.LT.0.)PRINT 118	44400000
000132	118	FORMAT(1X27H***THERMALLY PERFECT GAS***,14X16HAPPROX. SOLUTION)	44500000
000132		IF(DELTN.GE.0.)PRINT 6	44600000
000141	6	FORMAT(1X27H***THERMALLY PERFECT GAS***)	44700000
000141		PRINT 9	44800000
000145	9	FORMAT(38X16HIN FRONT OF WAVE)	44900000
000145		CALL TOTAL (P1,T1,XM,TO,PT1)	45000000
000151		GAM1=FGA(T1)	45100000
000154		XMIN=XM1	45200000
000156		GAM=GAM1	45300000
000157		SOUND=(R*T1*GAM1)**.5	45400000
000165		IF(DELTN.LT.0.)GO TO 446	45500000
000167		EMAX=SQRT((GAM+1.)*(1.+(GAM-1.)/2.*XMIN**2+(GAM+1.)/16.*XMIN**4))	45600000
000204		EMAX=(1./((GAM*XMIN**2))*((GAM+1.)/4.*XMIN**2-1.+EMAX))	45700000
000217		EMAX=ASIN(SQRT(EMAX))	45800000
000223		DELTNM=(GAM+1.)*XMIN**2/(2.*(XMIN**2*(SIN(EMAX)**2)-1.))	45900000
000234		DELTNM=(DELTNM-1.)*TAN(EMAX)	46000000
000241		DELTNM=ATAN(1./DELTNM)	46100000
000244		V1=XM1*SOUND	46200000
000246		PIE=3.141592654	46300000
000250		N2=4	46400000
000251		IF(1.EQ.2)N2=0	46500000
000255		IF(MC.GT.1)N2=4	46600000
000261		DEL2=DELTN	46700000
000262		IF(DELTNM.LT.DELTN)DEL2=DELTNM	46800000
000266		GAN=GAM1	46900000
000267		XM12=XM1**2	47000000
000271		XM14=XM1**4	47100000
000272		BB=-((XM12+2.)/XM12-GAN*SIN(DEL2)**2	47200000
000301		CC=(2.*XM12+1)/XM14+((GAN+1.)**2/4.+(GAN-1.)/XM12)*SIN(DEL2)**2	47300000
000320		D2=-COS(DEL2)**2/XM14	47400000
000324		EX=(9.*BB*CC/2.-BB**3-27.*D2/2.)/(BB**2-3.*CC)**1.5	47500000
000344		IF(EX.GT.1)EX=1.	47600000
000352		IF(EX.LT.-1)EX=-1	47700000
000357		EE=ACOS(EX)	47800000
000361		FF=COS((EE+N2*PIE)/3.)	47900000
000370		G2=(-BB/3.+(2*(BB**2-3.*CC)**.5/3.)*FF)**.5	48000000
000406		EPS=ASIN(G2)	48100000
000410		IF(NSTR.EQ.2.AND.DEL2.LT..01)GO TO 1000	48200000
000423		GO TO 1001	48300000
000423	1000	EPS=90.*C	48400000
000425		GO TO 1004	48500000
000426	1001	CONTINUE	48600000
000426		RR=TAN(EPS)/TAN(EPS-DEL2)	48700000
000435		PR1=1.+GAN*XM1**2*SIN(EPS)**2*(1.-1./RR)	48800000
000447	1004	CONTINUE	48900000
000447		EPI=EPS/C	49000000
000451		M=1	49100000
000452		N=1	49200000
000453		NN=1	49300000
000454		E1=1./(EXP(THETA/T1)-1.)	49400000
000462		NT=1	49500000
000464	111	CONTINUE	49600000
000464		KK=-1	49700000
000465		UI=V1*SIN(EPS)	49800000
000470		A=UI+R*T1/UI	49900000
000474		Q=A	50000000
000475		DD=2.0*UI**2	50100000
000477		HH=XM1**2*(SIN(EPS))**2	50200000
000503		HK=(2.*GAM1*HH-(GAM1-1.))*((GAM1-1.)*HH+2.)/((GAM1+1.)**2*HH)	50300000
000516		STR=((-.2/9000.)*TO+1.0)*HK	50400000
000523		TMAX=A**2/(4.*R)-.000001	50500000
000530		IF(N.EQ.1.AND.NDEBUG.GT.0)PRINT 223	50600000
000544	223	FORMAT(/)	50700000
000544		IF(NDEBUG.EQ.0)GO TO 120	50800000
000545		PRINT 222, TMAX,A,R,UI,T1,V1,EPI,PK1,PR2	50900000
000573	222	FORMAT(1X9H SUB REALG,9F12.4)	51000000
000573	120	CONTINUE	51100000
000573		WMAX=FW(TMAX)	51200000

APPENDIX A - Continued

000576		IF (WMAX) 140, 10, 143	51300000
000600	140	W=-Q	51400000
000601		NT=2	51500000
000602		T21=TMAX	51600000
000603		T22=T21	51700000
000605		W1=FW(TMAX)	51800000
000610	703	T22=T22-.1*(T21-T1)	51900000
000614		W2=FW(T22)	52000000
000616		NT=NT+1	52100000
000620		IF (NT-12) 803, 803, 802	52200000
000622	803	IF (W2) 703, 19, 707	52300000
000624	707	T21=T22+.1*(T21-T1)	52400000
000630		W1=FW(T21)	52500000
000632		T21=-W1/(W2-W1)*(T22-T21)+T21	52600000
000640		IF (T21-TMAX) 706, 706, 708	52700000
000642	708	T21=TMAX-.00001	52800000
000644	706	CONTINUE	52900000
000644		W1=FW(T21)	53000000
000646		T22=T21-.01*(T21-T1)	53100000
000652		W2=FW(T22)	53200000
000655		T21=-W1/(W2-W1)*(T22-T21)+T21	53300000
000663		IF (T21-TMAX) 712, 711, 711	53400000
000665	711	T21=TMAX	53500000
000667	712	CONTINUE	53600000
000667		W1=FW(T21)	53700000
000672		GO TO 802	53800000
000672	19	CONTINUE	53900000
000672		W1=W2	54000000
000673		T21=T22	54100000
000675		GO TO 802	54200000
000676	143	CONTINUE	54300000
000676		T21=STR*T1+40.	54400000
000701		IF (T21-TMAX) 300, 300, 301	54500000
000704	301	T21=TMAX	54600000
000706	300	T22=T21-10.*XM1	54700000
000711		W1=FW(T21)	54800000
000713		W2=FW(T22)	54900000
000716		T21=-W1/(W2-W1)*(T22-T21)+T21	55000000
000724		IF (T21-TMAX) 11, 11, 14	55100000
000726	14	T21=TMAX	55200000
000730	11	T22=T21-2.*XM1	55300000
000733		W1=FW(T21)	55400000
000735		W2=FW(T22)	55500000
000740		T21=-W1/(W2-W1)*(T22-T21)+T21	55600000
000746		IF (T21-TMAX) 141, 141, 305	55700000
000750	305	T21=TMAX	55800000
000752	141	T22=T21-.8*XM1	55900000
000755		W1=FW(T21)	56000000
000757		W2=FW(T22)	56100000
000762		T21=-W1/(W2-W1)*(T22-T21)+T21	56200000
000770		IF (T21-TMAX) 12, 12, 142	56300000
000772	142	T21=TMAX	56400000
000774	12	T22=T21-.1*XM1	56500000
000777		W1=FW(T21)	56600000
001001		W2=FW(T22)	56700000
001004		T21=-W1/(W2-W1)*(T22-T21)+T21	56800000
001012		IF (T21-TMAX) 15, 15, 10	56900000
001014	10	T21=TMAX	57000000
001016	15	CONTINUE	57100000
001016		W1=FW(T21)	57200000
001021	802	CONTINUE	57300000
001021		XNT=NT	57400000
001022		XNN=NN	57500000
001024		TRR=T21/T1	57600000
001026		T2=T21	57700000
001027	13	CONTINUE	57800000
001027		GAM2=FGA(T2)	57900000
001031		XM2=2.0*T1/(GAM2*T2)*((GAM1*XM1**2/2.0)+(GAMP/(GAMP-1.0))*(1.0-2T2/T1)+THETA/T1*(1./(EXP(THETA/T1)-1.0)-1./(EXP(THETA/T2)-1.0)))	58000000
001067		IF (XM2) 28, 28, 307	58200000
001072	307	CONTINUE	58300000
001072		XM2=XM2**5	58400000
001076		PR2=1./2.*(((1.+GAM2*XM2**2)-T1/T2*(1.+GAM1*XM1**2))+(((1.+GAM2*2XM2**2)-T1/T2*(1.+GAM1*XM1**2))**2)+4.*T1/T2**5)	58500000
001123		PR2=1./PR2	58600000
001125		ROR=((GAM2/GAM1)*(T2/T1)*(XM2/XM1)**2-1.)/SIN(EPS)**2)+1.	58700000
001137		IF (ROR) 100, 101, 102	58800000

APPENDIX A - Continued

001143	101	CONTINUE	59000000
001143		ROR=.000001	59100000
001145	102	CONTINUE	59200000
001145		ROR=ROR**.5	59300000
001151	100	CONTINUE	59400000
001151		ROR=1./ROR	59500000
001153		PR3=ROR*T2/T1	59600000
001155		EP1=EPS/C	59700000
001157		IF(NSTK.EQ.2.AND.DEL2.(T..01)GO TO 1002	59800000
001170		GO TO 1093	59900000
001170	1002	PK1=PR2	60000000
001172		GO TO 25	60100000
001172	1003	CONTINUE	60200000
001172		IF(ABS(PR2-PR1)-.001)25,25,27	60300000
001177	27	N=N+1	60400000
001201		NAP=N	60500000
001201		IF(M-2)55,56,56	60600000
001204	55	PRY=PR2	60700000
001205		PRX=PR1	60800000
001207		IF(NN-2)304,303,303	60900000
001212	304	PR1=PR1+.5*(PR2-PR1)	61000000
001216		NN=2	61100000
001217	303	CONTINUE	61200000
001217		PR1=PR1+.01*(PR2-PR1)	61300000
001223		M=M+1	61400000
001225		GO TO 191	61500000
001225	56	S=(PRY-PR2)/(PRX-PR1)	61600000
001231		PR1=(1./(1.-S))*(-S*PRX+PRY)	61700000
001237		M=M-1	61800000
001241	306	CONTINUE	61900000
001241	191	CONTINUE	62000000
001241		COTD=1.0/TAN(DEL1)	62100000
001244		EPS=ATAN(COTD/(GAM1*XM1**2/(PR1-1.)-1.))	62200000
001254		EP1=EPS/C	62300000
001256		IF(EP1.(T,1.)GO TO 28	62400000
001262		IF(N-20)111,28,28	62500000
001265	28	PRINT 112,EP1,T2,JJ,J,JAA,NN,N,XM2	62600000
001311	112	FORMAT(/21H PR DID NOT CONVERGE ,3X4HEP1=,F10.4,3X3HT2=,F10.4,3X3 2HJJ=,I4,3X2HJ=,I4,3X4HJAA=,3I6,F10.4)	62700000
001311		N=100	62800000
001312		RETURN	62900000
001313	25	CONTINUE	63000000
001313		P2=PR1*P1	63100000
001315		R2=ROR*R1	63200000
001317		GO TO 447	63300000
001321	446	CONTINUE	63400000
001321	C	C EXPANSION WAVE CALCULATIONS FOR TPG	63500000
001321		XNUDF=-DEL1N/C	63600000
001323		XNUD=XNUDF	63700000
001324		XMI=XM1	63800000
001326		T2=TO	63900000
001327		AW=SQRT((GAM+1.)/(GAM-1.))	64000000
001336		AAW=SQRT((GAM-1.)/(GAM+1.)*(XMI**2-1.))	64100000
001350		XMU=90.-ACOS(1./XMI)/C	64200000
001357		XNUS=AW*ATAN(AAW)/C-(90.-XMU)	64300000
001366		XNUS=XNUS+XNUDF	64400000
001367		BW=1./AW	64500000
001371		CW=(GAM-1.)/2.	64600000
001374		DW=(GAM+1.)/(2.*(GAM-1.))	64700000
001377		EW=-GAM/(GAM-1.)	64800000
001402		XMW=XMI	64900000
001403		XNUS=XNUS*C	65000000
001405		NW=0	65100000
001406	444	DO 445 JW=1,30	65200000
001411		XNU=AW*ATAN(BW*SQRT(XMW*XMW-1.))-ATAN(SQRT(XMW*XMW-1.))	65300000
001432		DIFF=XNUS-XNU	65400000
001433		IF(ABS(DIFF)-.00001)22,22,33	65500000
001440	33	DM=(XMW/SQRT(XMW*XMW-1.))*(1.+CW*XMW*XMW)*DIFF	65600000
001452		XMW=XMW+DM	65700000
001453	445	CONTINUE	65800000
001456		PRINT80	65900000
001462	90	FORMAT(30H MAX NO OF ITERATIONS EXCEEDED)	66000000
001462	22	XMU=ATAN(1./SQRT(XMW*XMW-1.))/C	66100000
001472		PR=(1.+CW*XMW*XMW)**EW	66200000
001501		IF(NW)64,64,66	66300000
001504	64	CONTINUE	66400000
001504		XMU1=XMU	66500000
001505		PR1=PR	66600000
001505			66700000

APPENDIX A - Continued

001507		XNUJ=XNUDF	56800000
001510		NW=NW+1	66900000
001512		XNUX=(XNUS+FLOAT(NW)*XNUJ)*C	67000000
001516		IF (XNUX-XNUB*C)444,444,66	67100000
001522	66	CONTINUE	67200000
001522		XM2N=XMW	67300000
001523		XM2=XM2N	67400000
001525		TR=(1.+(GAM-1.)/2.*XM1N**2)/(1.+(GAM-1.)/2.*XM2N**2)	67500000
001537		T2=T1*TR	67600000
001541		GAM2=FGA(T2)	67700000
001543		PR1=PR/PRT1	67800000
001545		P2=P1*PR1	67900000
001547		R2=P2*144./((RBAR/XMWT*T2)	68000000
001553		RHOR=R2/R1	68100000
001555		EPD=XMU1	68200000
001556		EP1=EPD	68300000
001557		EPDF=XMU	68400000
001561		EPDAVG=EPD-.5*(EPD-EPDF)	68500000
001564		B=1.0	68600000
001566		N=JW	68700000
001567		AR=RHOR*(XM2N/XMNORM)*TR**.5	68800000
001576		RNFR=RHOR*XM2N/(XMNORM*TR**.26)	68900000
001634		GAMM1=GAM-1.	69000000
001606		TPR=((GAM+1.)*B/(GAMM1*B+2.))*((GAM/GAMM1)*((GAM+1.)/(2.*GAM* 1B-(GAMM1)))*.5*(1./GAMM1))	69100000
001630		TPRA=TPRA*TPR	69200000
001632		DELTD=DELTD/C	69300000
	C	THIS PACKAGE OVER RIDES PERFECT GAS PRESSURE RATIO AND USES TPG EQ	69400000
001634		GAX = GAMP/(GAMP-1.)	69500000
001636		ETT=EXP(THETA/T2)	69600000
001642		ETTM1=ETT-1.	69700000
001644		ETIT=EXP(THETA/TO2)	69800000
001650		ETITM1=ETIT-1.	69900000
001652		ETR=ETITM1/ETTM1	70000000
001654		TTTR=T2/TO2	70100000
001656		THTR=THETA/T2	70200000
001660		THTR=THETA/TO2	70300000
001661		EX1=ETT/ETTM1	70400000
001663		EX2=ETIT/ETITM1	70500000
001665		PTPR=ETR*TTTR**GAX*EXP(THTR*EX1-THTR*EX2)	70600000
001700		P2=PT1*PTPR	70700000
001702		R2=P2*144./((RBAR/XMWT*T2)	70800000
001706		RHOR=R2/R1	70900000
001710	447	CONTINUE	71000000
001710		TR=T2/T1	71100000
001712		XM2T=XM1T*((GAM1*T1)/(GAM2*T2))**.5	71200000
001717		XM2F=(XM2T**2+XM2**2)**.5	71300000
001725		PRINT 7	71400000
001731	7	FORMAT(/38X11HBEHIND WAVE)	71500000
001731		CALL TOTAL(P2,T2,XM2F,TO2,PT2)	71600000
001735		PTR=PT2/PT1	71700000
001737		TPRA=TPRA*PTR	71800000
001740		DELTD=DELTD/C	71900000
001742		SN02=(R*T2*GAM2)**.5	72000000
001747		AR=R2*XM2*SN02/(R1*XM1*SCUND)	72100000
001754		ARA=ARA*AR	72200000
001755		PRINT 8	72300000
001761	8	FORMAT(/ / * FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING	72400000
	1	EDGE *)	72500000
001761		PRINT113, XM1, DELTD, P1, R1, T1, PT1, GAM1	72600000
002003	113	FORMAT(/2X4HMIN=,F6.3,4X7HDELTA=,F7.3,5X3HPI=,F8.4,6X3HR1=,F8.4, 26X3HT1=,F8.2,6X4HPT1=,F10.4,6X5HGAM1=,F6.4)	72700000
002003		PRINT114, XM2, EP1, P2, R2, T2, PT2, GAM2	72800000
002025	114	FORMAT(2X4HM2N=,F6.3,7X4HEPN=,F7.3,5X3HP2=,F8.4,6X3HR2=,F8.4, 26X3HT2=,F8.2,6X4HPT2=,F10.4,6X5HGAM2=,F6.4)	72900000
002025		RHOR=R2/R1	73000000
002027		RNFR=RHOR*XM2/(XM1*(T2/T1)**0.26)	73100000
002036		PRINT 115, RNFR, AR, P1, RHOR, TR, PTR, NAP	73200000
002060	115	FORMAT(1X, 5HREYR=,F6.3,5X6HA1/A2=,F7.3,2X6HP2/P1=,F8.4,3X6HR2/R1=, 1F8.4,3X6HT2/T1=,F8.4,6X4HTPR=,F10.4,9X2HN=,I6)	73300000
002060		IF(DELTD .LT.0.)PRINT 116, EPD, EPDF, EPDAVG	73400000
002075	116	FORMAT(/2X,14HEXPANSION FAN*,9X,10HLEAD WAVE=,F8.4,5X11HFINAL WAVE 1=,F8.4,5X9HAVG WAVE=,F9.4)	73500000
002075		J=J+1	73600000
002077		XM2N=XM2	73700000
002100		EPD=EP1	73800000
002102		RETURN	73900000
002103	109	STOP	74000000
002105		END	74100000

APPENDIX A - Continued

	SUBROUTINE PGAS	74700000
C	THIS SUBROUTINE COMPUTES WAVE PROPERTIES FOR A PERFECT GAS	74800000
C	INPUT= XMI, DELT, N OUTPUT= EP	74900000
C	NN= 0 FOR STRONG SHOCK	75000000
C	NN= 4 FOR WEAK SHOCK	75100000
000002	COMMON C,THV,GAMP,RBAR,XMWT,P1,T1,XM,XMNORM,TO	75200000
000002	COMMON P2,T2,DELTM,GAM,XM2N,EPD,RHOR	75300000
000002	COMMON EMAX,DELTM,N,KGAS,MC	75400000
000002	COMMON EPDF,TPRA,AR,XM1T,XM2T	75500000
000002	COMMON NOEBUG	75600000
000002	RBAR=1545.31	75700000
000003	XMWT=28.9644	75800000
000005	XMIN=XMNORM	75900000
000006	EPDF=0.	76000000
000007	EPDAVG=0.	76100000
000010	GR=(GAM+1.)/(GAM-1.)	76200000
000015	NN=4	76300000
000016	IF(MC.GT.1)N=0	76400000
000022	IF(N.EQ.2)NN=0	76500000
000025	IF(N.EQ.0)NN=4	76600000
000027	IF(DELTM.LT.DELTN)DELTM=DELTN	76700000
000032	XM1=XMIN	76800000
000033	DELT=DELTM	76900000
000035	PRINT 6	77000000
000040	6 FORMAT(1X17H***PERFECT GAS***)	77100000
000040	PRINT 9	77200000
000044	9 FORMAT(38X16HIN FRONT OF WAVE)	77300000
000044	CALL TOPG(P1,T1,XM,TO,PT1)	77400000
000050	IF(DELTM.LT.0.)GO TO 500	77500000
000052	PIE=3.141592654	77600000
000053	XM12=XM1**2	77700000
000054	XM14=XM1**4	77800000
000055	BB=-X(M12+2.)/X(M12-GAM*SIN(DELT)**2	77900000
000064	CC=(2.*X(M12+1.)/X(M14+(GAM+1.)*2/4.+(GAM-1.)/X(M12)*SIN(DELT)**2	78000000
000102	DD=-COS(DELT)**2/XM14	78100000
000126	EX=(9.*BB*CC/2.-BB**3-27.*DD/2.)/(BB**2-3.*CC)**1.5	78200000
000126	IF(EX.GT.1)EX=1.	78300000
000133	IF(EX.LT.-1)EX=-1	78400000
000140	EE=ACOS(EX)	78500000
000142	FF=COS((EE+NN*PI)/3.)	78600000
000151	GG=(-BB/3.+(2*(BB**2-3.*CC)**.5/3.)*FF)**.5	78700000
000167	EP=ASIN(GG)	78800000
000171	EPD=EP/C	78900000
000173	IF(EPD.GE.89.999)GO TO 25	79000000
000176	RR=TAN(EP)/TAN(EP-DELTM)	79100000
000206	25 CONTINUE	79200000
000206	IF(EPD.GT.89.999)RR= (GAM+1.)*XM1**2/(((GAM-1.)*XM1**2)+2.)	79300000
000220	PR1=1.+GAM*XMIN**2*SIN(EP)**2*(1.-1./RR)	79400000
000231	N=NN	79500000
000232	B=XMIN**2*SIN(EP)**2	79600000
000236	BB=((GAM-1.)*B+2.)/(2.*GAM*B-(GAM-1.))	79700000
000244	XM2N = (BB/(SIN(EP-DELTM)**2)**.5	79800000
000255	TR=((2.0*GAM*B-(GAM-1.))*((GAM-1.)*B+2.)/((GAM+1.)**2*B)	79900000
000270	T2=TR*T1	80000000
000272	P2=PR1*P1	80100000
000274	PR=P2/P1	80200000
000275	RHOR=RR	80300000
000276	EPD=EP/C	80400000
000300	GO TO 502	80500000
000301	500 CONTINUE	80600000
C	EXPANSION WAVE CALCULATION	80700000
000301	XMI=XMIN	80800000
000302	XNUDF=-DELTM/C	80900000
000304	XNUD=XNUDF	81000000
000306	AW=SQR(((GAM+1.)/(GAM-1.))	81100000
000314	AAW=SQR(((GAM-1.)/(GAM+1.))*(XMI**2-1.))	81200000
000326	XMU=90.-ACOS(1./XMI)/C	81300000
000335	XNUS=AAW*ATAN(AAW)/C-(90.-XMU)	81400000
000344	XNUB=XNUS+XNUDF	81500000
000345	BW=1./AW	81600000
000347	CW=(GAM-1.)/2.	81700000
000352	DW=(GAM+1.)/(2.*(GAM-1.))	81800000
000355	EW=-GAM/(GAM-1.)	81900000
000360	X*W=XMI	82000000
000361	XNUX=XNUS*C	82100000
000363	NW=0	82200000
000364	444 DO10JW=1,30	82300000

APPENDIX A - Continued

000366		XNU=AW*ATAN(BW*SQRT(XMW*XMW-1.))-ATAN(SQRT(XMW*XMW-1.))	82400000
000407		DIFF=XNUX-XNU	82500000
000410		IF(ABS(DIFF)-.00001)22,22,33	82600000
000414	33	DM=(XMW/SQRT(XMW*XMW-1.))*(1.+CW*XMW*XMW)*DIFF	82700000
000426		XMW=XMW+DM	82800000
000427	10	CONTINUE	82900000
000432		PRINT80	83000000
000435	80	FORMAT(30H MAX NU OF ITERATIONS EXCEEDED)	83100000
000435	22	XMU=ATAN(1./SQRT(XMW*XMW-1.))/C	83200000
000445		PR=(1.+CW*XMW*XMW)**EW	83300000
000454		IF(NW)55,55,66	83400000
000456	55	CJNTINUE	83500000
000456		XMU1=XMU	83600000
000457		PRT1=PR	83700000
000461		XNUD=XNUDF	83800000
000462		NW=NW+1	83900000
000464		XNUX=(XNUX+FLOAT(NW)*XNUD)*C	84000000
000470		IF(XNUX-XNUB*C)444,444,66	84100000
000474	66	CONTINUE	84200000
000474		XM2N=XMW	84300000
000475		PR1=PR/PRT1	84400000
000477		TR=(1.+(GAM-1.)/2.*XM1N**2)/(1.+(GAM-1.)/2.*XM2N**2)	84500000
000512		T2=T1*TR	84600000
000514		P2=P1*PR1	84700000
000516		RHOR=PR1/TR	84800000
000517		EPD=XMU1	84900000
000521		EPDF=XMU	85000000
000522		EPDAVG=EPD-.5*(EPD-EPDF)	85100000
000526		B=1.0	85200000
000530		N=JW	85300000
000532	502	CONTINUE	85400000
000532		AR=RHOR*(XM2N/XMNORM)*TR**.5	85500000
000541		RNFR=RHOR*XM2N/(XMNORM*TR**.26)	85600000
000547		GAMM1=GAM-1.	85700000
000551		TPR=((GAM+1.)*B/(GAMM1*B+2.))**((GAM/GAMM1)*((GAM+1.)/(2.*GAM* 18-(GAMM1))**((1./GAMM1)	85800000
000573		XM2T=XM1T*(T1/T2)**.5	85900000
000600		XM2F=(XM2T**2+XM2N**2)**.5	86000000
000606		PRINT 7	86100000
000612	7	FORMAT(/39X11HBEHIND WAVE)	86200000
000612		CALL TOPG(P2,T2,XM2F,T02,PT2)	86300000
000616		TPKA=TPRA*TPR	86400000
000620		DEL TN1=DEL TN/C	86500000
000621		ACR=0.	86600000
000622		GAM1=GAM	86700000
000624		GAM2=GAM	86800000
000624		R1=P1*144./(RBAR*T1/XMW)	86900000
000630		R2=P2*144./(RBAR*T2/XMW)	87000000
000634		RHOR=R2/R1	87100000
000636		PRINT 8	87200000
000642	8	FORMAT(/ * FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING	87300000
000642		1 EDGE *)	87400000
000642		PRINT 3, XMNORM, DEL TN1, P1, R1, T1, PT1, GAM1	87500000
000664	3	FORMAT(/2X4HM1N=,F6.3,4X7HDELTA=,F7.3,5X3HP1=,F8.4,6X3HR1=,F8.4, 26X3HT1=,F8.2,6X4HPT1=,F10.4,6X5HGAM1=,F6.4)	87600000
000664		PRINT 4, XM2N, EPD, P2, R2, T2, PT2, GAM2	87700000
000706	4	FORMAT(2X4HM2N=,F6.3,7X4HEPN=,F7.3,5X3HP2=,F8.4,6X3HR2=,F8.4, 26X3HT2=,F8.2,6X4HPT2=,F10.4,6X5HGAM2=,F6.4)	87800000
000706		PRINT 2, RNFR, AR, PR1, RHOR, TR, TPR, N	87900000
000730	2	FORMAT(1X,5HREYR=,F6.3,5X6HA1/A2=,F7.3,2X6HP2/P1=,F8.4,3X6HR2/R1=, 1F9.4,3X6HT2/T1=,F8.4,6X4HTPR=,F10.4,9X2HN=,I6)	88000000
000730		IF(DEL TN1.LT.0.)PRINT 5, EPD, EPDF, EPDAVG	88100000
000743	5	FORMAT(/2X,14HEXPANSION FAN*,9X,10HLEAD WAVE=,F8.4,5X11HFINAL WAVE 1=,F8.4,5X9HAVG WAVE=,F8.4)	88200000
000743		RETURN	88300000
000744		END	88400000
		SUBROUTINE TOTAL(P,T,YM,TT,T,PO)	89000000
	C	THIS SUBROUTINE COMPUTES TOTAL PROPERTIES FOR A THERMALLY PERFECT GAS	89100000
000010		COMMON C, THV, GAMP, RBAR, XMW, P1, T1, XM, XMNORM, T0	89200000
000010		COMMON P2, T2, DELTN, GAM, XM2N, EPD, RHOR	89300000
000010		COMMON EMAX, DELTNM, N, KGAS, MC	89400000
000010		COMMON EPDF, TPRA, AR, XM1T, XM2T	89500000
000010		COMMON NDEBUD	89600000
000010		FGA(T)=1.+(GAMP-1.)/(1.+(GAMP-1.)*(THETA/T)**2*EXP(THETA/T)/( 2*EXP(THETA/T)-1.))**2)	89700000
000044		FXM(T0)=SQRT((A*T0-7./GAM)+B*(1./[EXP(THV/T0)-1.]-E))	89800000

APPENDIX A - Continued

000072	THETA=THV	90000000
000074	PRINT2	90100000
000077	2 FORMAT(49X,*TOTAL PROPERTIES*)	90200000
000077	PRINT3	90300000
000103	3 FORMAT(8X1HM,9X6HMCHECK,7X2HT0,9X4HT/T0,8X2HP0,10X4HP/P0,9X1HR, 11)X4HR/R0,8X3HGAM,6X1HN)	90400000
000103	N=1	90500000
000104	GAM=FGA(T)	90600000
000111	RHO=P*144./((RBAR*T/XMWT)	90700000
000115	A= 7./(GAM*T)	90800000
000120	B= 2.*THV/(GAM*T)	90900000
000122	ET= EXP(THV/T)	91000000
000130	E=1./(ET-1.)	91100000
000133	T01 = T*(1.+(GAM-1.)*YM**2/2.)	91200000
000140	T02=T01-50.	91300000
000142	8 XM1=FXM(T01)	91400000
000144	XM2= FXM(T02)	91500000
000147	T0=(YM-XM1)/(XM2-XM1)*(T02-T01)+T01	91600000
000156	XM3=FXM(T0)	91700000
000161	IF(ABS(YM-XM3)-.0001)10,10,5	91800000
000166	5 T01=TC	91900000
000167	T02=T0-10.	92000000
000171	N=N+1	92100000
000173	IF(N-25)9,9,10	92200000
000175	9 GO TO 8	92300000
000176	10 CONTINUE	92400000
000176	ETO=EXP(THV/T0)	92500000
000202	ET01=ET0-1.	92600000
000204	ET1=ET-1.	92700000
000206	APR=EXP((THV*ET/(T*ET1))-(THV*ET0/(T0*ET01)))	92800000
000225	PR= ET01*(T/T0)**(GAMP/(GAMP-1.))*APR/ET1	92900000
000236	RHOR = ET01*(T/T0)**(1./(GAMP-1.))*APR/ET1	93000000
000247	TR=T/T0	93100000
000251	P0=P/PR	93200000
000253	TTOT=T0	93300000
000253	PRINT1,YM,XM3,T0,TR,P0,PR,RHO,RHOR,GAM,N	93400000
000303	1 FORMAT(1X,2F12.5,F12.3,F10.5,F13.3,F13.9,F12.6,F13.9,F9.5,15)	93500000
000303	RETURN	93600000
000304	END	93700000
	SUBROUTINE TOPG(P,T,YM,TTOT,P0)	93800000
	C THIS SUBROUTINE COMPUTES TOTAL PROPERTIES FOR A PERFECT GAS	93900000
000010	COMMON C,THV,GAMP,RBAR, XMWT,P1,T1, XM, XMNORM,T0	94000000
000010	COMMON P2,T2,DEL TN,GAM, XM2N,EPD,RHDR	94100000
000010	COMMON EMAX,DEL TNM,N,KGAS,MC	94200000
000010	COMMON EPDF,TPRA,AR, XM1T, XM2T	94300000
000010	COMMON NDEBUB	94400000
000010	PRINT2	94500000
000013	2 FORMAT(49X,*TOTAL PROPERTIES*)	94600000
000013	PRINT3	94700000
000017	3 FORMAT(8X1HM,9X6HMCHECK,7X2HT0,9X4HT/T0,8X2HP0,10X4HP/P0,9X1HR, 11)X4HR/R0,8X3HGAM,6X1HN)	94800000
000017	RBAR=1545.31	94900000
000020	XMWT=28.9644	95000000
000022	RHO=P*144./((RBAR*T/XMWT)	95100000
000030	A = (GAM-1.)/2.*YM**2	95200000
000034	TR = 1./(1.+A)	95300000
000036	PR = (1./(1.+A))**((GAM/(GAM-1.))	95400000
000045	RHOR = (1./(1.+A))**((1./(GAM-1.))	95500000
000055	T0=T/TR	95600000
000057	P0=P/PR	95700000
000060	TTOT=T0	95800000
000061	XM3=YM	95900000
000062	PRINT1,YM,XM3,T0,TR,P0,PR,RHO,RHOR,GAM	96000000
000110	1 FORMAT(1X,2F12.5,F12.3,F10.5,F13.3,F13.9,F12.6,F13.9,F9.5,15)	96100000
000110	RETURN	96200000
000111	END	96300000

## APPENDIX A - Continued

\*\*\*\* SAMPLE CASES \*\*\*\*

CASE NO. 1 -- FOR AN INITIAL SWEEP ANGLE OF 48 DEGREES, THIS CASE COMPUTES FLOW PROPERTIES ACROSS 3 SUCCESSIVE SHOCK WAVES. THE WAVES ALTERNATE TYPE A, TYPE B, AND TYPE A, WITH THE FLOW TURNING ACROSS EACH SHOCK WAVE EQUAL TO 6 DEGREES WHEN MEASURED IN THE XZ PLANE.

INPUT FOR CASE NO. 1

3.	6.	6.0	48.	6.0	0.	1.4		02200
6.	6.	6.						
1.	-1.	1.						

CASE NO. 2 -- THIS IS ALSO A PERFECT GAS CASE, WITH AN INITIAL SWEEP ANGLE OF 48 DEGREES. THE FIRST WAVE IS A SHOCK FOLLOWED BY AN EXPANSION FAN. BOTH WAVES ARE TYPE A, AND THE FLOW TURNING ACROSS EACH WAVE IS EQUAL TO 6 DEGREES WHEN MEASURED IN THE XZ PLANE.

INPUT FOR CASE NO. 2

2.	6.0	48.	6.0	0.	1.4			02200
6.	-6.							
1.	1.							

CASE NO. 3 -- THIS CASE IS A REPEAT OF CASE NO. 1, BUT FOR A THERMALLY PERFECT GAS AND AT A FLIGHT DYNAMIC PRESSURE OF 1000 PSF.

INPUT FOR CASE NO. 3

3.	6.0	48.	6.0	0.	.2775	402.		22200
6.	6.	6.						
1.	-1.	1.						

APPENDIX A - Continued

CASE NO	1	WAVE NO	1	K1	0	K2	2	K3	2	K4	0	K5	0
***PERFECT GAS***													
(WEAK SHOCK)													
IN FRONT OF WAVE													
M	6.00000	MCHECK	4100.000	T/O	.12195	P/O	1578.878	R	.005398	R/R/O	.005193563	GAM	1.40000
TOTAL PROPERTIES													
M	5.17681	MCHECK	4100.000	T/O	.15724	P/O	1490.317	R	.009618	R/R/O	.009803422	GAM	1.40000
BEHIND WAVE													
TOTAL PROPERTIES													
M	5.17681	MCHECK	4100.000	T/O	.15724	P/O	1490.317	R	.009618	R/R/O	.009803422	GAM	1.40000
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE													
MIN	4.015	DELTA N	8.927	P1	1.0000	R1	.0054	TI	500.00	PI1	1578.8777	GAM1	1.4000
MZN	3.373	EPN	21.221	P2	2.2972	R2	.0096	I2	644.67	PI2	1490.3174	GAM2	1.4000
REYR	1.401	A1/A2	1.700	P2/P1	2.2972	R2/R1	1.7817	T2/T1	1.2893	TPR	.9439	N	4
FLOW PROPERTIES REFERENCED TO SWEEP WEDGE													
M1	4.01478	M2	3.37334	M2T	3.92683	M2	5.17691	P/PINF	2.29725	R/RINF	1.78173	I/TINF	1.28933
DELTA	8.92684	AJOC	14.56494	ACO12P	5.80584	ACO13P	1.68065	AE011P	40.66416	THETA	42.00000	DELTA N MAX	66.06870
M1	6.000	SWEEP	48.000	RIDGE ANGLE	6.000	DE/AD	0.000	PI	1.0000	TI	500.00		
M2	5.177	P/PINF	2.2972	R/RINF	1.7817	I/TINF	1.2893	GAM	1.4000				
RECOVERY (PT/PTINF)	= .9439 KINETIC ENERGY EFF. = .99769												
CONTRACTION (AINF/A)	= 1.7456 EPS = 14.565 CROSS FLOW = 1.681												
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM													
M2	5.177	DELTA XZ	6.000	EPS XZ	14.565								
TOTAL CROSS FLOW (DELTA XY)	= 1.681 GAP RATIO (W1/W2) = 1.688												

APPENDIX A - Continued

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CASE NO 1 WAVE NO 2 K1 K2 K3 K4 K5
(WEAK SHOCK) 0 2 2 0 0
***PERFECT GAS***
IN FRONT OF WAVE
M MCHECK TO P/PO R R/RO GAM N
5.17681 4100.000 .15724 1490.317 .001541448 .009618 .009803422 1.40000
BEHIND WAVE
M MCHECK TO P/PO R R/RO GAM N
4.54388 4100.000 .19496 1436.267 .003271737 .015867 .016781921 1.40000
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE
MIN= 3.373 DELTAN= 8.927 P1= 2.2972 R1= .0096 I1= 644.67 PT1= 1490.3174 GAM1=1.4000
M2N= 2.865 EPN= 24.092 P2= 4.6991 R2= .0159 I2= 792.32 PT2= 1436.2673 GAM2=1.4000
REVR= 1.325 A1/A2= 1.560 P2/P1= 2.0455 R2/R1= 1.6498 I2/I1= 1.2399 TPR= .9637 N= 4
FLOW PROPERTIES REFERENCED TO SWEEP WEDGE
MIN MIT M2N M2T M2 P/PINF R/RINF T/TINF GAM
3.37334 3.92683 2.85536 3.52655 4.54388 4.69909 2.93943 1.59864 1.40000
DELTAN EPSN AJOC ACOI2P ACOI3P AEOI1P THETA DELTAN MAX EPSN MAX N
9.92684 24.09216 15.75064 5.80336 1.23139 39.09427 40.66416 36.26086 65.58180 4
M1= 5.177 SWEEP= 49.535 RIDGE ANGLE= 5.803 DE/AD= 1.000 P1= 2.2972 I1= 644.67
M2= 4.544 P/PINF= 4.6991 R/RINF= 2.9394 T/TINF= 1.5986 GAM= 1.4000
RECOVERY (PT/PTINF) = .9097 KINETIC ENERGY EFF.= .99619
CONTRACTION (AINF/A) = 2.8146 EPS= 15.751 CROSS FLOW= 1.231
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM
M2= 4.544 DELTA XZ= 6.000 EPS XZ= 10.280
TOTAL CROSS FLOW (DELTA XY)= 2.906 GAP RATIO (W1/W2)= 2.653

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CASE NO	1	WAVE NO	3	K1	K2	K3	K4	K5						
				0	2	2	0	0						
***PERFECT GAS***														
WEAK SHOCK1														
IN FRONT OF WAVE														
TOTAL PROPERTIES														
M	4.54388	MCHECK	4.54388	T/T0	0.19496	P/P0	0.003271737	R/R0	0.015867	GAM	1.40000			
BEHIND WAVE														
TOTAL PROPERTIES														
M	4.03831	MCHECK	4.03831	T/T0	0.23465	P/P0	0.006258880	R/R0	0.024607	GAM	1.40000			
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE														
MIN	2.86536	DELTA N	8.927	PI	4.5991	R1	0.0159	I1	799.32	PT1	1.26.2673			
M2N	2.4447	EPN	27.434	P2	8.7712	R2	0.0246	I2	962.08	PT2	1.401.4016			
REYN	1.261	AI/A2	1.451	P2/P1	1.3666	R2/R1	1.5508	I2/I1	1.2036	TPR	0.9757			
FLOW PROPERTIES REFERENCED TO SWEEP WEDGE														
MIN	2.86536	M2T	3.21443	M2	4.03831	P/PINF	8.77120	R/RINF	4.55846	T/TINF	1.92416			
DELTA N	8.92684	AJOC	18.12559	ACO12P	2.17835	ACO13P	37.25179	THETA	39.09427	DELTA N MAX	EPSN MAX			
M1	4.544	SWEEP	50.906	RIDGE ANGLE	5.657	DE/AD	0.000	PI	4.6991	I1	799.32			
M2	4.038	P/PINF	8.7712	R/RINF	4.5585	T/TINF	1.9242	GAM	1.4000					
RECOVERY (PT/PTINF) = .8876									KINETIC ENERGY EFF. = .99519					
CONTRACTION (AINF/AI) = 4.2559									EPS = 18.126			CROSS FLOW = 2.178		
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM														
M2	4.038	DELTA XZ	6.030	EPS XZ	19.155									
TOTAL CROSS FLOW (DELTA XY) = 5.084									GAP RATIO (W1/W2) = 3.820					

APPENDIX A - Continued

```

CASE NO 2          WAVE NO 1          K1 K2 K3 K4 K5
          (LEAK SHOCK)          0 2 2 0 0
***PERFECT GAS***
IN FRONT OF WAVE
M          MCHECK          TO          I/T0          P0          P/P0          R          R/R0          GAM          N
6.00000    6.00000    4100.000    .12195    1578.878    .000633361    .005398    .005193563    1.40000
BEHIND WAVE
M          MCHECK          TO          I/T0          P0          P/P0          R          R/R0          GAM          N
5.17681    5.17681    4100.000    .15124    1490.317    .001541448    .009618    .009803422    1.40000
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE
MIN= 4.015    DELTAN= 8.927    PI= 1.0000    RI= .0054    TI= 500.00    PT1= 1578.8777    GAM1=1.4000
M2N= 3.373    EPN= 21.221    P2= 2.2972    R2= .0096    I2= 644.67    PT2= 1490.3174    GAM2=1.4000
REVR= 1.401    A1/A2= 1.700    P2/P1= 2.2972    R2/R1= 1.7817    T2/T1= 1.2893    IPR= .9439    N= 4
FLOW PROPERTIES REFERENCED TO SWEEP WEDGE
M1N          M1T          M2N          M2T          M2          P/PINF          R/RINF          T/TINF          GAM
4.01478      4.45887      3.37334      5.92683      5.17681      2.29725      1.78173      1.28933      1.40000
DELTA          EPSN          AJOC          ACOI2P          ACOI3P          AEOILP          THETA          DELTAN          MAX          EPSN          MAX          N
8.92684      21.22146      14.56494      5.80584      1.68065      40.66416      42.00000      38.82060      66.06870      4
M1= 6.000    SWEEP= 48.000    RIDGE ANGLE= 6.000    DE/AD= 0.000    PI= 1.0000    TI= 500.00
M2= 5.177    P/PINF= 2.2972    R/RINF= 1.7817    T/TINF= 1.2893    GAM= 1.4000
RECOVERY (PI/PTINF) = .9439    KINETIC ENERGY EFF.= .99769
CONTRACTION (AINF/A) = 1.7456    EPS= 14.565    CROSS FLOW= 1.681
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM
M2= 5.177    DELTA XZ= 6.000    EPS XZ= 14.565
TOTAL CROSS FLOW (DELTA XY)= 1.681    GAP RATIO (W1/W2)= 1.688
    
```

APPENDIX A - Continued

CASE NO	2	WAVE NO	2	(EXPANSION)					K1	K2	K3	K4	K5
								0	2	2	0	0	
***PERFECT GAS***													
IN FRONT OF WAVE													
M	MCHECK	TO	T/T0	PJ	P/PO	R	R/RO	GAM	N				
5.17681	5.17681	4100.000	.15724	1490.317	.001541448	.009618	.009803422	1.40000					
BEHIND WAVE													
M	MCHECK	TO	T/T0	PO	P/PO	R	R/RO	GAM	N				
5.93700	5.93700	4100.000	.12423	1490.317	.000675761	.005337	.005439594	1.40000					
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE													
MIN=	3.350	DELTA N=	-8.927	P1=	2.2972	R1=	.0096	TI=	644.67	PI1=	1490.3174	GAM1=	1.4000
M2N=	3.941	EPN=	17.370	P2=	1.0071	R2=	.0053	T2=	509.34	PI2=	1490.3174	GAM2=	1.4000
REYR=	.694	AL/A2=	.580	P2/P1=	.4384	R2/R1=	.5549	T2/T1=	.7901	TPR=	1.0000	N=	4
EXPANSION FAN*		LEAD WAVE=	17.3699	FINAL WAVE=	14.7001	AVG WAVE=	16.0350						
FLOW PROPERTIES REFERENCED TO SWEPT WEDGE													
MIN	M1T	M2N	M2T	M2	P/PINF	R/RINF	T/TINF	GAM					
3.34964	3.94706	3.94075	4.44054	5.93700	1.00710	.98862	1.01869	1.40000					
DELTA N	EPSN	AJOC	ACO12P	ACO13P	AEO11P	THETA	DELTA N MAX	EPSN MAX	N				
-8.92684	17.36989	11.44203	-5.91259	-9.2163	41.58737	40.31935	36.14072	65.56125	4				
M1=	5.177	SHEEP=	49.681	RIDGE ANGLE=	-5.803	DE/AD=	0.000	P1=	2.2972	TI=	644.67		
M2=	5.937	P/PINF=	1.0071	R/RINF=	.9886	T/TINF=	1.0187	GAM=	1.4000				
RECOVERY (PT/PINF)	=	.9439	KINETIC ENERGY EFF.=	.99769									
CONTRACTION (AINF/A)	=	.9873	EPS=	11.442	CROSS FLOW=	-.922							
EXPANSION FAN*		LEAD WAVE=	11.4420	FINAL WAVE=	3.7429	AVG WAVE=	7.5925						
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM													
M2=	5.937	DELTA XZ=	-6.000	EPS XZ=	11.822								
EXPANSION FAN*		LEAD WAVE=	11.8217	FINAL WAVE=	3.8703	AVG WAVE=	7.8460						
TOTAL CROSS FLOW (DELTA XY)=	.759		GAP RATIO (W1/W2)=	.973									

CASE NO 3	WAVE NO 1	K1	K2	K3	K4	K5							
	(WEAK SHOCK)	2	2	2	0	0							
***THERMALLY PERFECT GAS***													
IN FRONT OF WAVE													
M	MCHECK	TO	P/O	R	R/O	GAM							
6.00000	5.99999	2999.707	.13401	528.661	.000524911	.001863							
TOTAL PROPERTIES													
M	MCHECK	TO	P/O	R	R/O	GAM							
5.17765	5.17764	2999.706	.17273	498.961	.00127606	.003320							
BEHIND WAVE													
TOTAL PROPERTIES													
M	MCHECK	TO	P/O	R	R/O	GAM							
5.17765	5.17764	2999.706	.17273	498.961	.00127606	.003320							
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE													
MIN=	4.015	DELTA N=	8.927	PI=	.2775	RI=	.0019	TI=	402.00	PTI=	528.6610	GAM1=	1.4000
MZN=	3.374	EPN=	21.221	P2=	.6375	R2=	.0033	T2=	518.29	PT2=	498.9614	GAM2=	1.3996
REVR=	1.402	A1/A2=	1.700	P2/P1=	2.2972	R2/R1=	1.7819	T2/T1=	1.2893	IPR=	.9438	N=	R
FLOW PROPERTIES REFERENCED TO SWEEP WEDGE													
MIN	M1T	M2N	M2T	M2	P/PINF	R/RINF	T/TINF	GAM					
4.01478	4.45887	3.37387	3.92747	5.17765	2.29721	1.78194	1.28927	1.39958					
DELTA N	EPSN	AJOC	ACOI2P	ACOI3P	AEOI1P	THETA	DELTA N MAX	EPSN MAX					
8.92684	21.22136	14.56486	5.80582	1.68078	40.66402	42.00000	38.82164	66.08918					
M1=	6.000	SHEEP=	48.000	RIDGE ANGLE=	6.000	DE/AD=	0.000	PI=	.2775	TI=	402.00		
M2=	5.178	P/PINF=	2.2972	R/RINF=	1.7819	T/TINF=	1.2893	GAM=	1.3996				
RECOVERY (PT/PTINF) =	.9438	KINETIC ENERGY EFF.=		.99769									
CONTRACTION (AINF/A) =	1.7458	EPS=	14.565	CROSS FLOW=	1.681								
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM													
M2=	5.178	DELTA XZ=	6.000	EPS XZ=	14.565								
TOTAL CROSS FLOW (DELTA XY)=	1.681	GAP RATIO (WL/M2)=	1.688										

CASE NO 3	WAVE NO 2	K1	K2	K3	K4	K5
	(WEAK SHOCK)	2	2	2	0	0
**THERMALLY PERFECT GAS**						
IN FRONT OF WAVE						
M	MCHECK	T0	T/IO	P0	P/P0	R
5.17765	5.17764	2999.706	.17278	498.961	.001277606	.003320
						R/ZRO
						.007394459
						GAM
						1.39958
						N
						2
BEHIND WAVE						
M	MCHECK	T0	T/IO	P0	P/P0	R
4.54805	4.54804	2999.706	.21416	480.627	.002712833	.005478
						R/ZRO
						.012667153
						GAM
						1.39786
						N
						2
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE						
MIN=	3.374	DELTA=	8.927	PI=	.6375	R1=
						.0033
						TI=
						518.29
						PTI=
						498.9614
						GAM1=
						1.3996
						M2N=
						2.868
						EPN=
						24.088
						P2=
						1.3039
						R2=
						.0055
						T2=
						642.43
						PT2=
						480.6274
						GAM2=
						1.3979
						REYR=
						1.327
						A1/A2=
						1.561
						P2/P1=
						2.0454
						R2/R1=
						1.6508
						T2/T1=
						1.2395
						IPR=
						.9633
						N=
						R
						2
FLOW PROPERTIES REFERENCED TO SWEEP WEDGE						
M1N	M1T	M2N	M2T	M2	P/PINF	R/RINF
						T/TINF
						GAM
						1.39786
						3.37387
						3.92747
						2.86794
						3.52982
						4.54805
						4.69860
						2.94169
						1.59807
						1.39786
						DELTA
						EPSN
						AJOC
						ACO12P
						ACO13P
						AEO11P
						THETA
						DELTA MAX
						EPSN MAX
						N
						8.92684
						24.08782
						15.74766
						5.80334
						1.23208
						39.09345
						40.66402
						36.27601
						65.58789
						2
						M1=
						5.178
						SWEEP=
						49.535
						RIDGE ANGLE=
						5.803
						DE/AD=
						1.000
						PI=
						.6375
						TI=
						518.29
						M2=
						4.548
						P/PINF=
						4.6986
						R/RINF=
						2.9417
						T/TINF=
						1.5981
						GAM=
						1.3979
						RECOVERY (PI/PTINF) =
						.9091
						KINETIC ENERGY EFF.=
						.99616
						CONTRACTION (AINF/A) =
						2.8167
						EPS=
						15.748
						CROSS FLOW=
						1.232
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM						
M2=	4.548	DELTA XZ=	6.000	EPS XZ=	10.277	
TOTAL CROSS FLOW (DELTA XY)=						
	2.907	GAP RATIO (M1/M2)=	2.654			

APPENDIX A - Concluded

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CASE NO 3 WAVE NO 3 (WEAK SHOCK) K1 K2 K3 K4 K5
                2 2 2 2 0 0
***THERMALLY PERFECT GAS***
IN FRONT OF WAVE
TOTAL PROPERTIES
M MCHECK TC P/PO P/PO R/R0 R/R0 GAM N
4.54805 4.54804 2999.706 .21415 480.627 .002712833 .005478 .012667153 1.39785 2
BEHIND WAVE
TOTAL PROPERTIES
M MCHECK TO T/T0 P0 P/PO R/R0 R/R0 GAM N
4.05131 4.05130 2999.707 .25738 468.389 .005185326 .008502 .020146935 1.39377 2
FLOW PROPERTIES MEASURED NORMAL TO WEDGE LEADING EDGE
MIN= 2.868 DELTAN= 8.927 P1= 1.3039 R1= .0055 I1= 642.43 P1I= 480.6274 GAM1=1.3979
M2N= 2.453 EPN= 27.384 P2= 2.4319 R2= .0085 I2= 772.05 P2I= 468.9891 GAM2=1.3938
REVR= 1.265 A1/A2= 1.453 P2/P1= 1.8651 R2/R1= 1.5520 I2/I1= 1.2018 TPR= .9758 N= 3
FLOW PROPERTIES REFERENCED TO SWEEP WEDGE
M1N M1T M2N M2T P/PINF R/RINF I/IINF GAM
2.86794 3.52982 2.45253 3.22462 4.05131 8.76346 4.56542 1.92052 1.39377
DELTA EPSN AJOC ACOI2P ACOI3P AE0I1P THETA DELTAN MAX EPSN MAX N
8.92684 27.38449 18.08956 5.39400 2.17396 37.25537 39.09345 33.17773 65.13902 2
M1= 4.548 SWEEP= 50.907 RIDGE ANGLE= 5.657 DE/AD= 0.000 P1= 1.3039 I1= 642.43
M2= 4.051 P/PINF= 8.7635 R/RINF= 4.5654 I/IINF= 1.9205 GAM= 1.3938
RECOVERY (PI/PIINF) = .8871 KINETIC ENERGY EFF.= .99514
CONTRACTION (AINE/A) = 4.2626 EPS= 18.090 GROSS FLOW= 2.174
FLOW PROPERTIES REFERENCED TO INITIAL XYZ COORDINATE SYSTEM
M2= 4.051 DELTA XZ= 6.000 EPS XZ= 19.117
TOTAL GROSS FLOW (DELTA XYI)= 5.081 GAP RATIO (M1/W2I)= 3.827
    
```

## APPENDIX B

### INLET PERFORMANCE FOR LOW REYNOLDS NUMBER AND UNSTARTED OPERATION

In order to evaluate the inlets operating characteristics better, one test was made with the Reynolds number reduced by a factor of 1/3 to  $3.3 \times 10^6$  per meter. The resulting static-pressure distributions within the inlet are found in figure 61 where they are compared with the high-pressure tests. Also given in figure 61 are the results of a test in which the model failed to start because of blockage produced by a survey rake.

The low Reynolds number tests had only a small effect on inlet operation as determined by static-pressure level changes produced by slight alterations in shock-wave positions. In the side passage these effects were seen near the cowl in figures 61(f) and 61(h), whereas the center-passage effects are observed in figure 61(k). The high-pressure level indicated on the foreplate (fig. 61(a)) is in error because of the difficulty in measuring the extremely low pressures.

Alterations in static-pressure levels for the unstarted choked inlet were observed throughout the model. High pressures were found on the foreplate (fig. 61(a)), top surface (figs. 61(b) and 61(c)), sidewalls in front of the struts (fig. 61(d)), and on the cowl (figs. 61(f) and 61(g)). The pressure level in the center passage was low and uniform and indicated the absence of shock waves (figs. 61(i) and 61(k)).

## APPENDIX C

### CAPTURE MEASUREMENT DATA

The primary conclusions from the capture measurement data (Mach number and capture parameter contour maps) taken downstream from the struts are presented in the report in figures 53 and 54. The purpose of this appendix is to include the data from pitot and static-pressure surveys used to produce those results. Like the data taken at the inlet throat, the program used to analyze these data and generate the contour maps is discussed in appendix B.

The static-pressure distribution around the walls of the inlet at the capture measurement station is given in figure 62 where  $\lambda$  is the peripheral distance around the area as defined in the sketch. The static probe survey data are found in figure 63 which also includes the wall values of figure 62. A nominal value of 80 percent was selected for the total-pressure recovery limit at the capture measurement location downstream of the struts. When the static surveys were combined with the pitot surveys of figure 64, the computed total-pressure recovery was above the imposed limit of 80 percent only in the very small region indicated by the dashed line in figure 63(d). The data are seen in contour map form in figures 65 and 66, and a total-pressure recovery map is given in figure 67.

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TABLE I.- THEORETICAL FLOW FIELD PROPERTIES USED FOR FIGURE 5

Bay	M	P/P <sub>1</sub>	P <sub>t</sub> /P <sub>t,1</sub>	δ <sub>xz</sub>	δ <sub>xy</sub>	A/A <sub>1</sub>	P <sub>pitot</sub> /P <sub>1</sub>
1	6.0	1.0	1.0	0	0	1.0	46.8
2	5.18	2.30	.944	6.0	1.7	1.75	80.4
3	4.54	4.70	.910	0	2.9	2.81	127.0
4	4.04	8.77	.888	6.0	5.1	4.26	188.0
5	3.76	12.74	.883	2.0	6.2	5.25	237.0
6	3.51	18.02	.879	6.0	7.9	6.85	294.0
7	4.75	3.74	.933	10.0	2.8	2.43	110.0
8	4.21	7.16	.903	4.0	4.5	3.74	167.0
9	3.77	12.67	.891	10.0	6.9	5.45	238.0
10	3.40	20.99	.879	6.0	8.95	7.57	322.0
11	3.17	28.91	.871	2.0	10.5	9.29	388.0
12	4.54	4.70	.910	0	2.9	2.81	127.0
13	4.04	8.77	.888	-6.0	5.1	4.26	188.0
14	3.76	12.77	.886	-2.0	6.2	5.46	238.0
15	3.51	18.02	.879	-6.0	7.9	6.85	294.0
16	3.08	33.26	.870	10.0	12.2	10.16	422.0

Free stream

Side-passage throat

Center-passage throat

TABLE II.- THEORETICAL END EFFECTS USED FOR FIGURE 5

(a) Top surface ( $\delta_{xy} = 4^\circ$ )

Bay	M	p/p <sub>1</sub>	p <sub>t</sub> /p <sub>t,1</sub>	p <sub>pitot</sub> /p <sub>1</sub>
2	4.92	3.07	0.939	97.1
3	4.46	5.22	.910	136.0
4	4.13	7.79	.888	175.0
5	3.92	10.25	.883	208.0
6	3.77	12.53	.879	235.0
7	4.67	4.26	.933	122.0
8	4.25	6.80	.903	161.0
9	3.98	9.53	.891	199.0
10	3.72	13.58	.879	248.0
11	3.56	16.47	.871	277.0
12	4.46	5.22	.910	136.0
13	4.13	7.79	.888	175.0
14	3.92	10.27	.886	208.0
On plow*	5.33	1.98	.968	73.3

(b) Cowl ( $\delta_{xy} = 0^\circ$ )

Bay	M	p/p <sub>1</sub>	p <sub>t</sub> /p <sub>t,1</sub>	p <sub>pitot</sub> /p <sub>1</sub>
2	4.99	2.82	0.942	91.7
3	4.28	6.48	.907	156.0
4	3.67	14.40	.877	256.0
5	3.35	22.30	.867	333.0
6	3.04	34.90	.854	432.0
7	4.48	5.17	.930	136.0
8	3.86	11.30	.894	222.0
9	3.31	23.60	.870	344.0
10	2.88	43.40	.846	484.0
11	2.62	63.60	.829	592.0
12	4.28	64.80	.907	156.0
13	3.67	14.40	.877	257.0
14	3.35	22.40	.870	334.0

\*In front of bay number 2.

TABLE III.- CORRECTED THEORETICAL FLOW FIELD PROPERTIES  
USED FOR FIGURE 27

Bay	M	p/p <sub>1</sub>	p <sub>t</sub> /p <sub>1</sub>	δ <sub>xz</sub>	δ <sub>xy</sub>	A/A <sub>1</sub>	p <sub>pitot</sub> /p <sub>1</sub>
1	6.00	1.00	1.000	0	0	1.00	46.8
2	5.07	2.54	.922	6.83	2.00	1.80	85.2
3	4.46	5.12	.891	0	3.18	2.96	133.0
4	3.97	9.44	.870	6.00	5.40	4.44	196.0
5	3.70	13.61	.866	2.00	6.52	5.66	246.0
6	3.45	19.14	.862	6.00	8.27	7.07	302.0
7	4.66	4.09	.912	10.83	3.19	2.56	116.0
8	4.07	8.37	.879	4.00	5.20	4.11	182.0
9	3.59	15.55	.858	10.83	8.14	6.16	265.0
10	3.24	25.52	.842	4.83	10.28	8.45	357.0
11	---	----	-----	-----	-----	---	-----
12	4.38	5.59	.879	0	3.44	3.13	141.0
13	3.90	10.19	.859	-6.00	5.71	4.65	204.0
14	3.64	14.62	.857	-2.00	6.87	5.91	256.0
*15	3.40	20.40	.852	-6.00	8.66	7.34	313.0
16	3.24	25.28	.835	4.83	11.30	8.38	354.0

\*For large center strut.

TABLE IV.- CORRECTED THEORETICAL END EFFECTS USED FOR FIGURE 27

(a) Top surface ( $\delta_{xy} = 4^\circ$ )

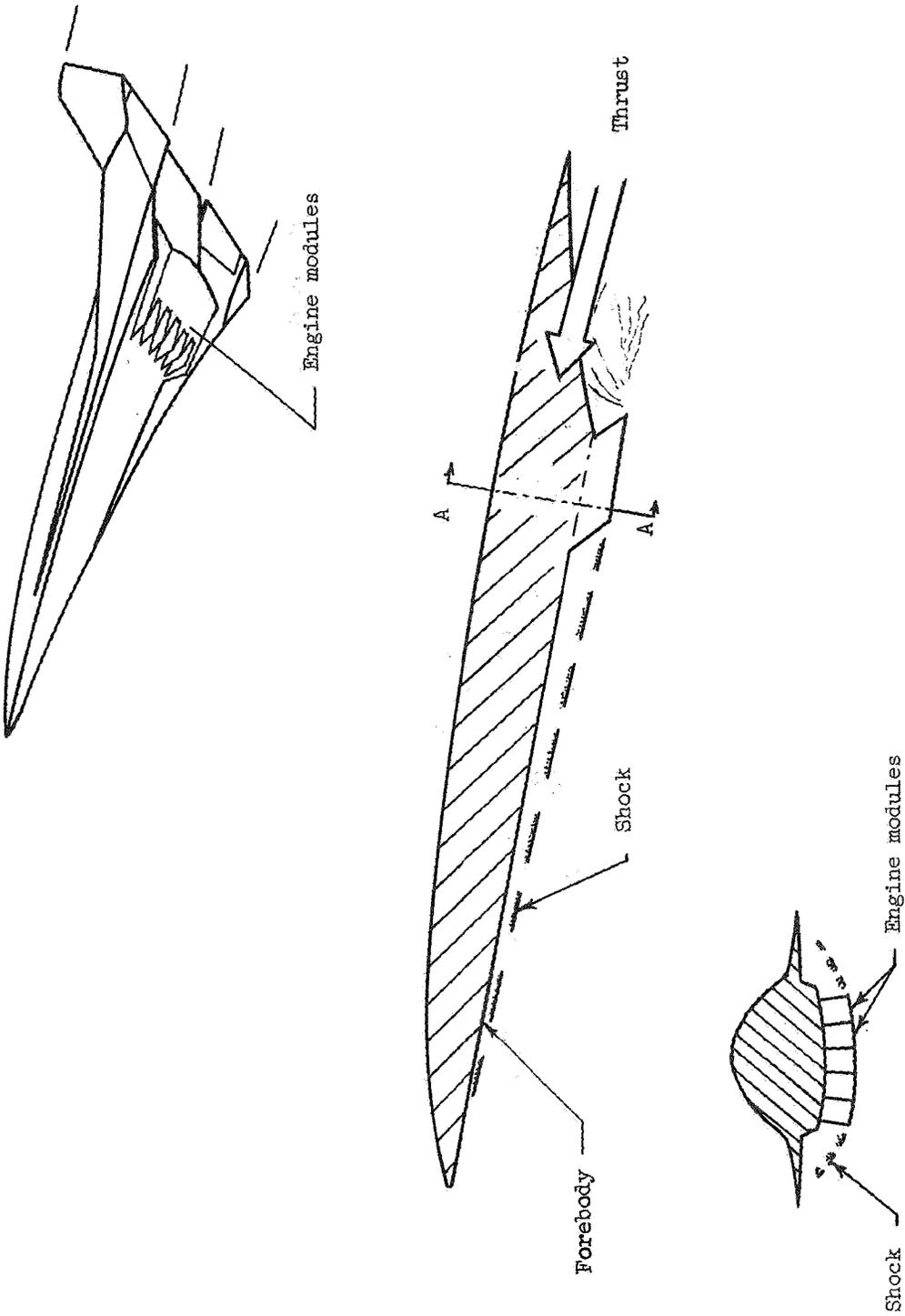
Bay	M	p/p <sub>1</sub>	p <sub>t</sub> /p <sub>t,1</sub>	p <sub>pitot</sub> /p <sub>1</sub>
2	4.86	3.25	0.921	100.0
3	4.39	5.61	.891	142.0
4	4.07	8.26	.870	180.0
5	3.88	10.60	.866	210.0
6	3.73	12.90	.862	522.0
7	4.58	4.46	.912	123.0
8	4.17	7.34	.879	168.0
9	3.87	10.60	.858	209.0
10	3.63	14.60	.842	254.0
11	---	---	---	---
12	4.33	5.95	.878	146.0
13	4.03	8.56	.859	183.0
14	3.84	11.10	.857	216.0
*15	3.70	13.40	.852	242.0
16	3.69	13.80	.835	248.0

\*For large center strut.

(b) Cowl ( $\delta_{xy} = 0^\circ$ )

Bay	M	p/p <sub>1</sub>	p <sub>t</sub> /p <sub>t,1</sub>	p <sub>pitot</sub> /p <sub>1</sub>
2	4.86	3.25	0.921	100.0
3	4.18	7.22	.996	166.0
4	3.57	15.80	.858	267.0
5	3.28	24.30	.849	348.0
6	2.97	37.80	.835	447.0
7	4.35	6.52	.902	162.0
8	3.68	13.40	.867	240.0
9	3.10	31.10	.829	399.0
10	2.69	56.30	.801	551.0
11	---	---	---	---
12	4.11	8.08	.873	180.0
13	3.50	17.40	.845	283.0
14	3.22	26.60	.838	368.0
*15	2.90	41.10	.822	465.0
16	2.63	59.90	.783	562.0

\*For large center strut.



Section A-A

Figure 1.- Airframe-scramjet-engine integration.

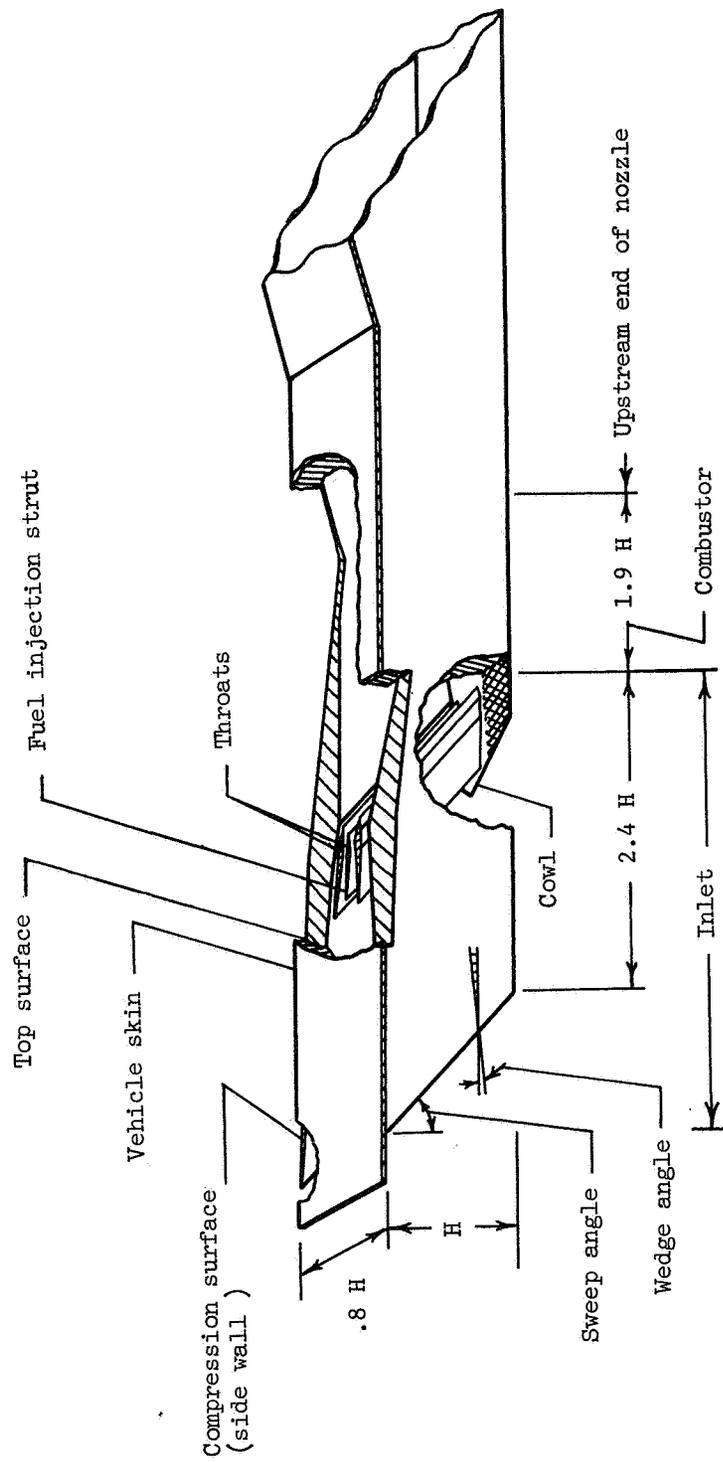


Figure 2.- Inner module of scramjet engine concept (ref. 8).

Plane of minimum (1-D) cross-sectional area

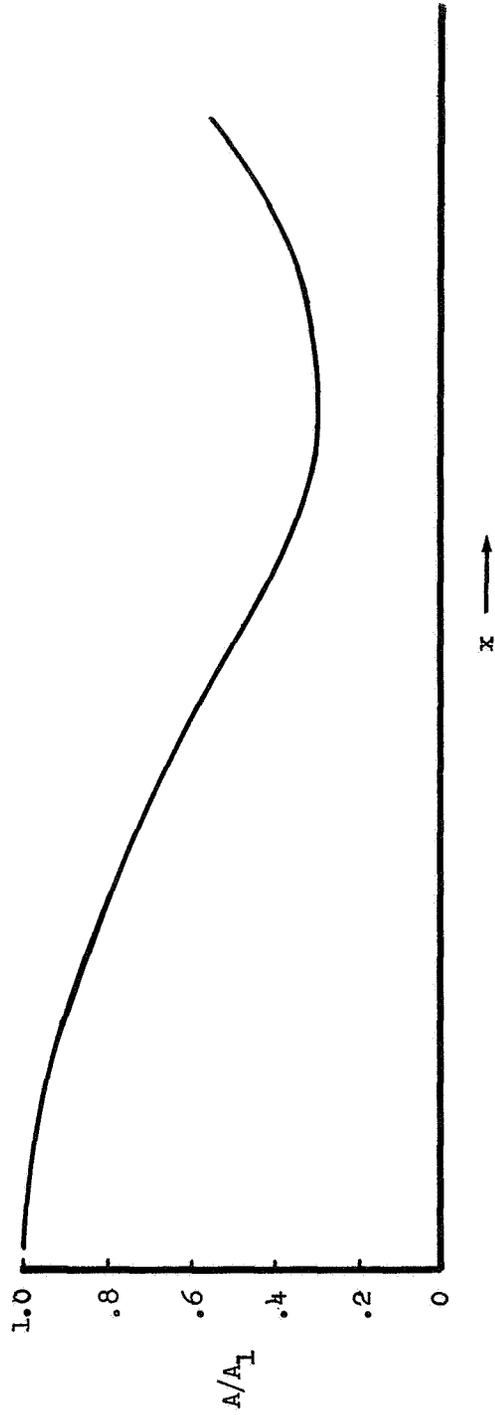
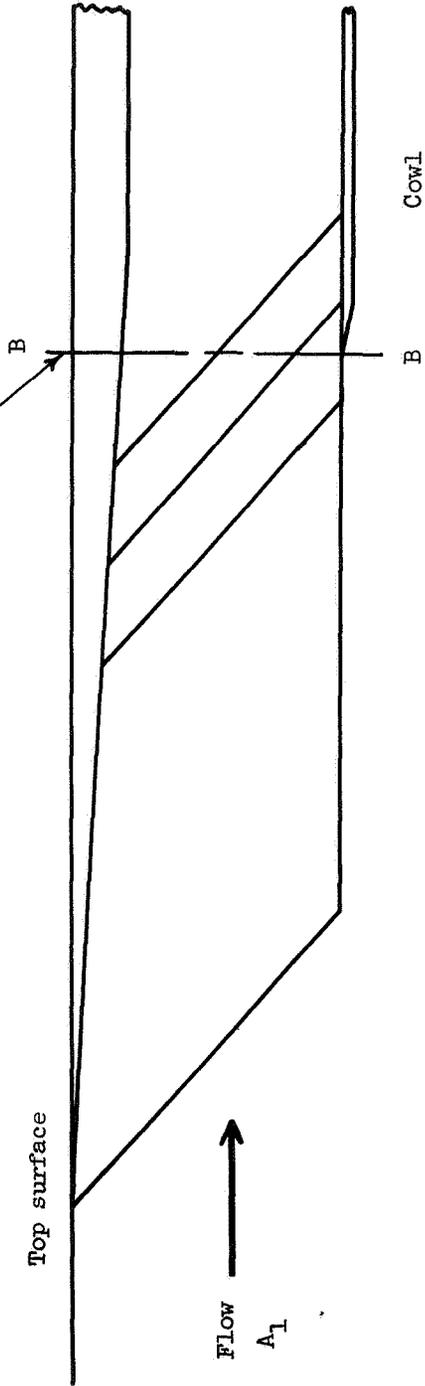


Figure 3.- One-dimensional inlet contraction.

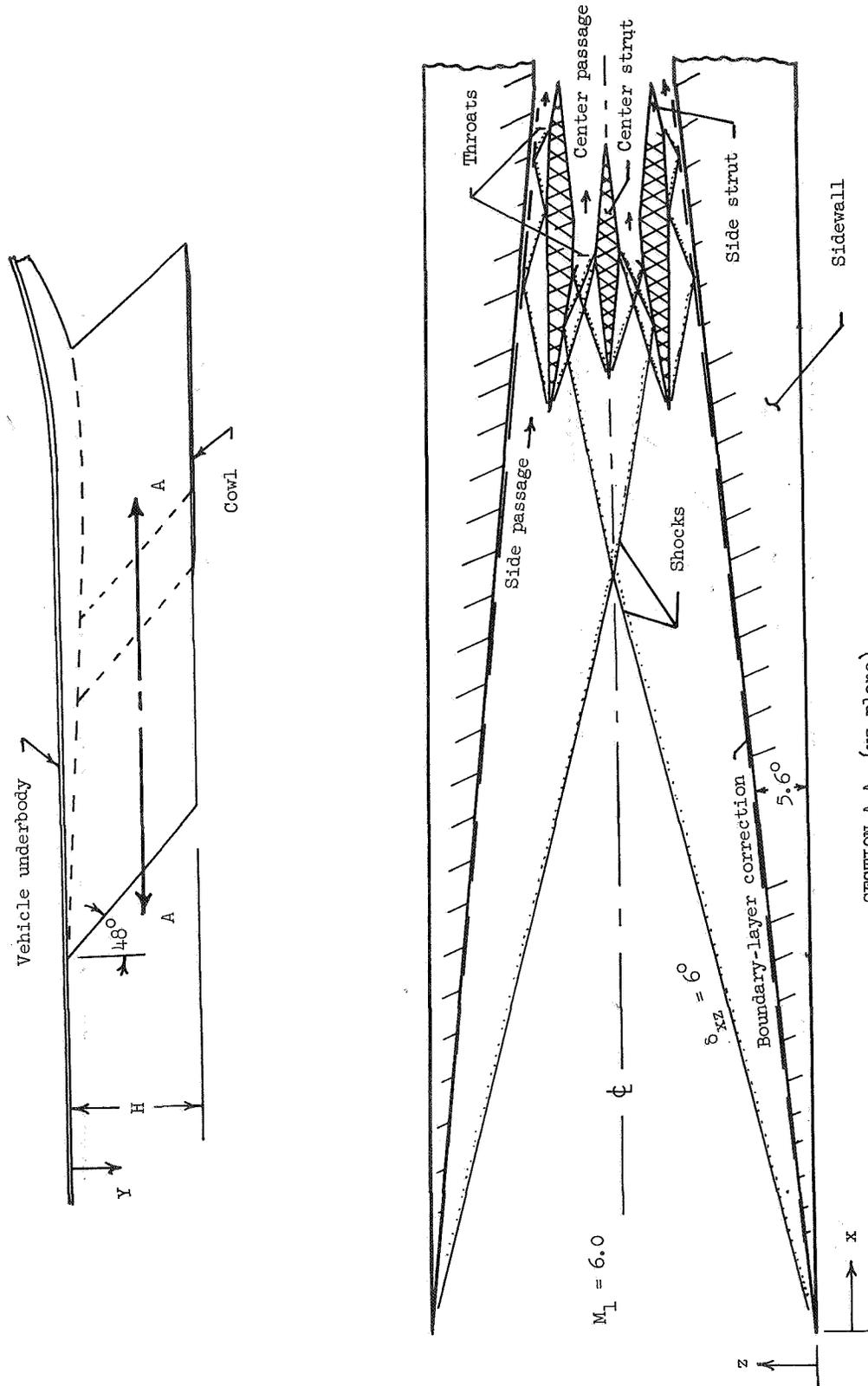
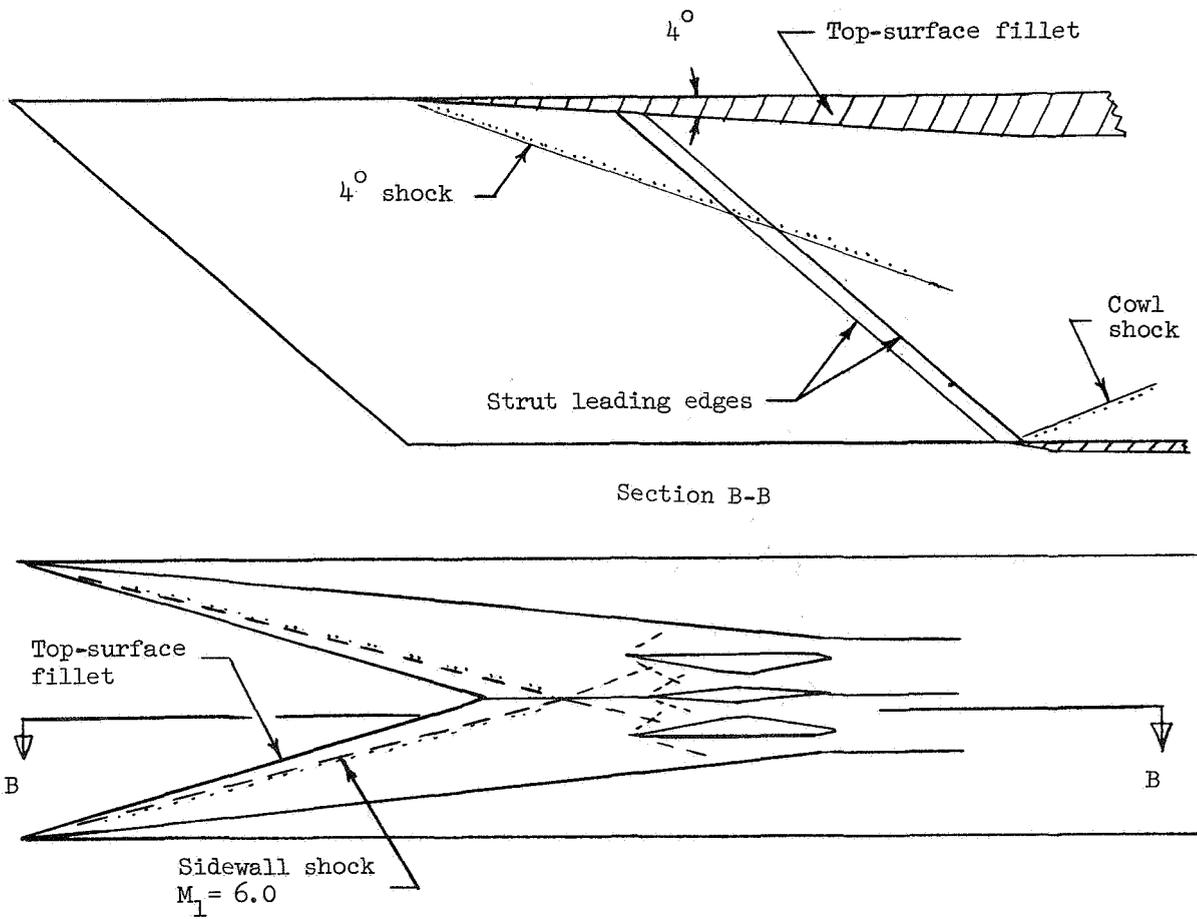


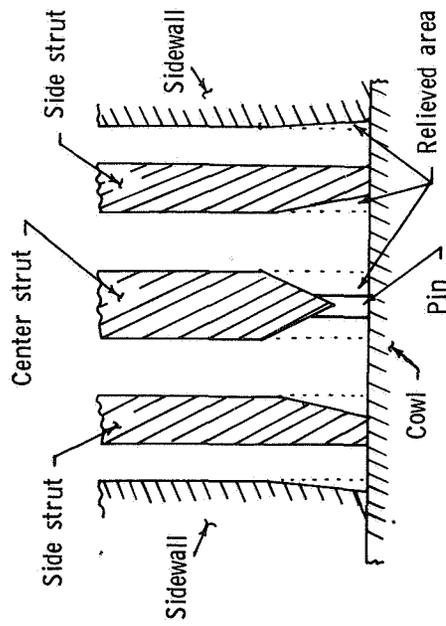
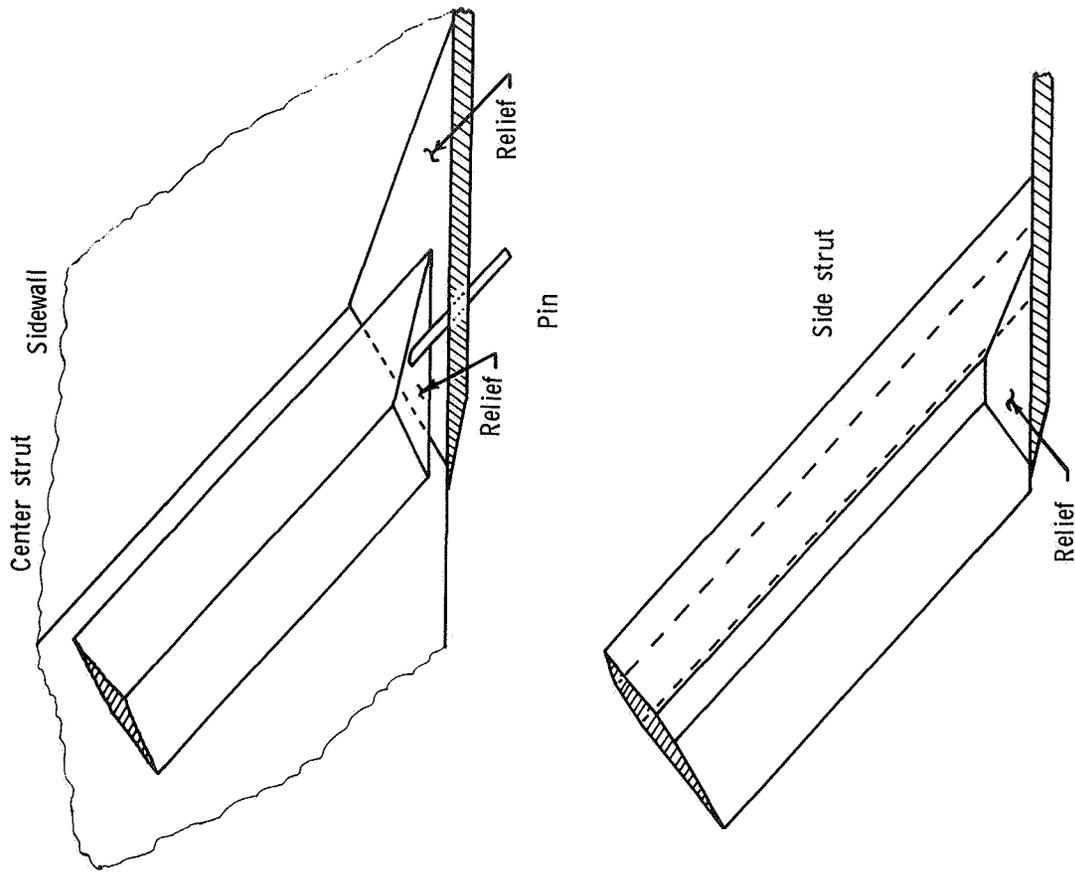
Figure 4.- Inlet model sketch and Mach 6 shock diagram.





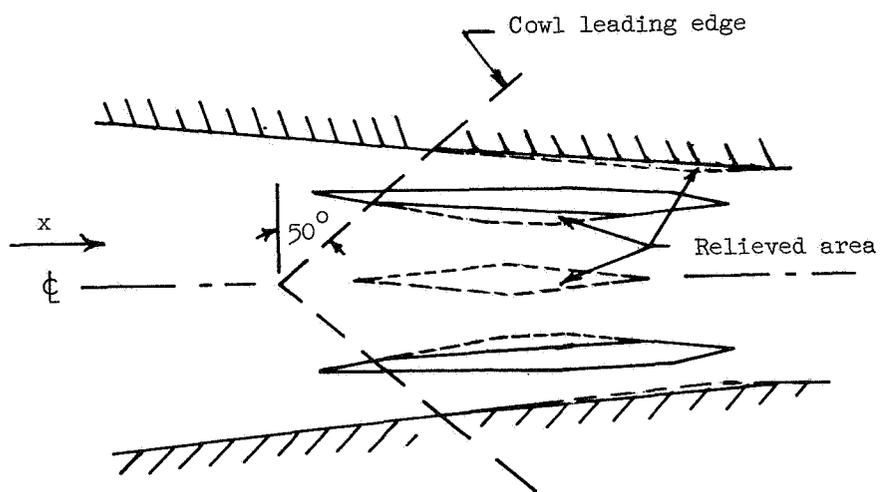
(a) Top surface.

Figure 6.- Theoretical end effects.



(b) Throat relief next to cowl.

Figure 6.- Continued.



(c) Cowl leading-edge design.

Figure 6.- Concluded.

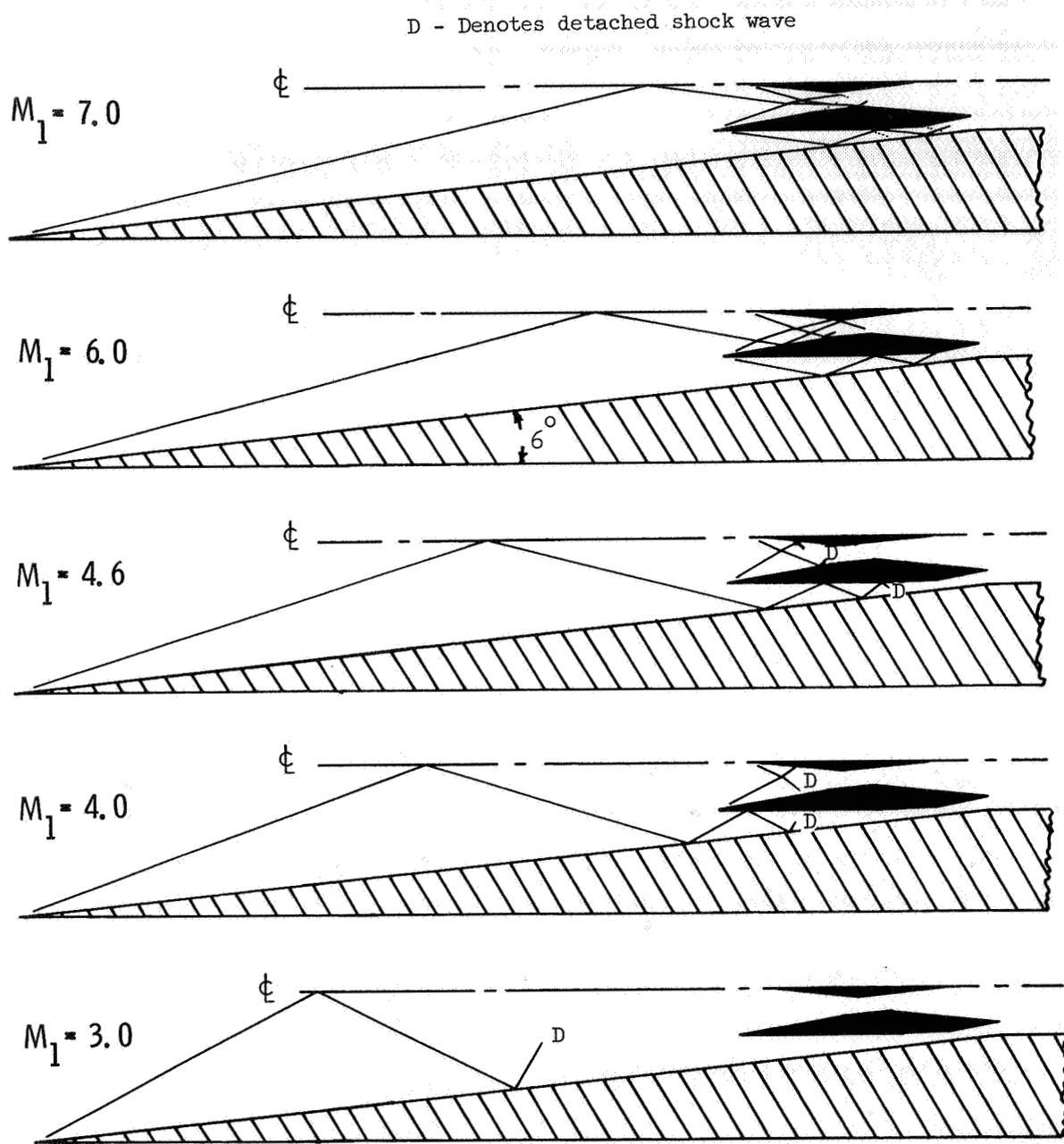
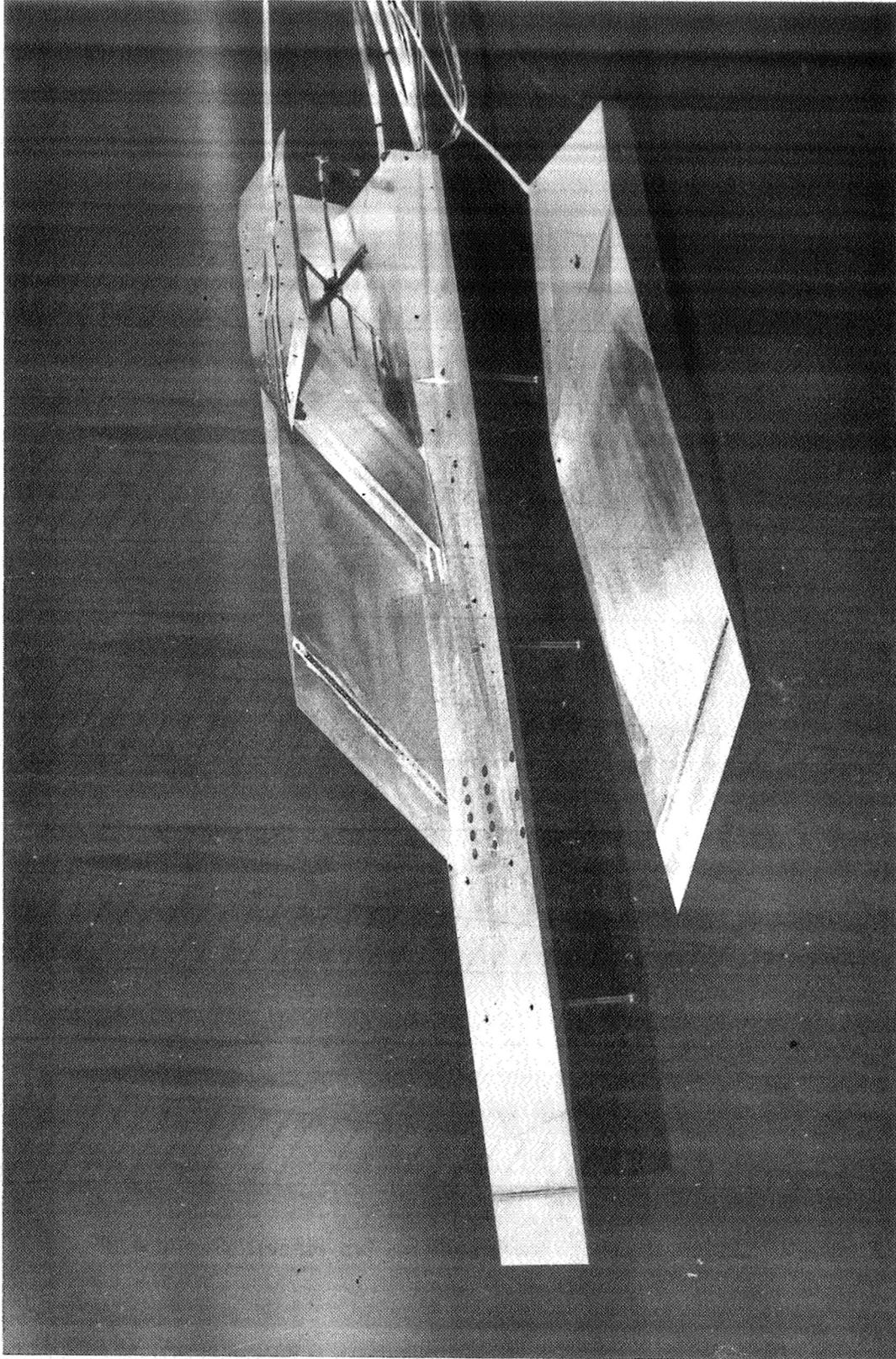


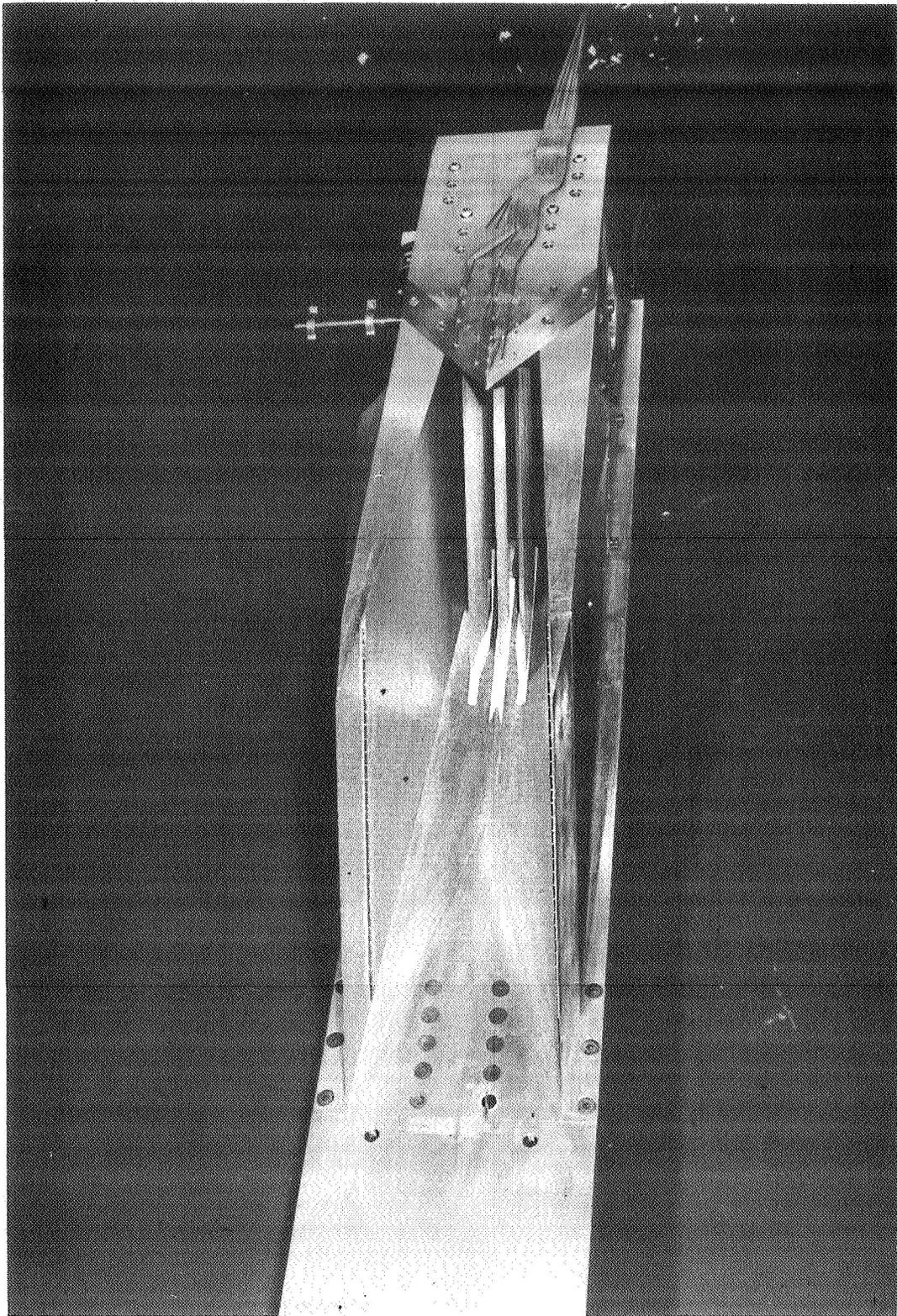
Figure 7.- Off-design shock wave systems (xz-plane). Sweep =  $48^\circ$ .



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(a) Side view.

Figure 8.- Model photograph.



L-72-7494

(b) Front view.

Figure 8.- Concluded.

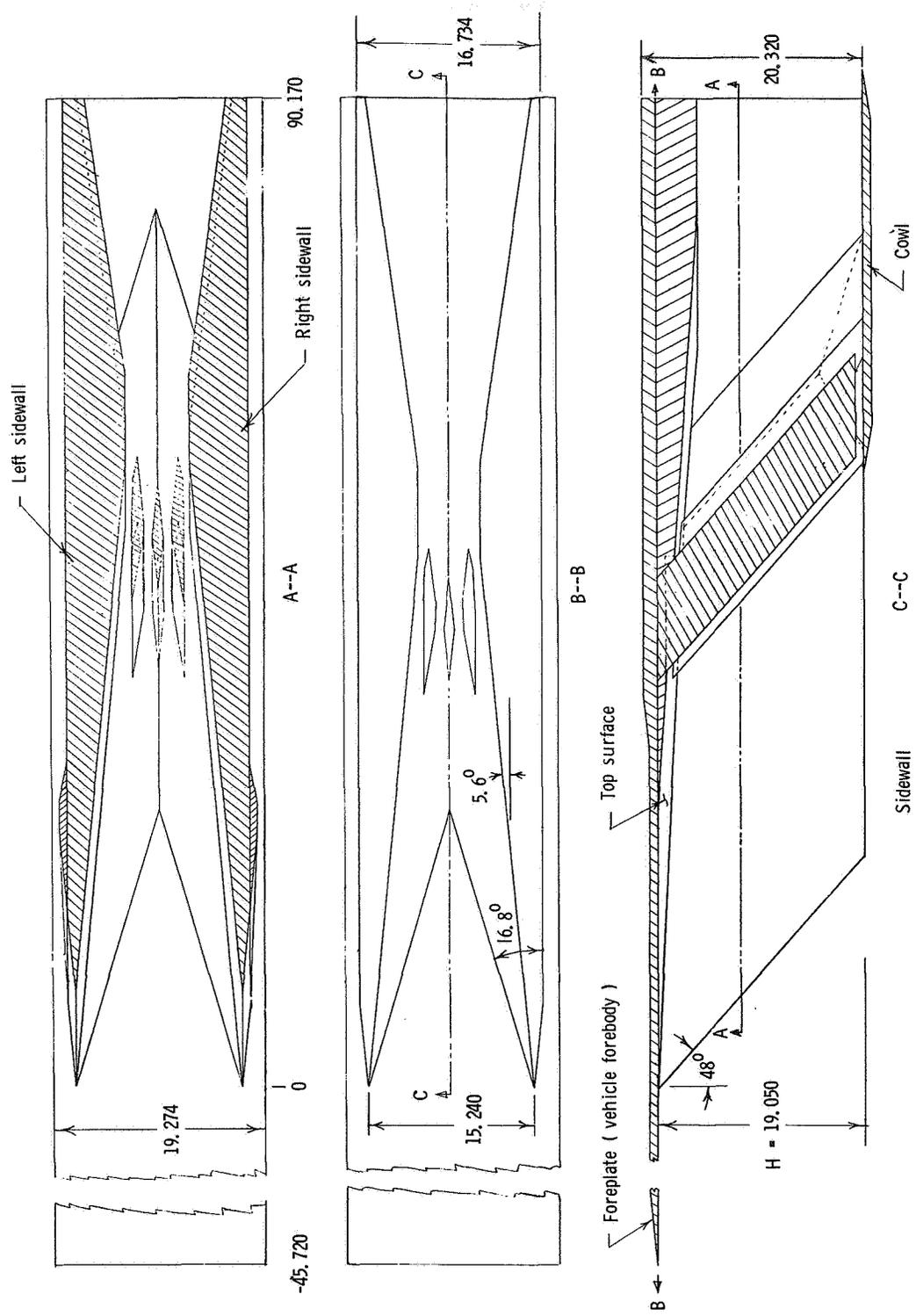


Figure 9.- Model schematics. All dimensions are in centimeters.

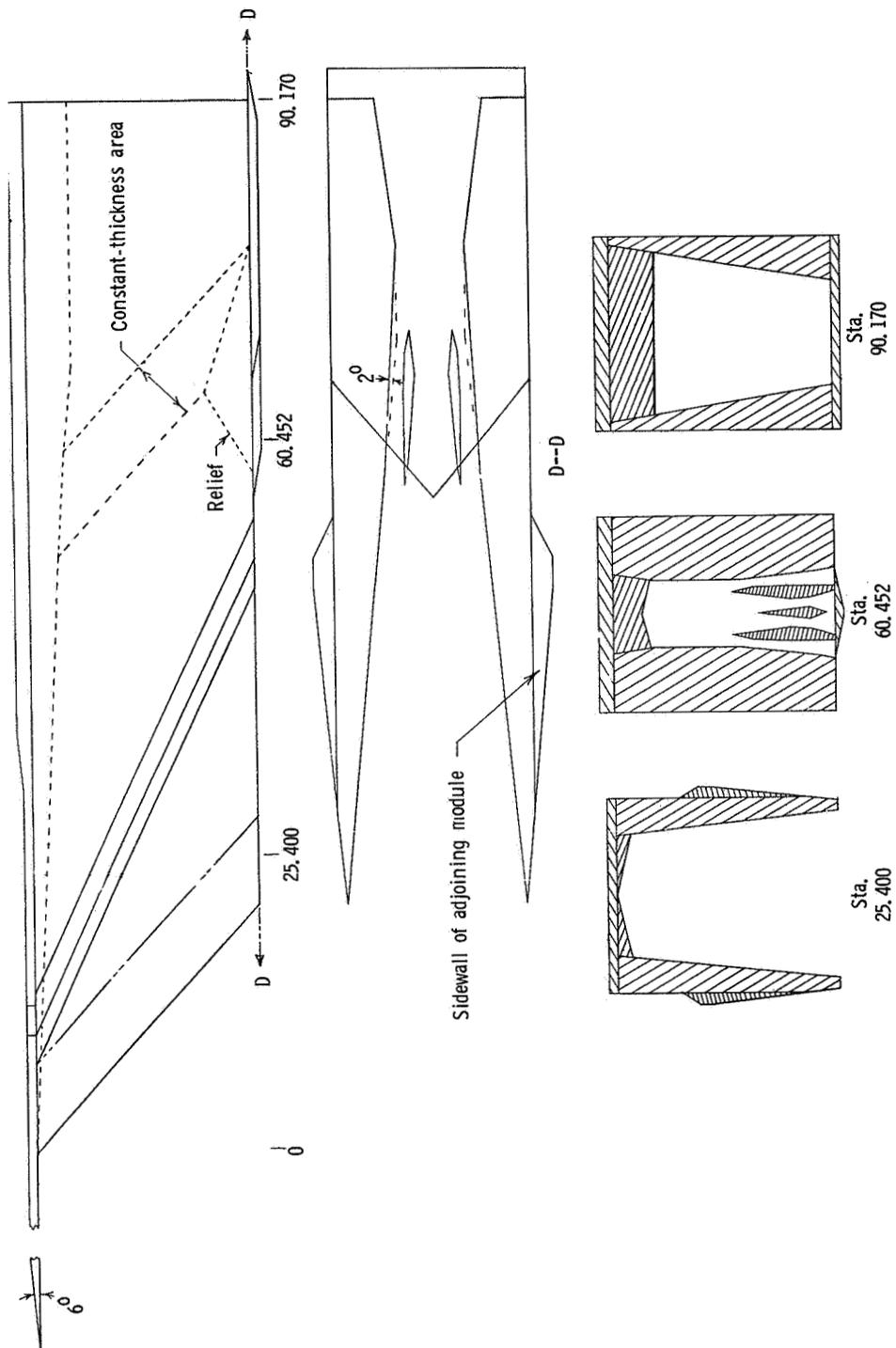


Figure 9.- Concluded.

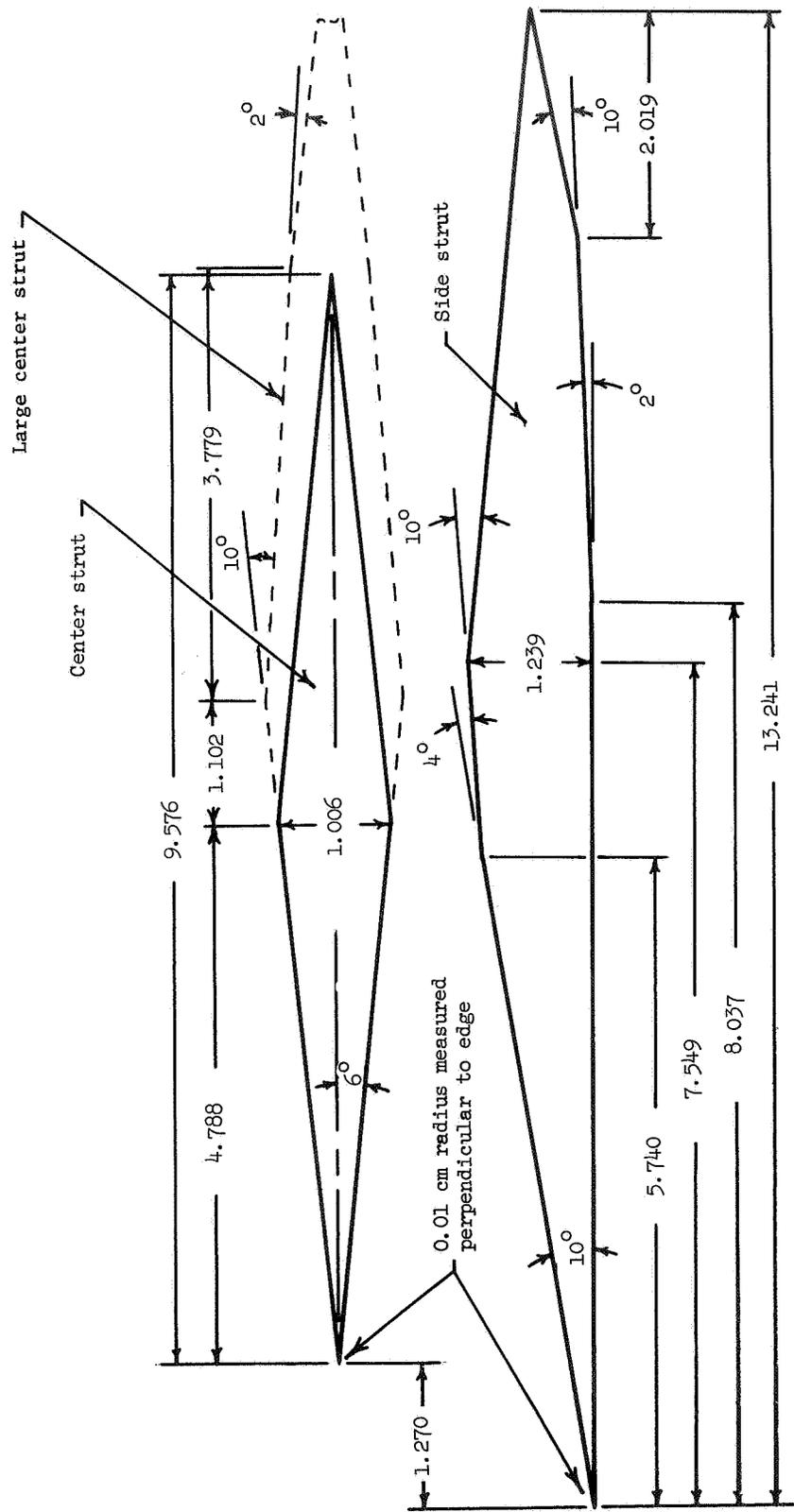


Figure 10.- Side and center strut dimensions as measured in the xz-plane. All dimensions are in centimeters.

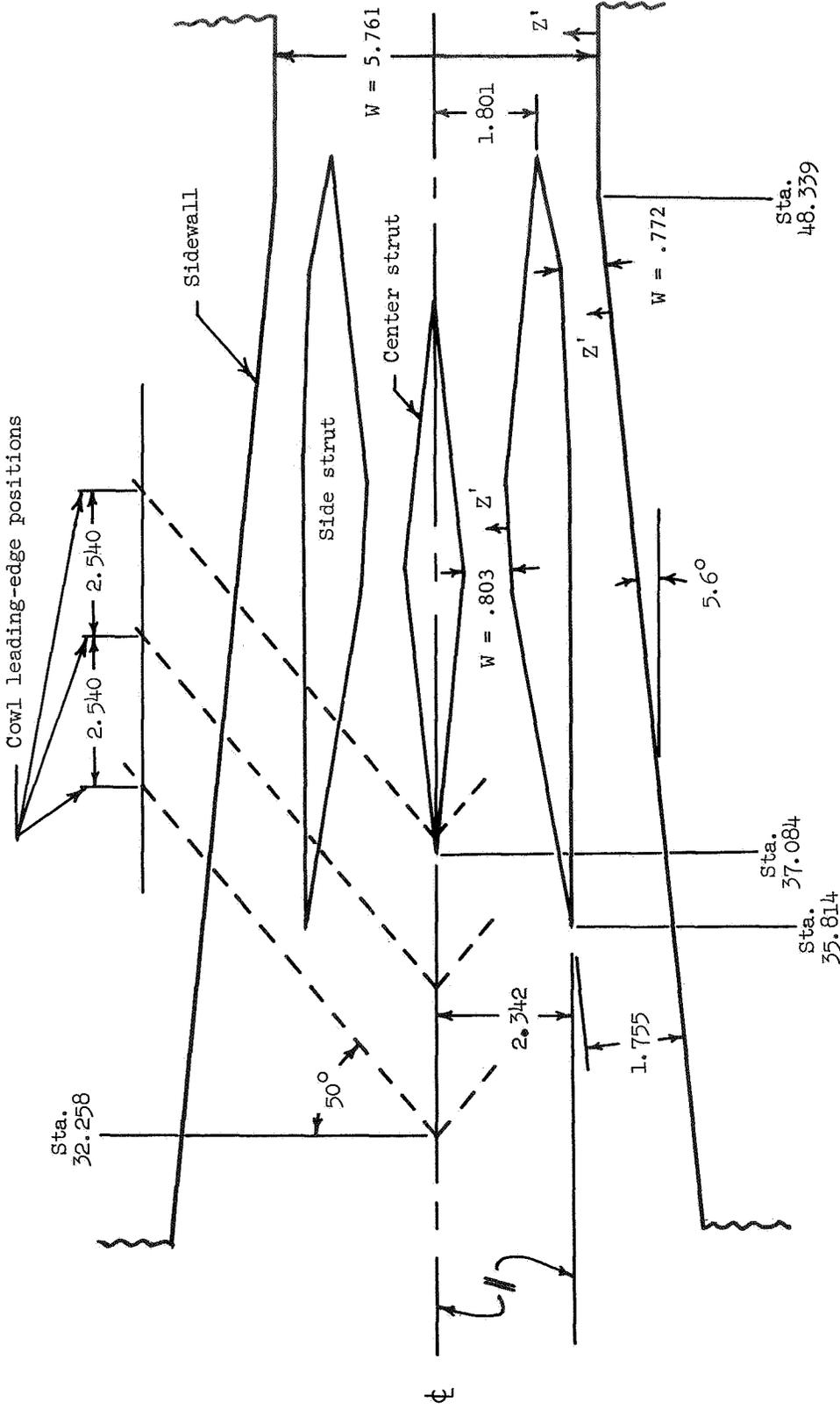


Figure 11.- Relative positions of struts and cowl in xz-planes. All dimensions are in centimeters. Stations are measured relative to sidewall leading edge; cowl leading edge shown at  $y = H$ .

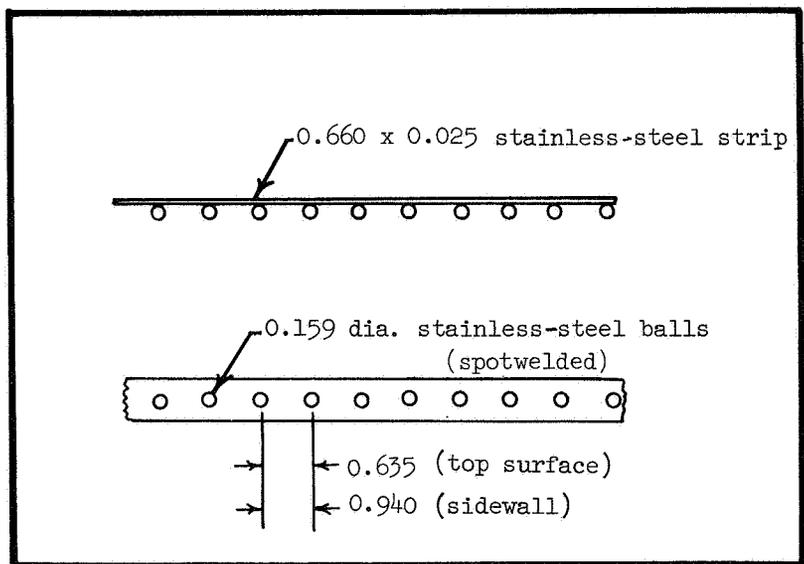
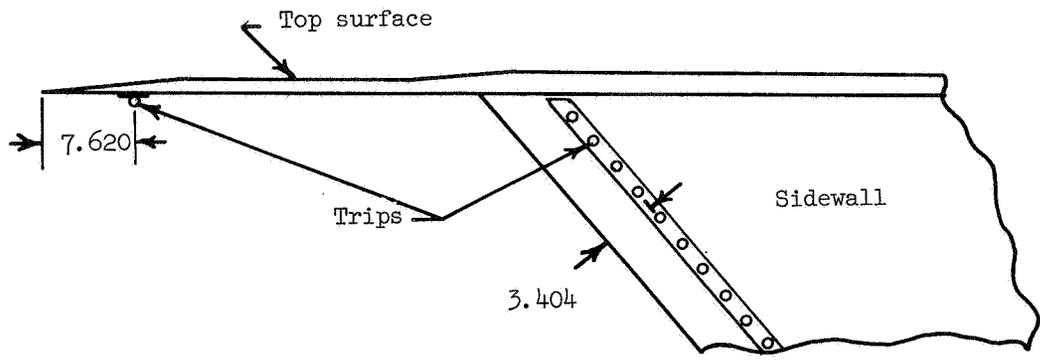


Figure 12.- Boundary-layer trips. All dimensions are in centimeters.

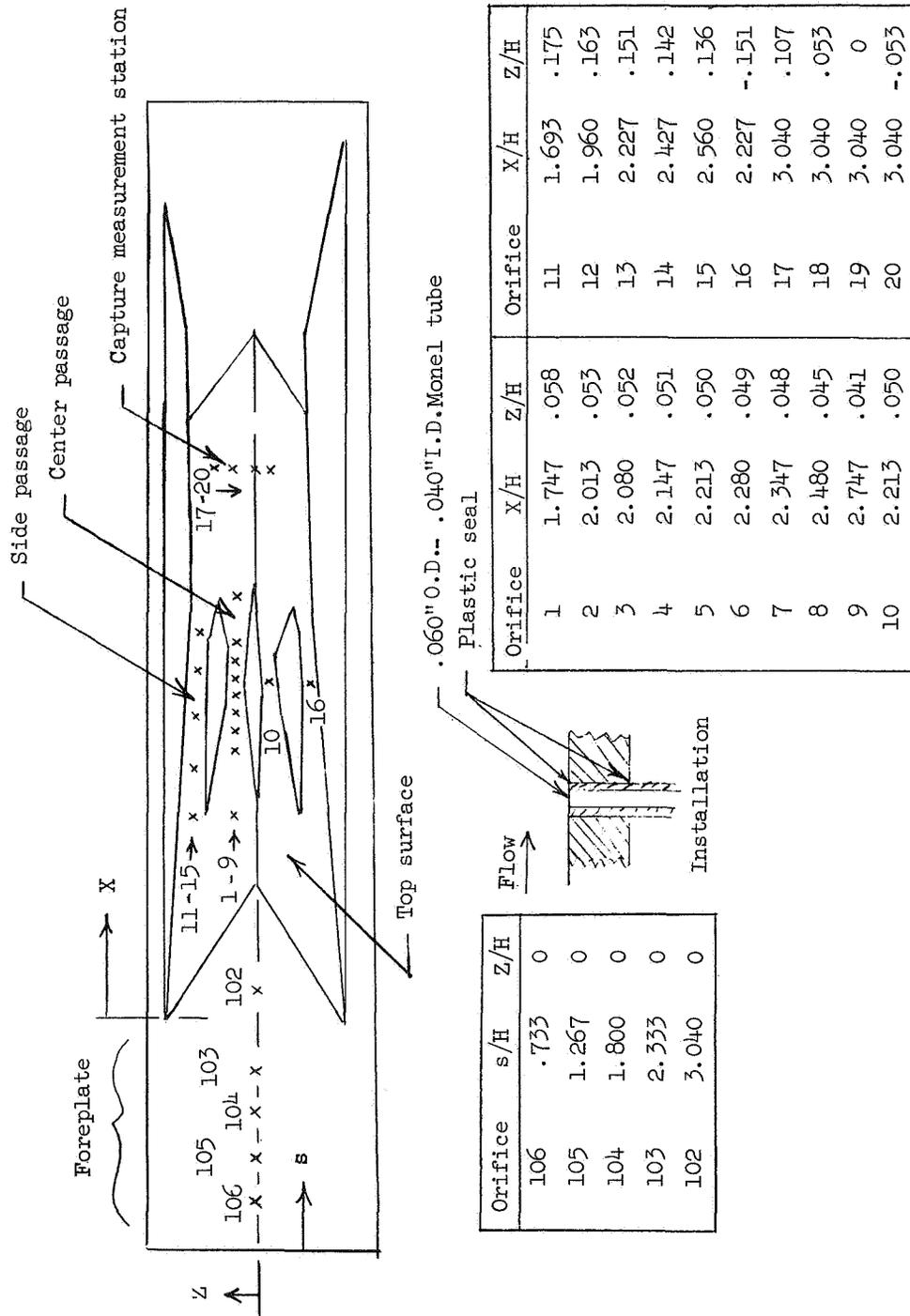
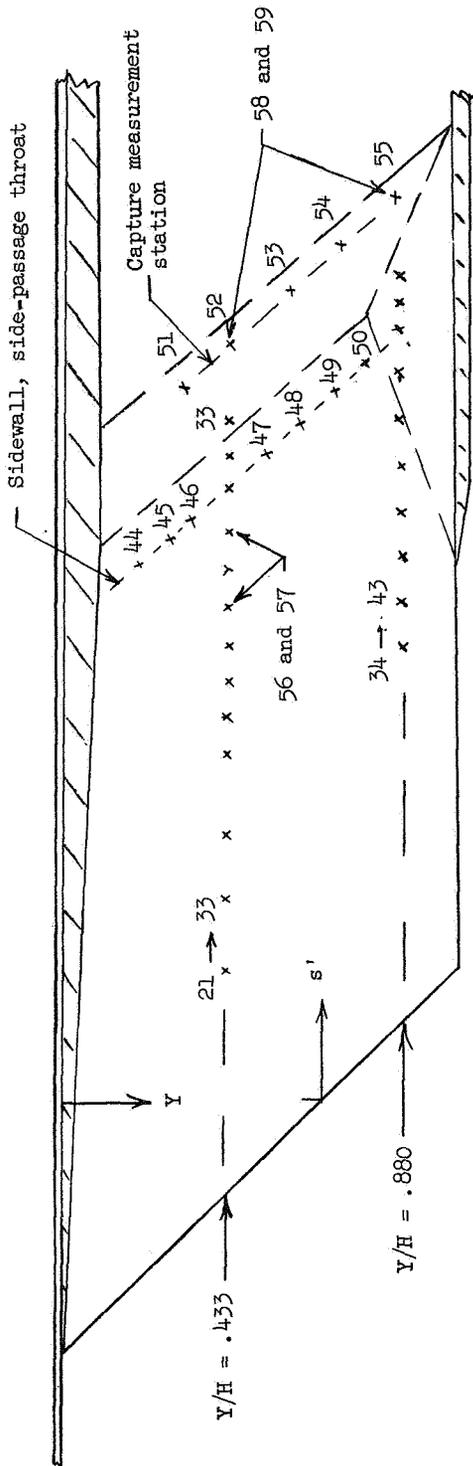


Figure 13.- Static orifice locations. H = 19.05 cm.



Left sidewall

Orifice	s'/H	Y/H
21	.924	.433
22	1.191	.433
23	1.457	.433
24	1.724	.433
25	1.857	.433
26	1.991	.433
27	2.124	.433
28	2.257	.433
29	2.324	.433
30	2.391	.433

Orifice	s'/H	Y/H
31	2.457	.433
32	2.524	.433
33	2.591	.433
34	1.591	.880
35	1.724	.880
36	1.857	.880
37	1.991	.880
38	2.124	.880
39	2.257	.880
40	2.391	.880

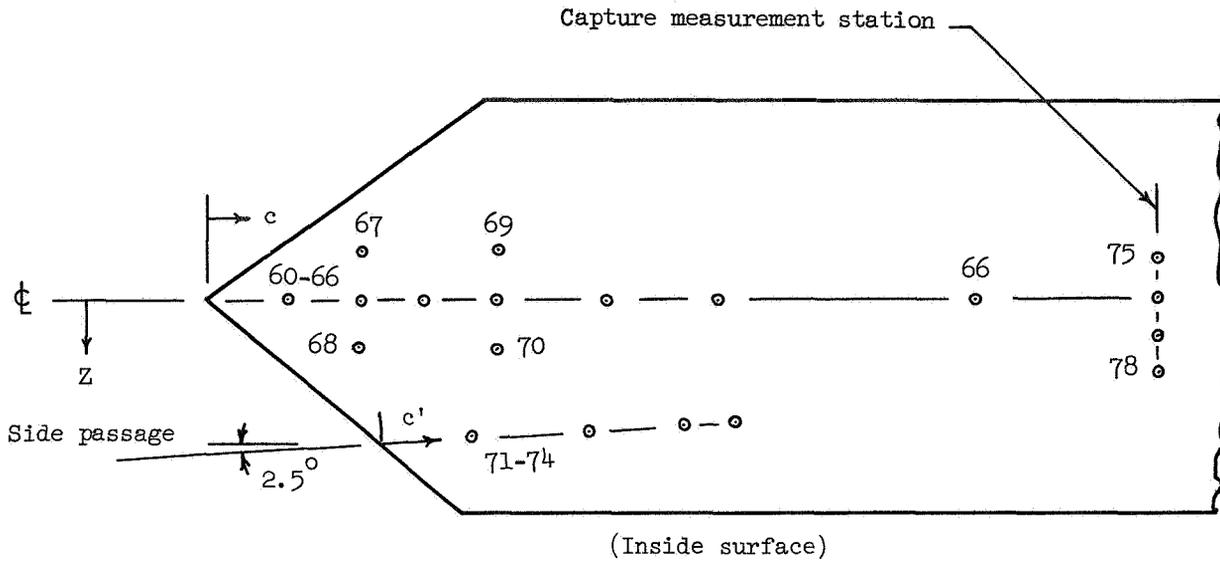
Orifice	s'/H	Y/H
41	2.457	.880
42	2.524	.880
43	2.591	.433
44	2.457	.166
45	2.457	.255
46	2.457	.344
47	2.497	.522
48	2.457	.612
49	2.457	.701
50	2.457	.790

Orifice	s'/H	Y/H
51	2.907	.284
52	2.907	.433
53	2.907	.582
54	2.907	.731
55	2.907	.880
*56	2.257	.433
*57	2.391	.433
*58	2.907	.433
*59	2.907	.880

\*Right sidewall

(c) Sidewall.

Figure 13.- Continued.

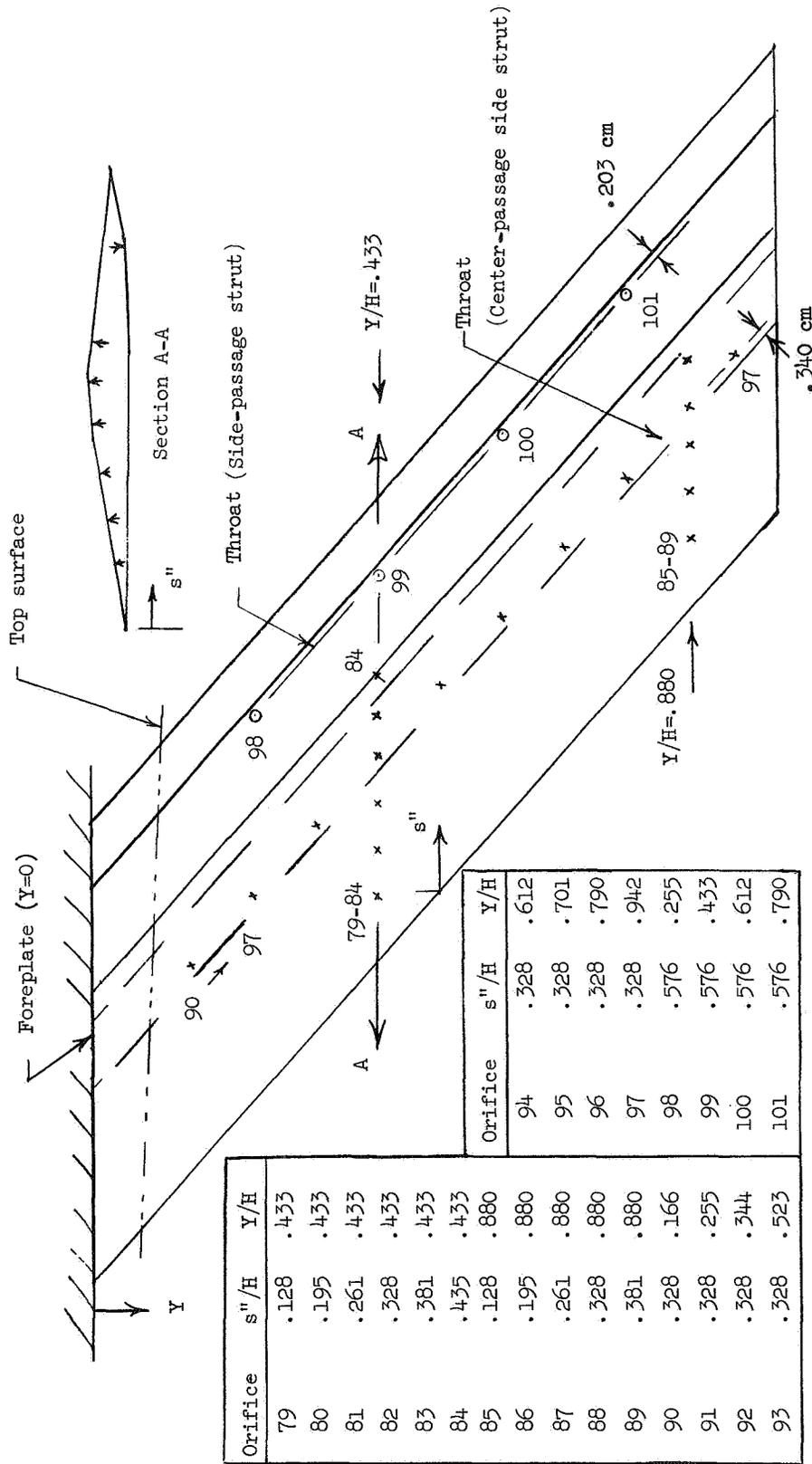


Orifice	$c/H$	$Z/H$
60	.093	0
61	.160	0
62	.227	0
63	.293	0
64	.427	0
65	.560	0
66	.827	0
67	.160	-.056
68	.160	.056
69	.293	-.056
70	.293	.056

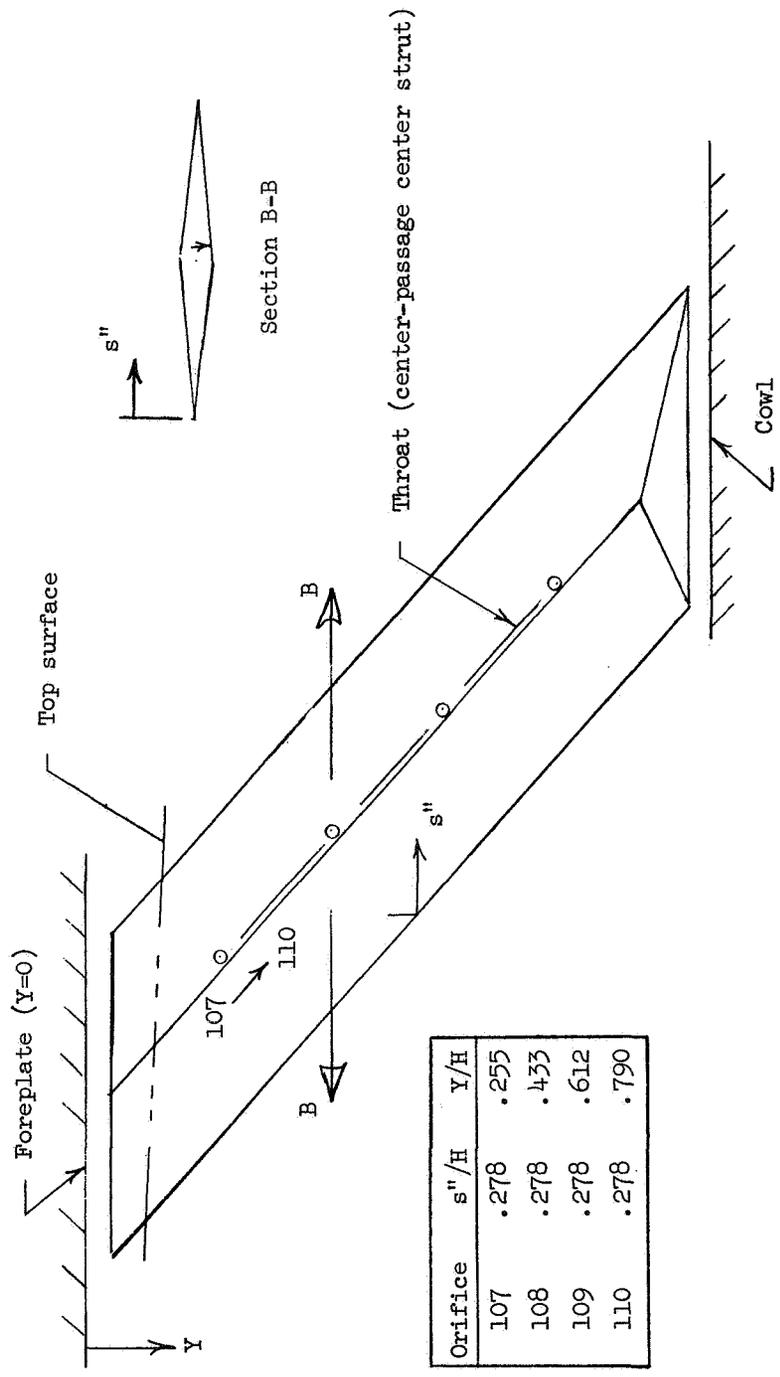
Orifice	$c'/H$	$Z/H$
71	.087	.163
72	.220	.157
73	.353	.151
74	.420	.149
Orifice	$c/H$	$Z/H$
75	1.080	-.053
76	1.080	0
77	1.080	.053
78	1.080	.107

(d) Cowl.

Figure 13.- Continued.

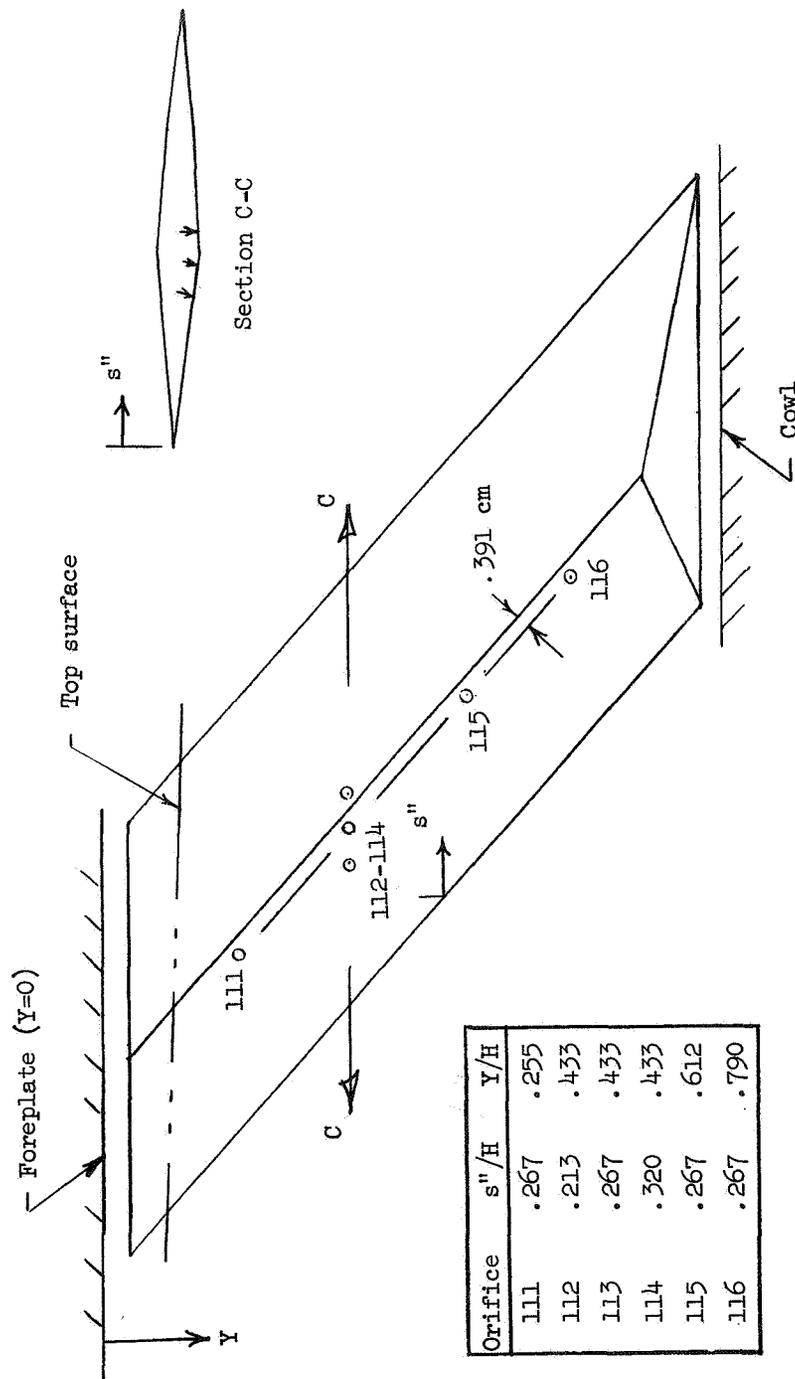


(e) Left side strut.  
Figure 13.- Continued.



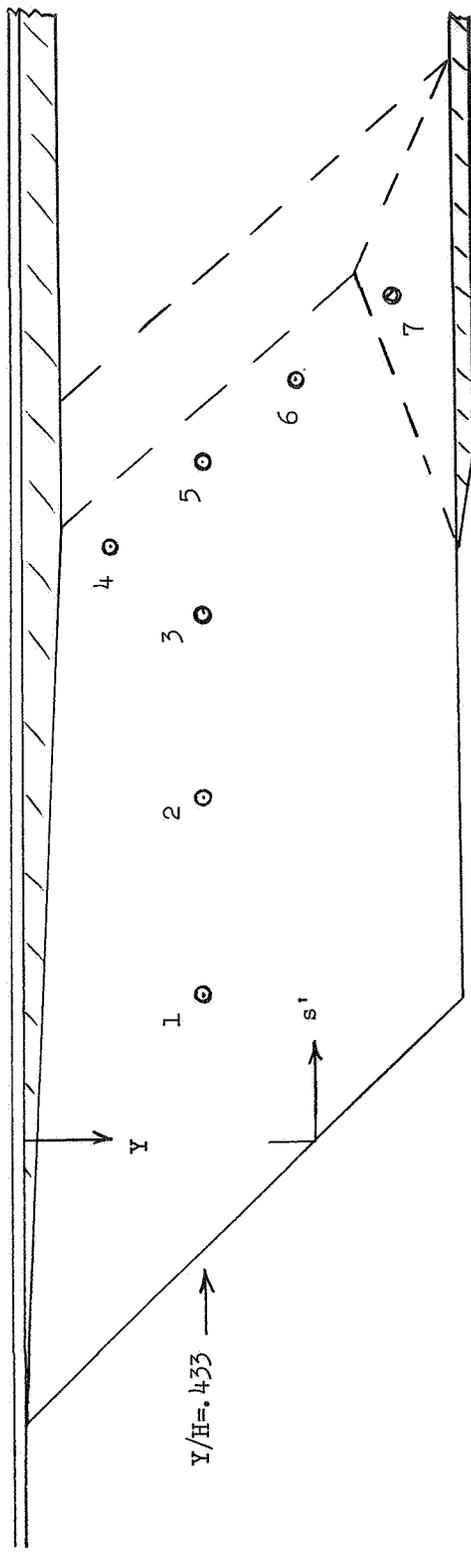
(f) Center strut.

Figure 13.- Continued.



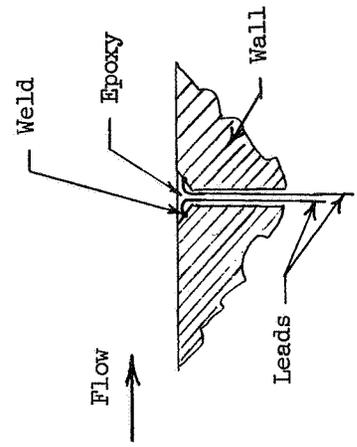
(g) Large center strut.

Figure 13.- Concluded.



Right sidewall

Thermocouple	$s'/H$	$Y/H$
1	.924	.433
2	1.591	.433
3	2.057	.433
4	2.457	.210
5	2.457	.433
6	2.457	.656
7	2.457	.880



Thermocouple installation

Figure 14.- Thermocouple locations.  $H = 19.05$  cm; 24-gage iron-constantan.

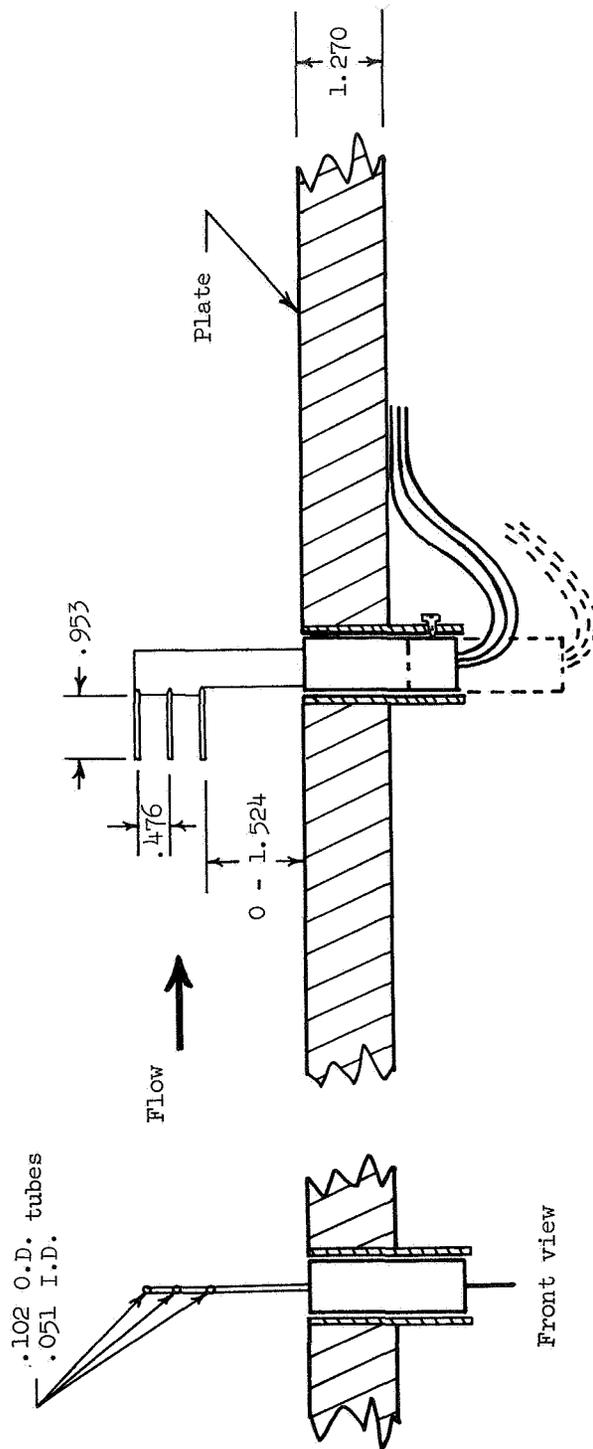


Figure 15.- Foreplate boundary-layer probe. All dimensions are in centimeters.

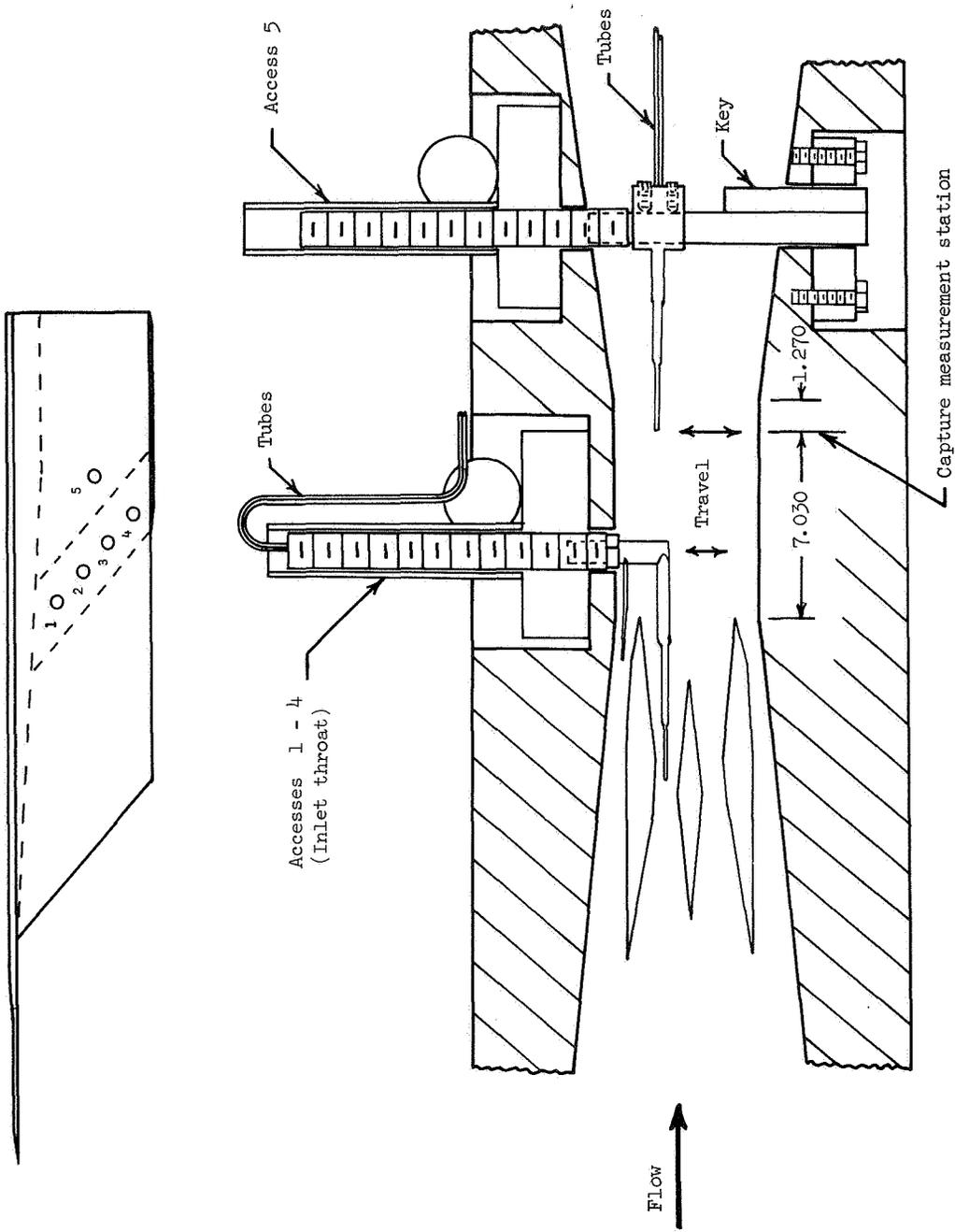
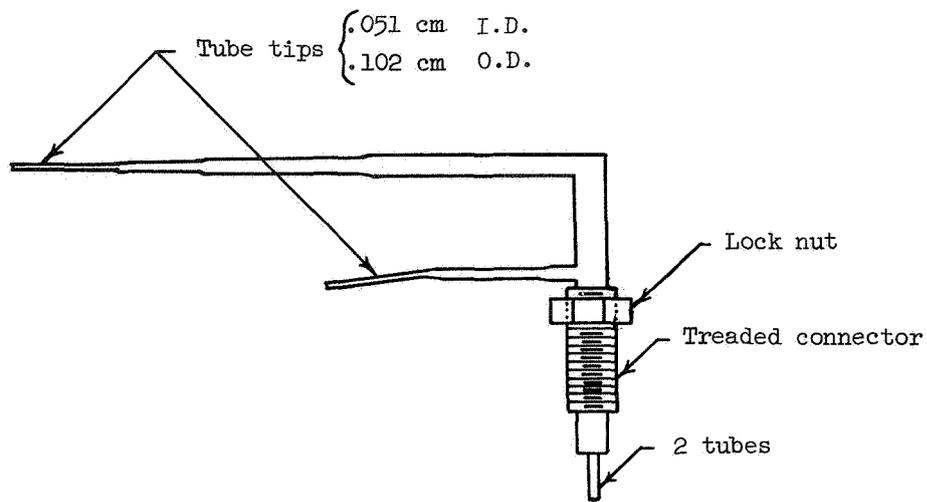
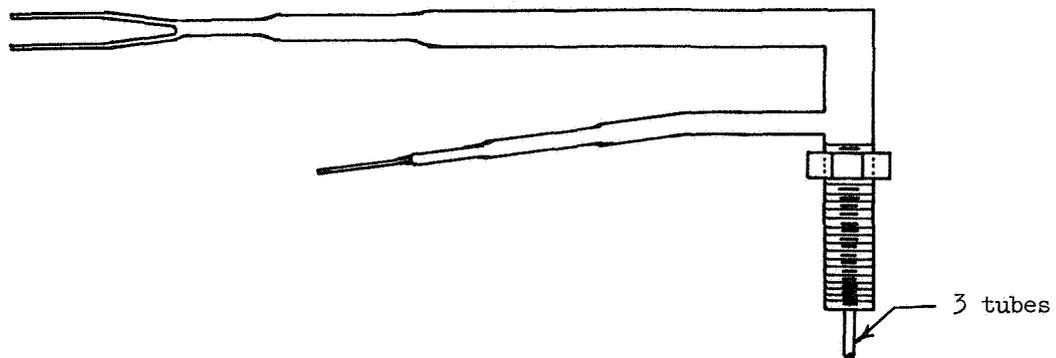


Figure 16.- Survey probe mechanism and access locations. All dimensions are in centimeters.

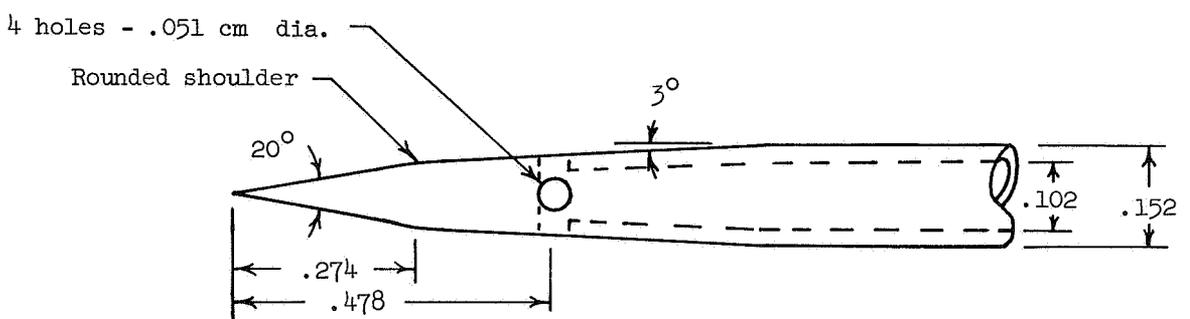
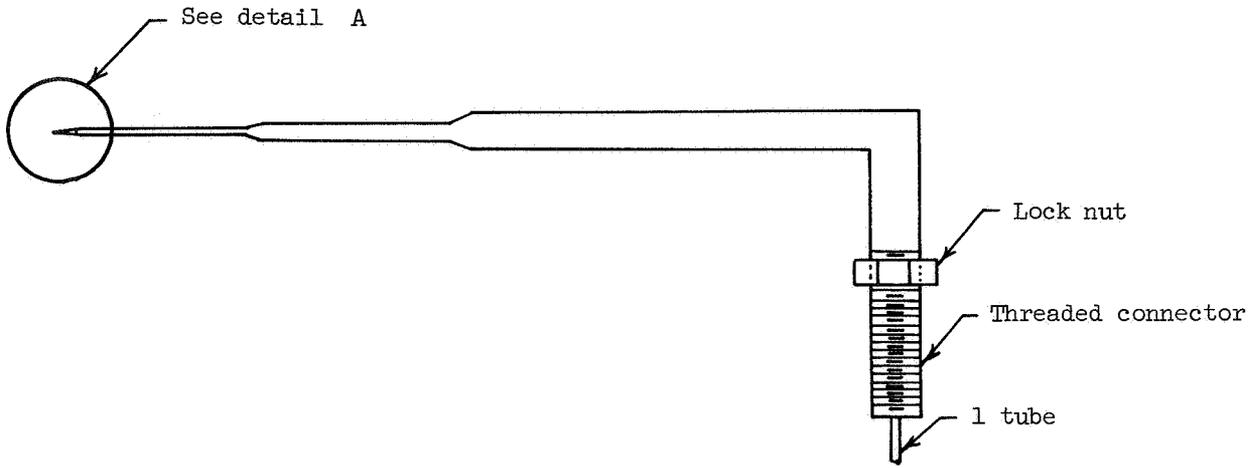


(a) Pitot probe 1. Tube tips bent to aline with inlet throats for each test, and onsite calibration performed.



(b) Pitot probe 2. This probe used with modified strut configuration which had wider gap in center passage.

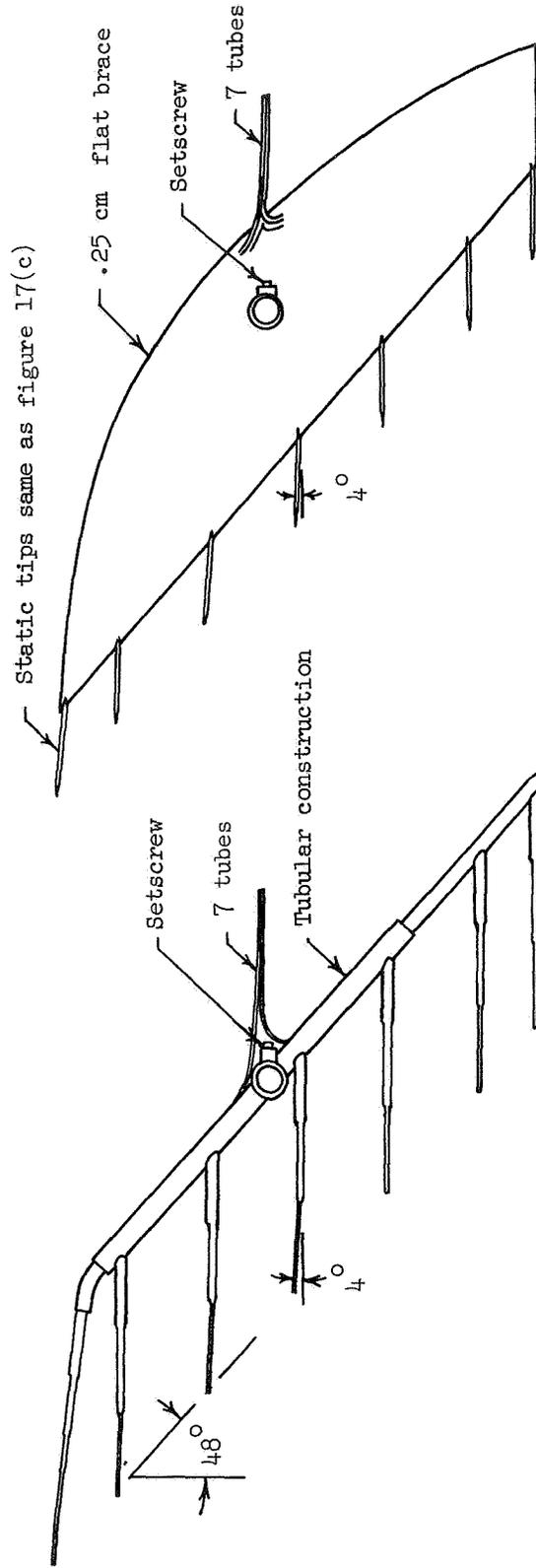
Figure 17.- Throat survey probes. All dimensions are in centimeters.



Detail A

(c) Static probe of reference 9.

Figure 17.- Concluded.



(a) Pitot probe. (b) Static probes.

Figure 18.- Capture measurement survey probes.

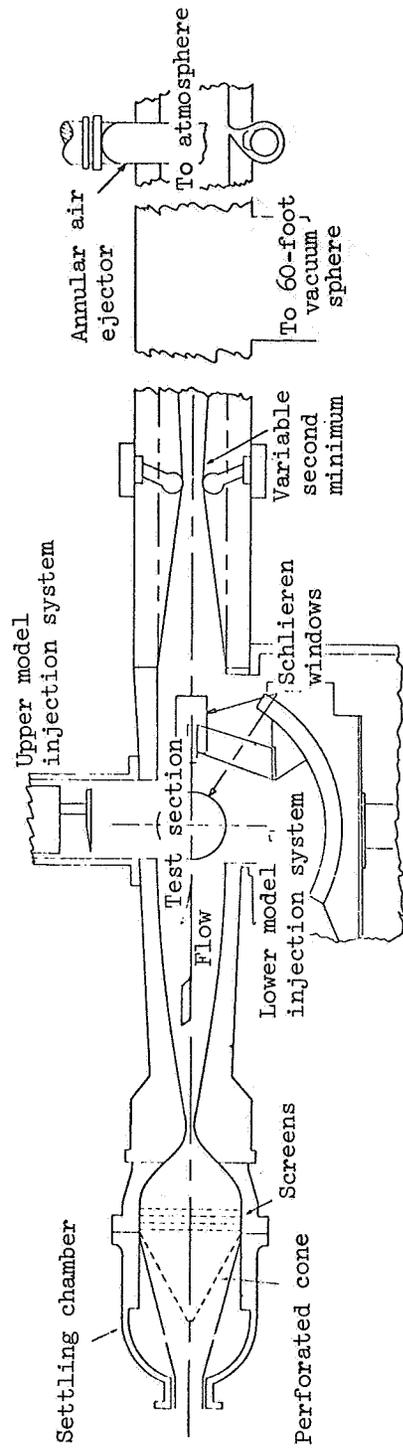
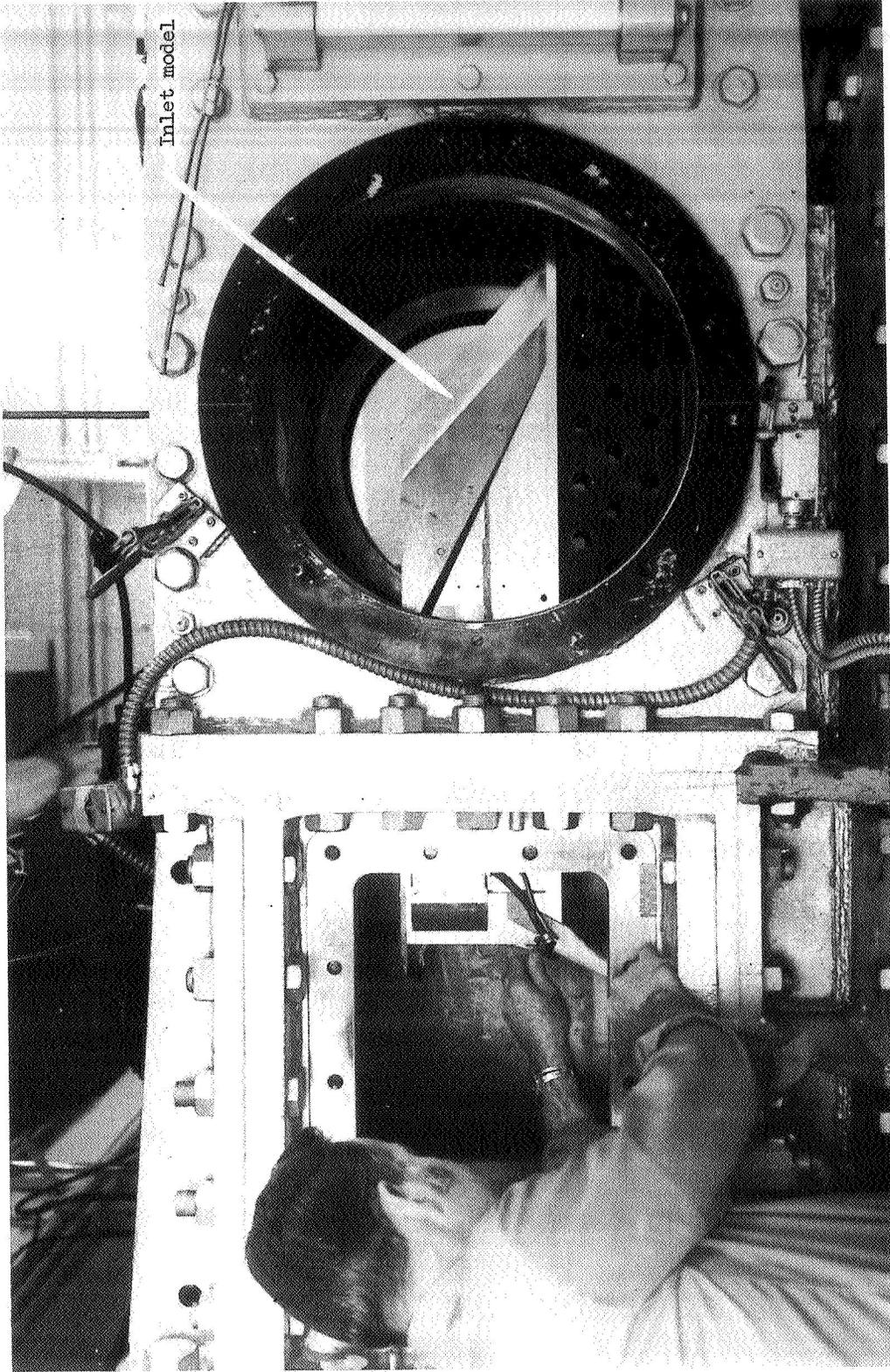
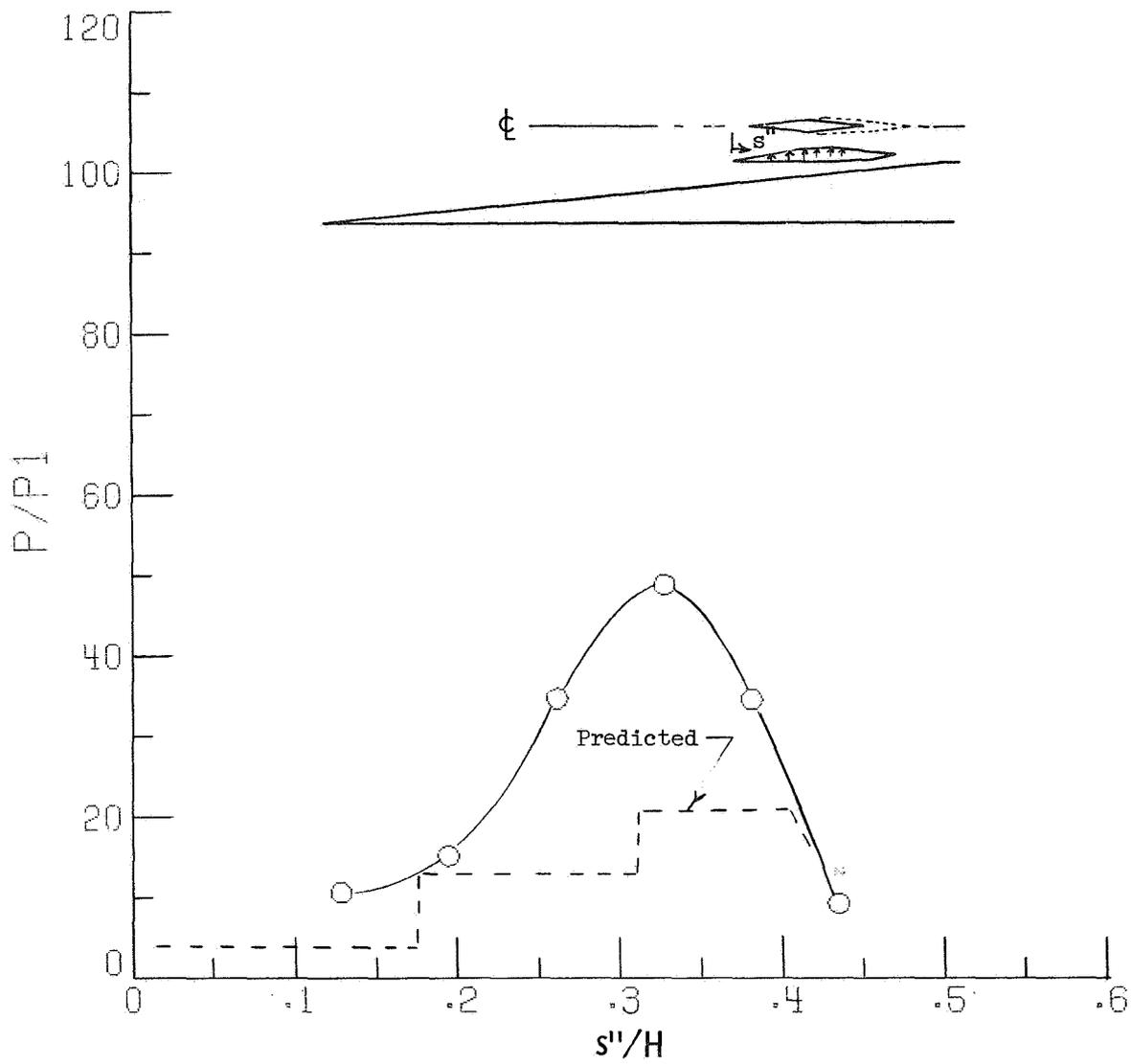


Figure 19.- Langley 20-inch Mach 6 test facility. (See ref. 12.)



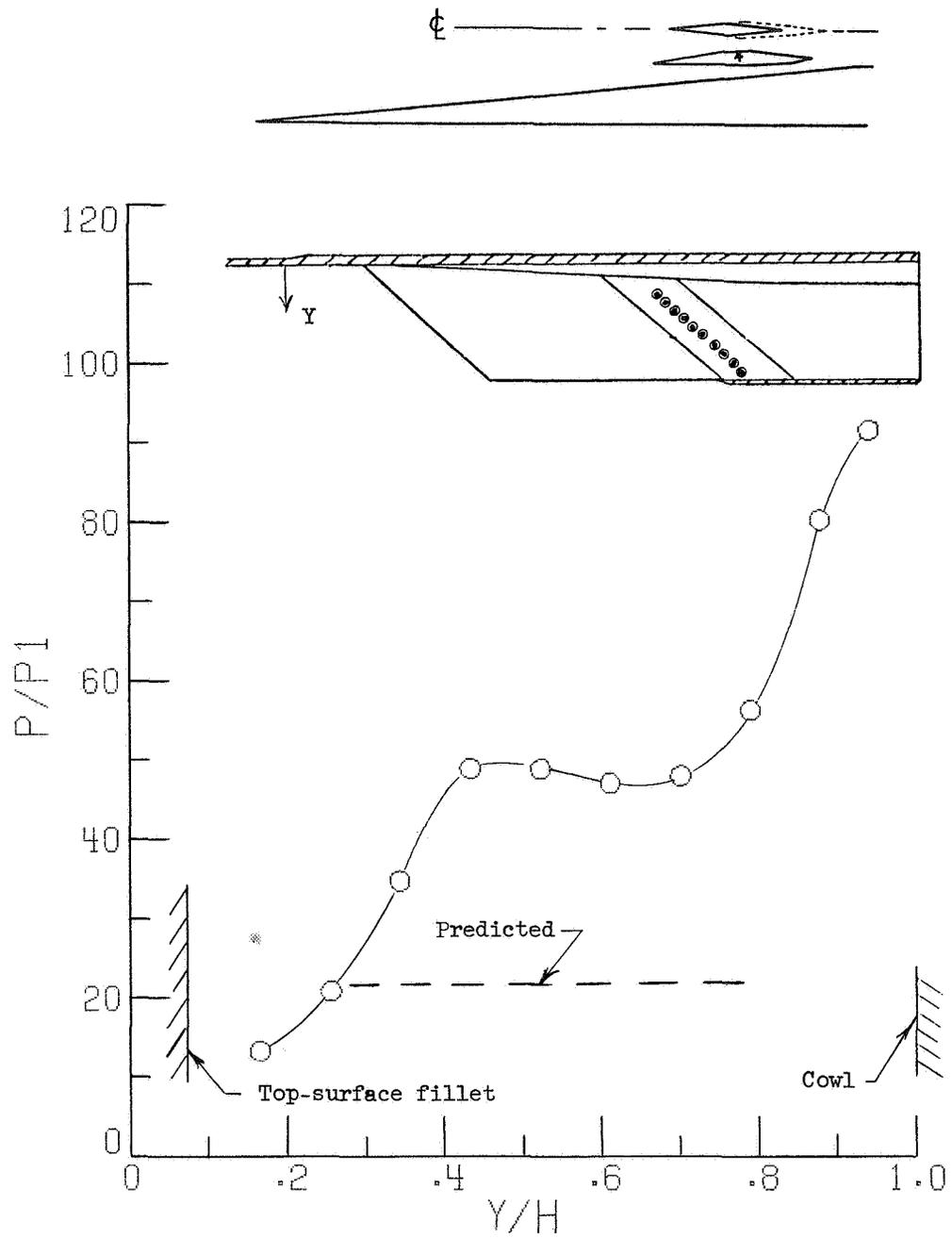
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Figure 20. - Inlet model mounted in test facility.



(a) Side strut;  $Y/H = 0.43$ .

Figure 21.- Center-passage static-pressure distribution.



(b) Side strut; throat.

Figure 21.- Concluded.

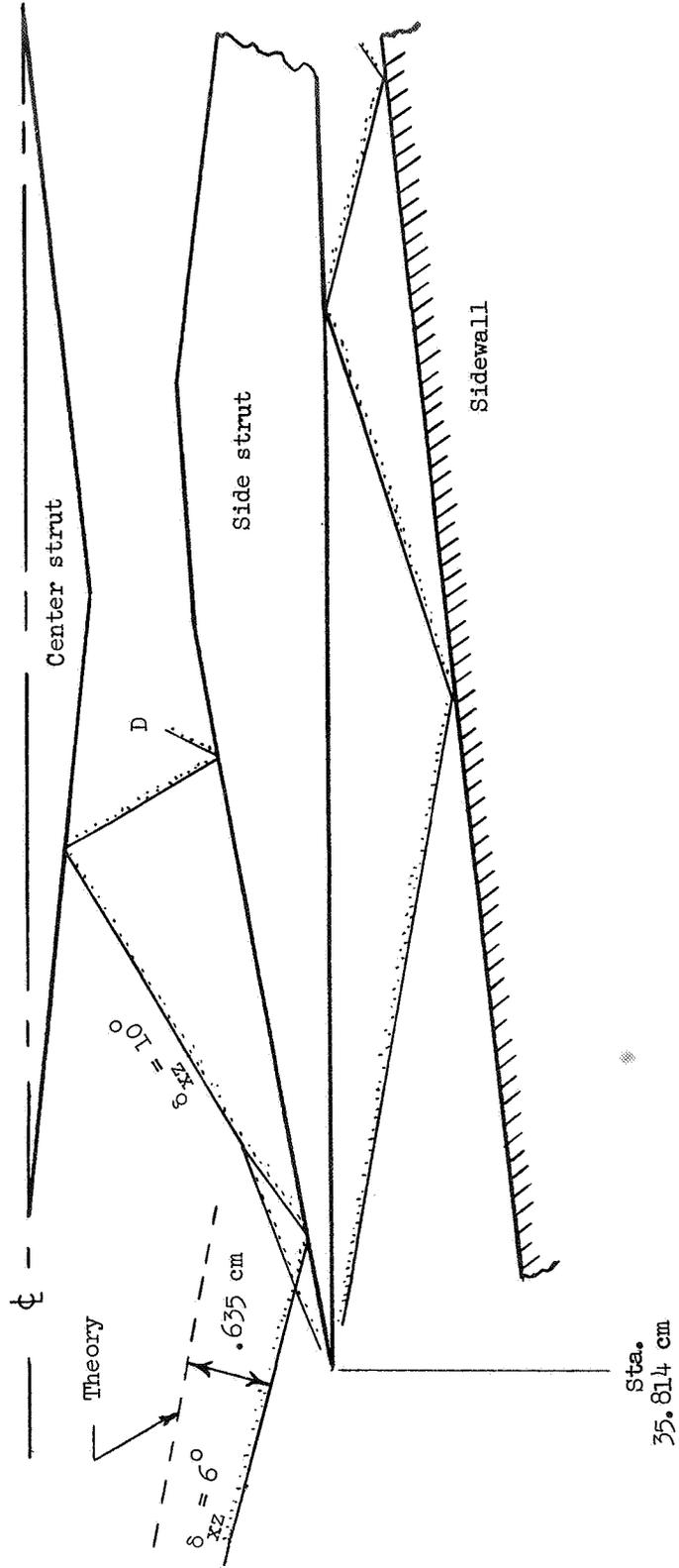


Figure 22.- Effect of shifted shock wave on center passage (xz-plane).

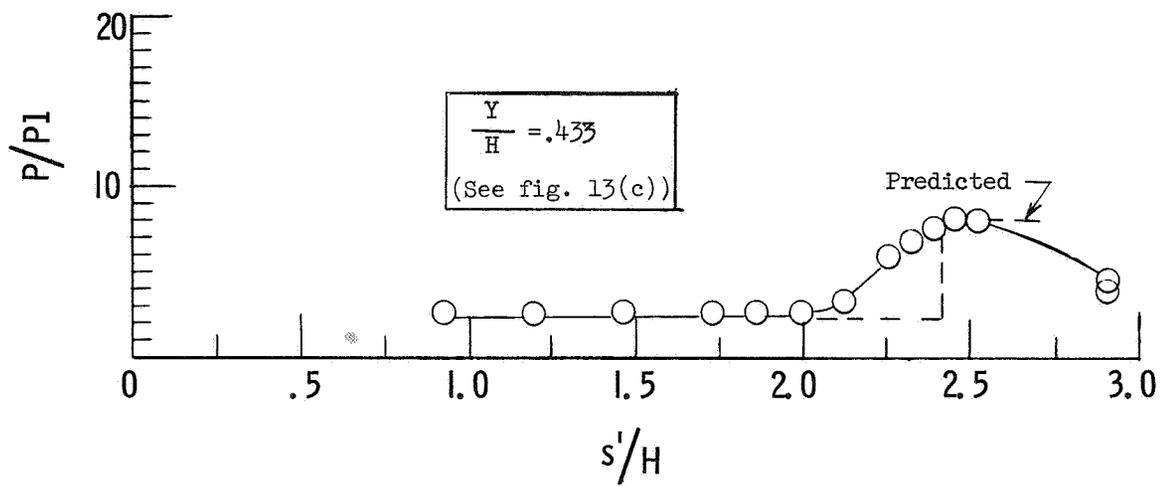
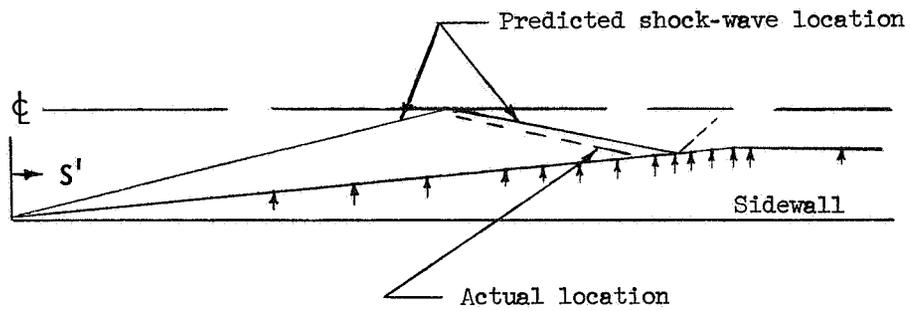
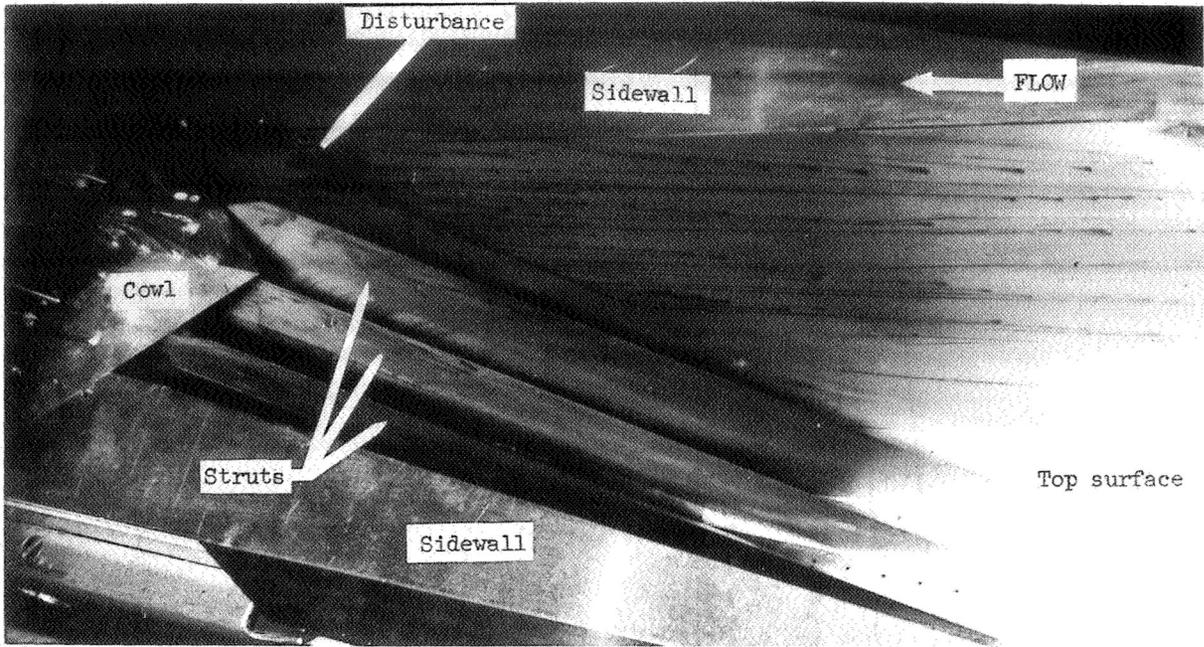
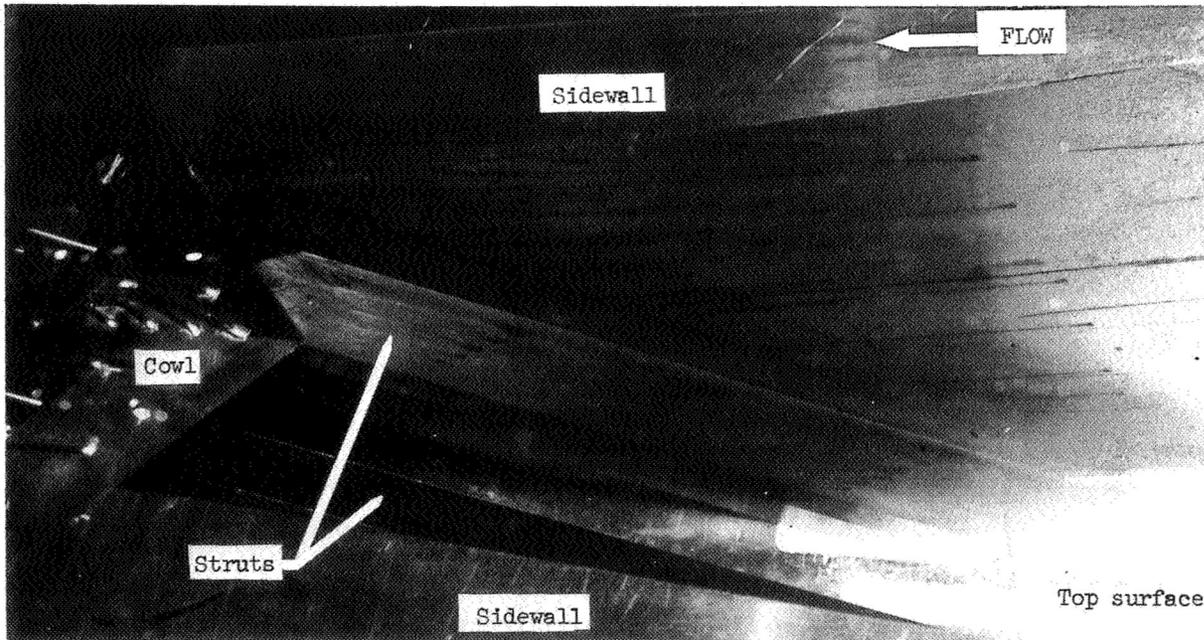


Figure 23.- Sidewall static-pressure distribution. No struts.



(a) Three-strut configuration (Capture = 81 percent).



(b) No center strut (Capture = 92 percent).

Figure 24.- Oil-streak photograph.

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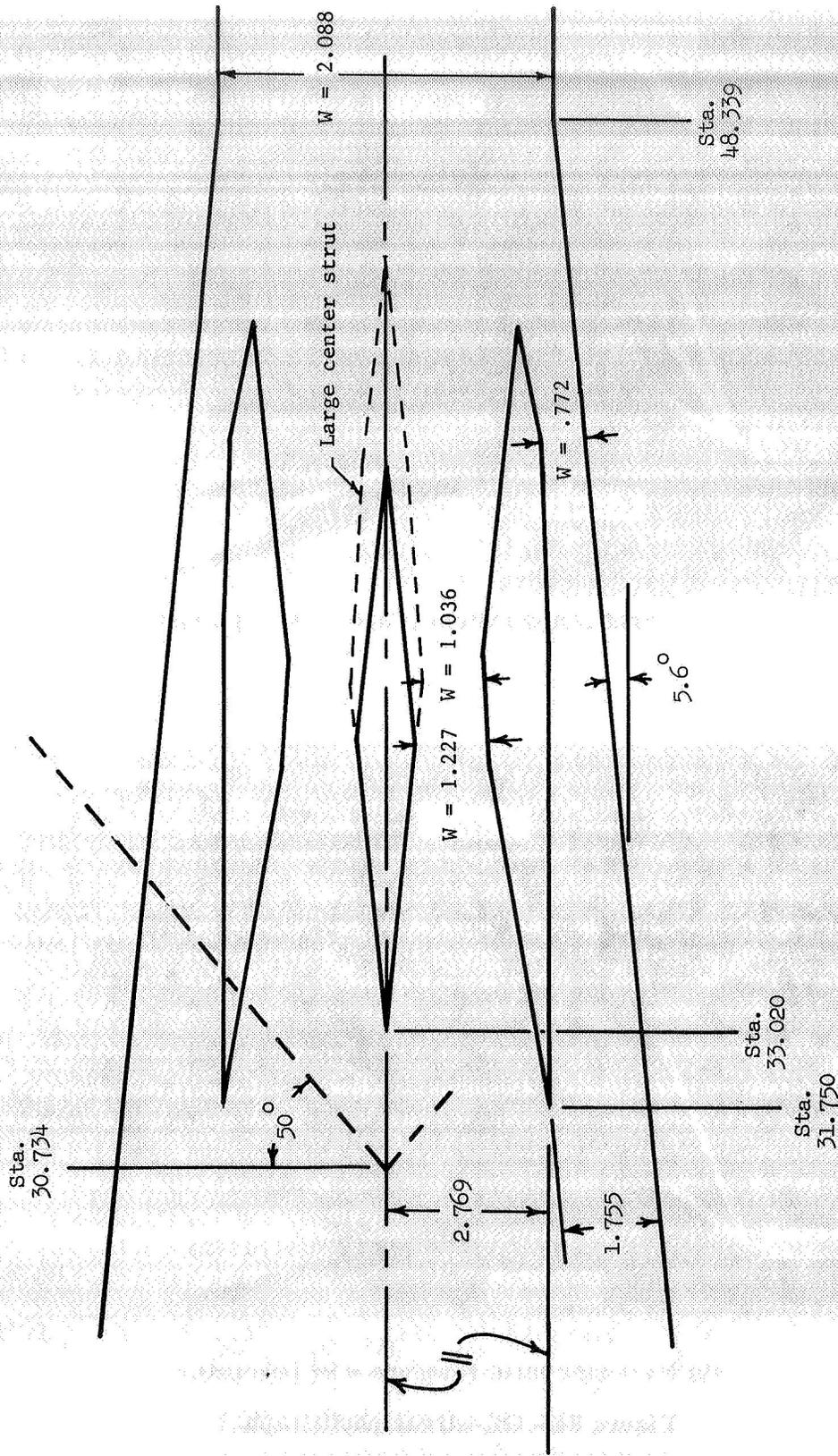


Figure 25.- Modified strut positions (xz-plane). All dimensions are in centimeters.

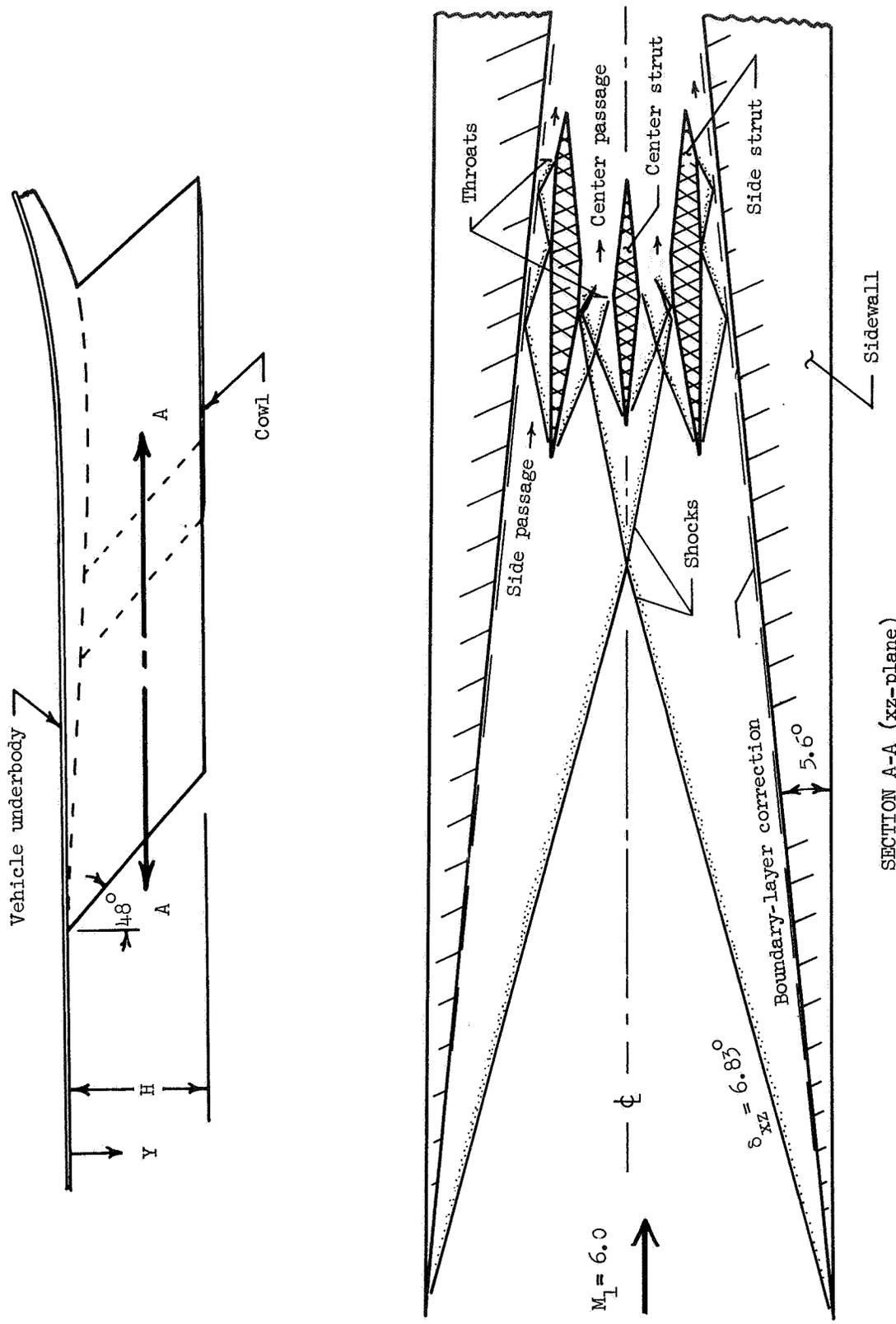


Figure 26. - Corrected Mach 6 shock diagram.

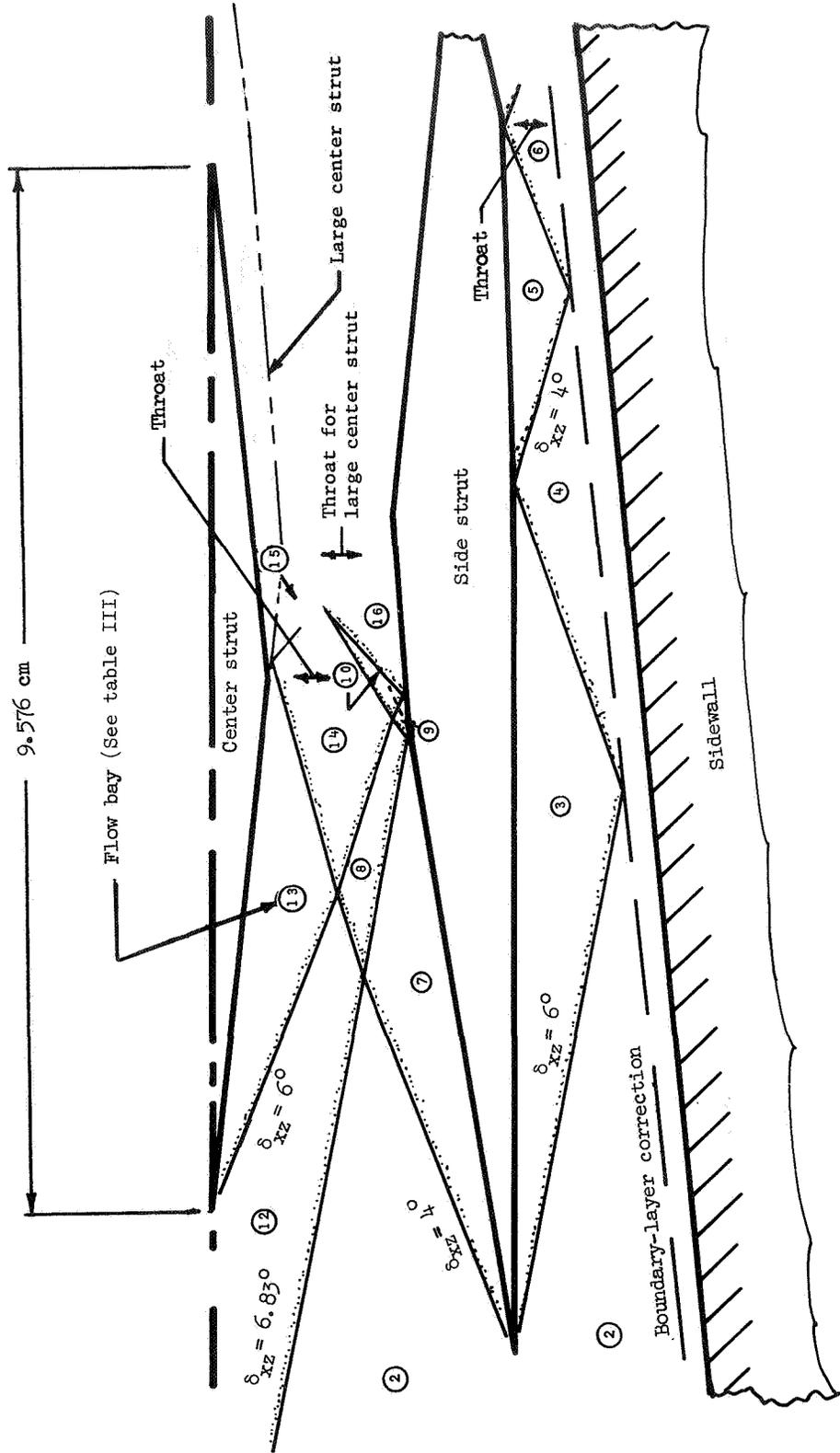
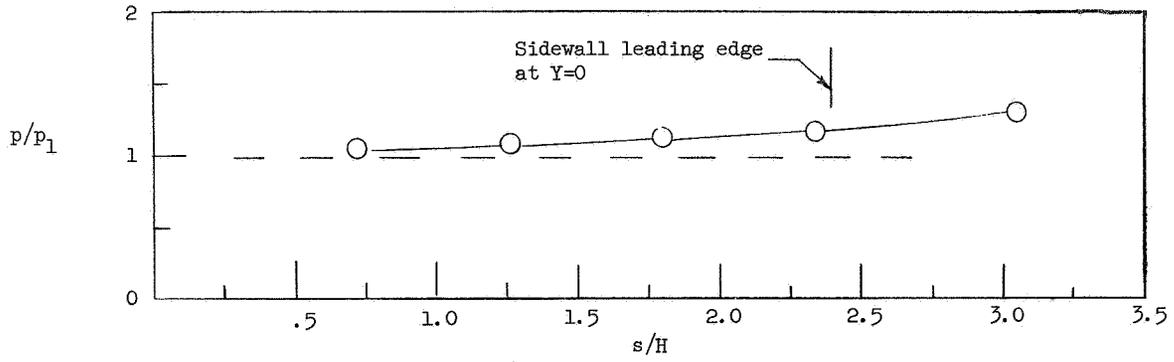
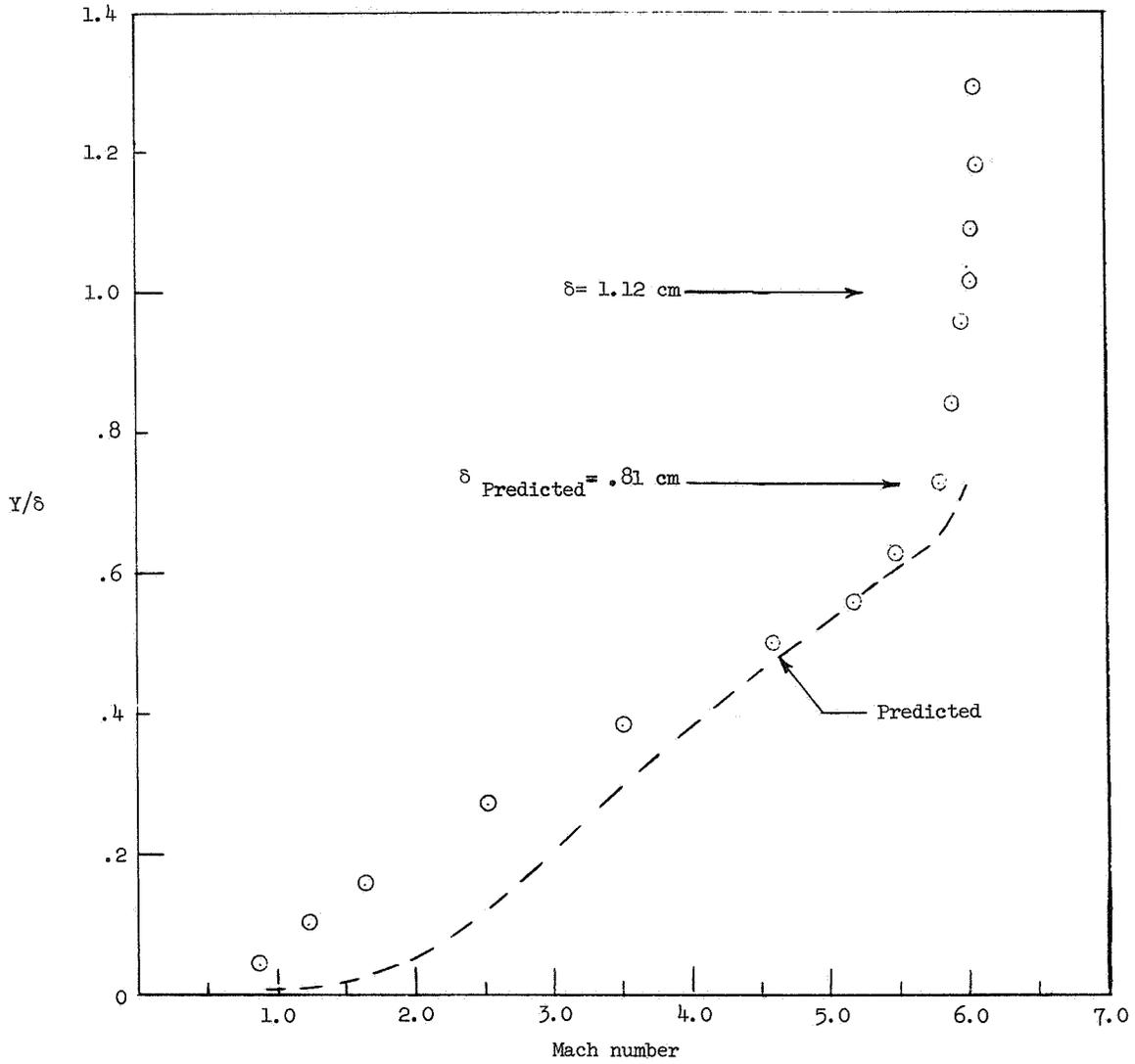


Figure 27.- Corrected shock-wave detail in vicinity of struts.  $M_1 = 6.0$ .



(a) Static pressure on foreplate.  $Z/H = 0$ .



(b) Foreplate boundary layer.  $s/H = 6.096$ ;  $Z/H = 0.133$ .

Figure 28.- Foreplate conditions.

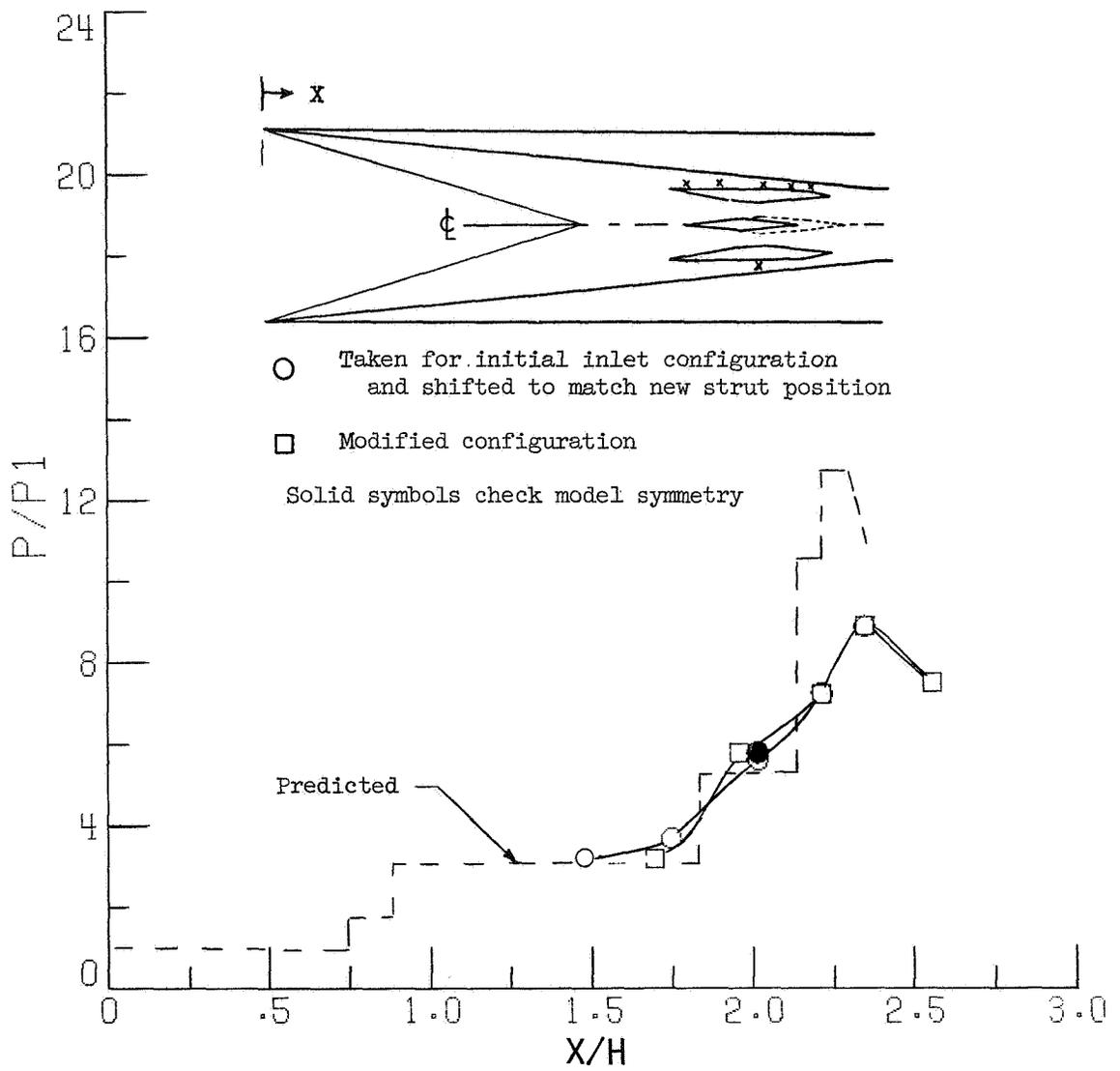


Figure 29.- Static-pressure distribution. Top surface (side passage).

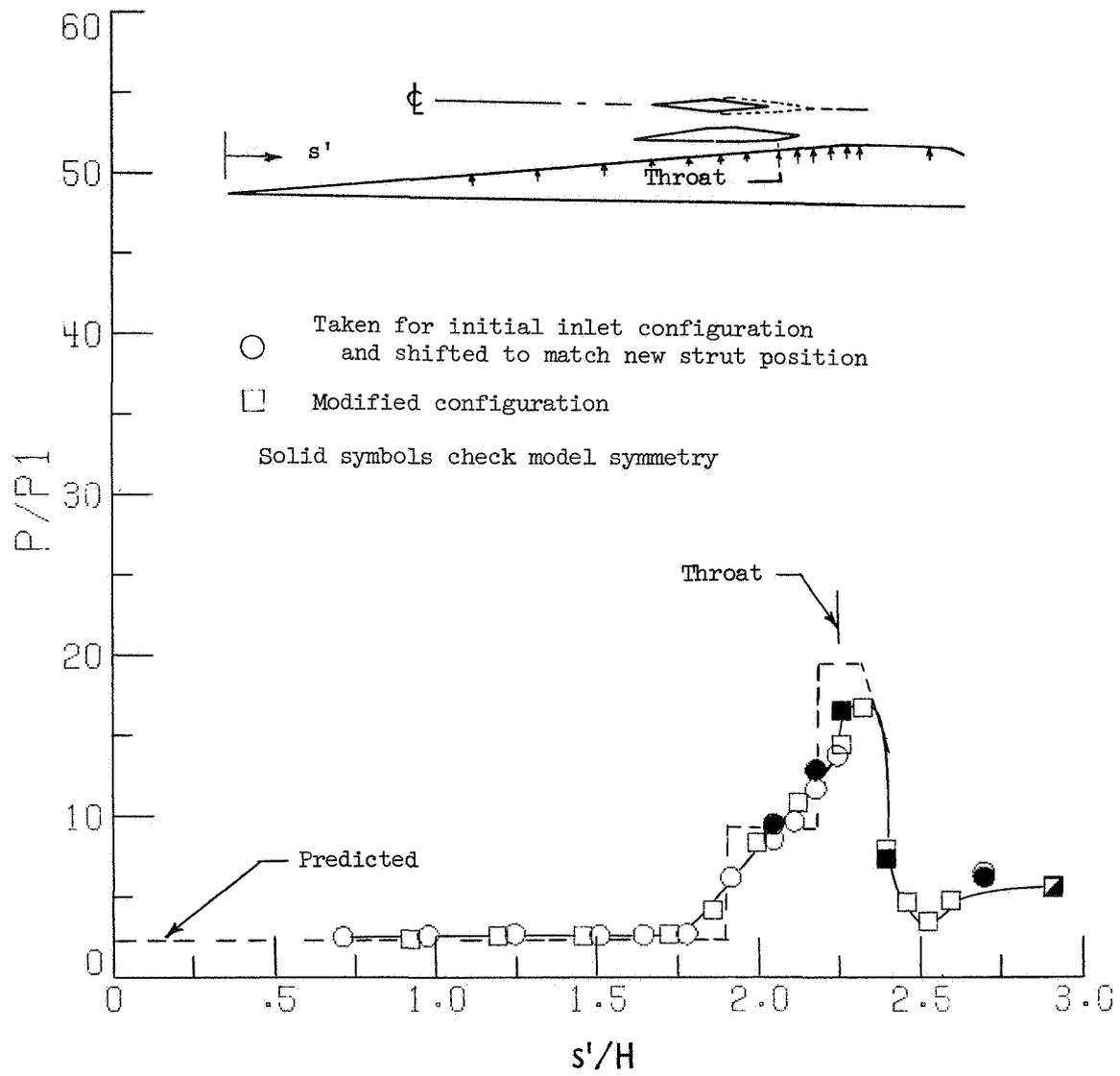


Figure 30.- Static-pressure distribution. Sidewall;  $Y/H = 0.43$ .

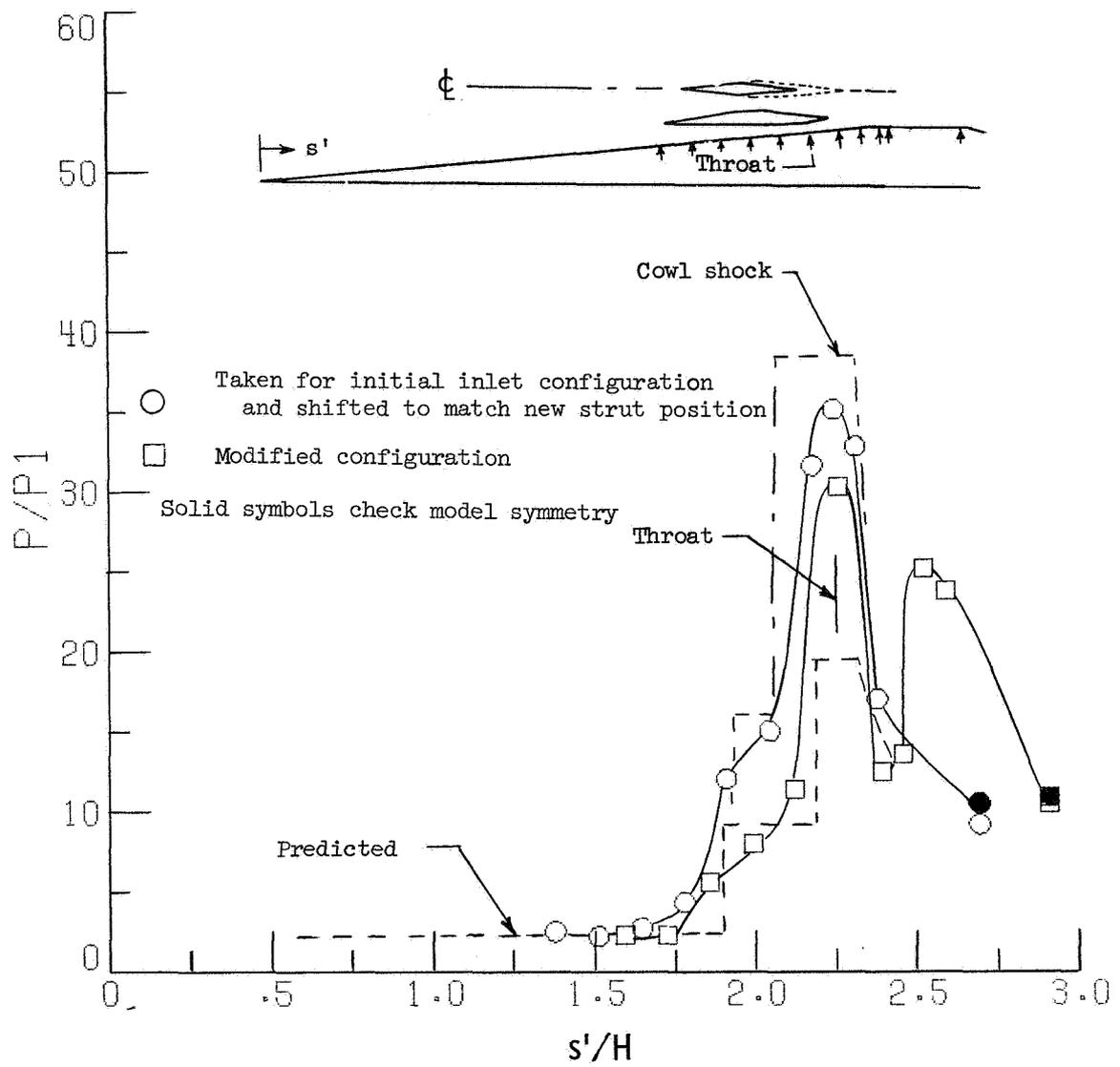


Figure 31.- Static-pressure distribution. Sidewall;  $Y/H = 0.88$ .

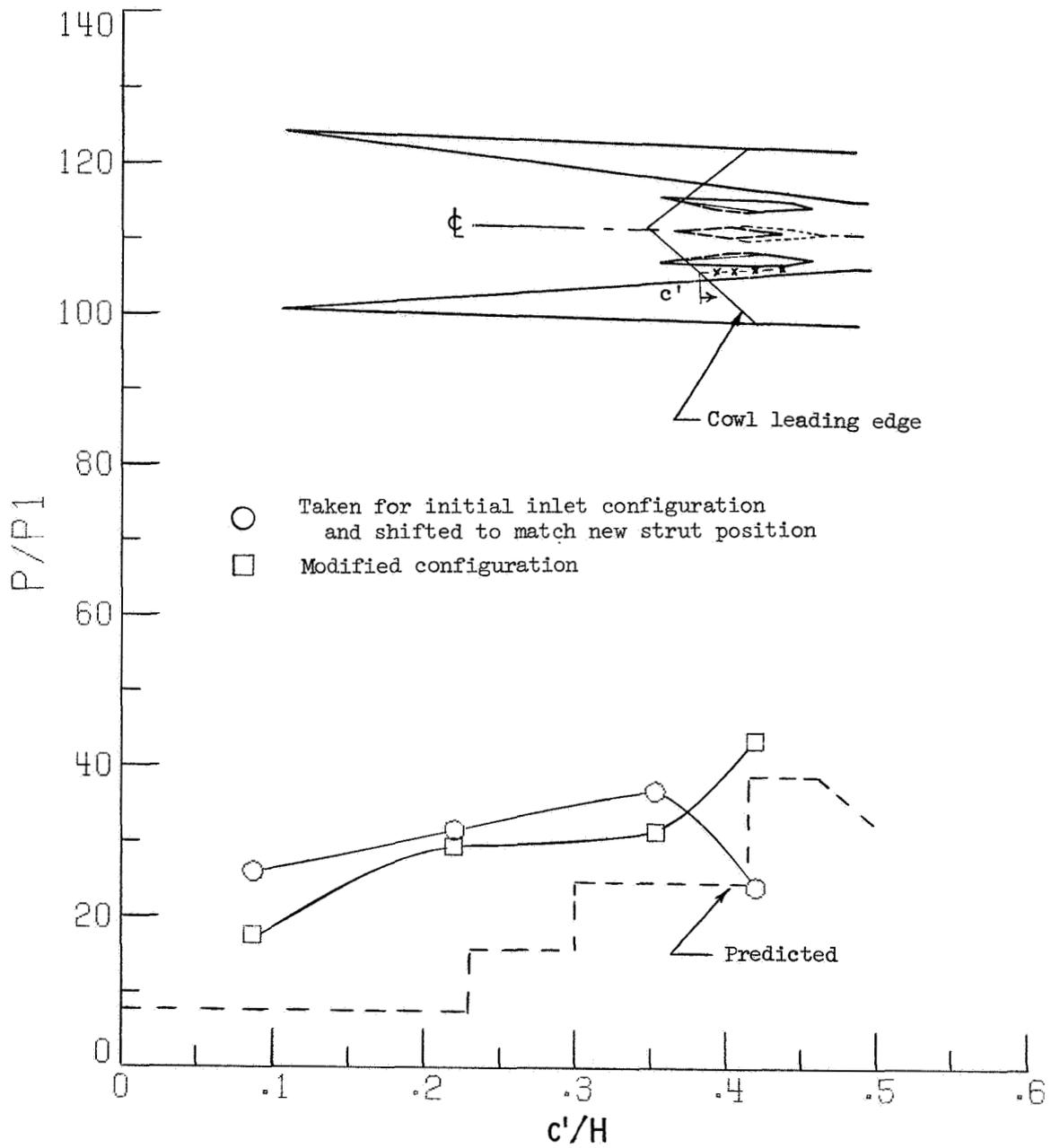
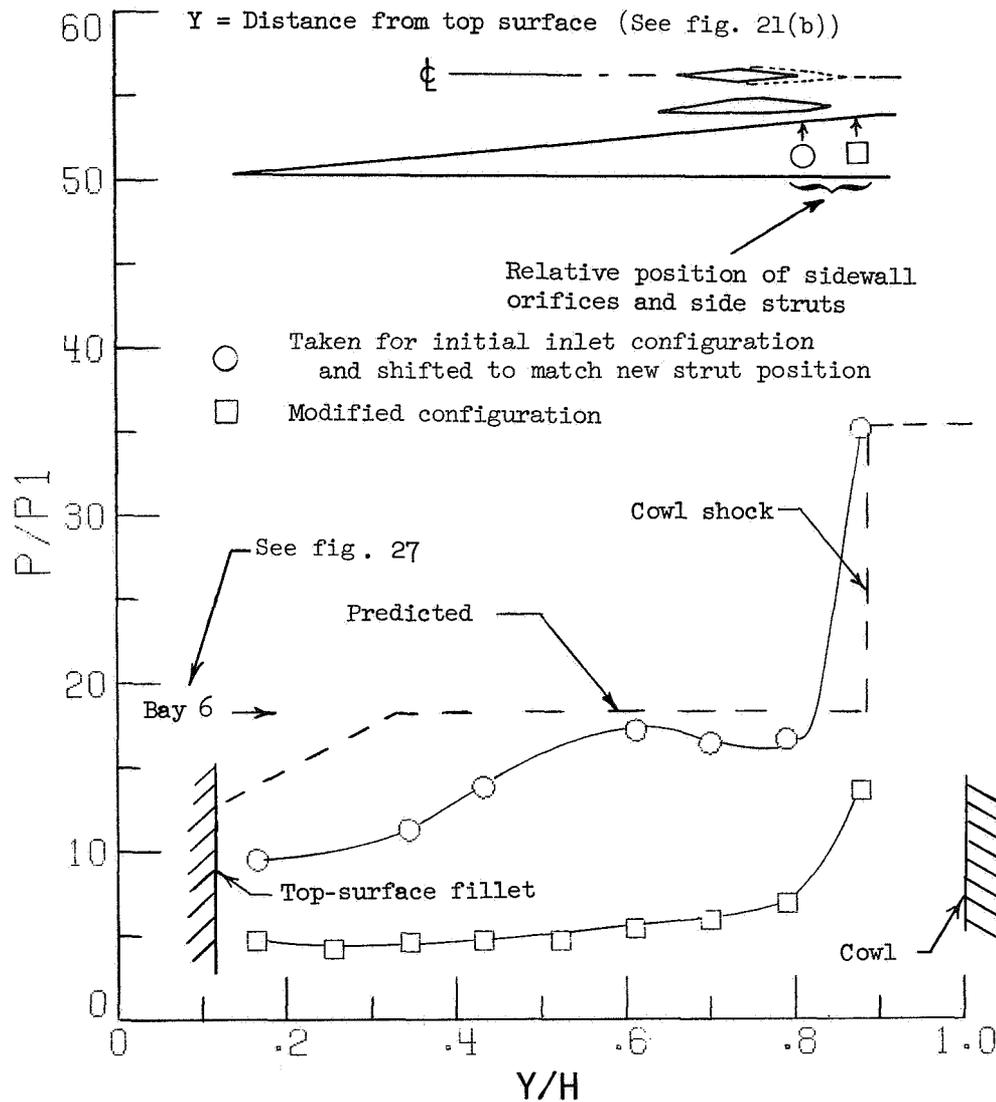
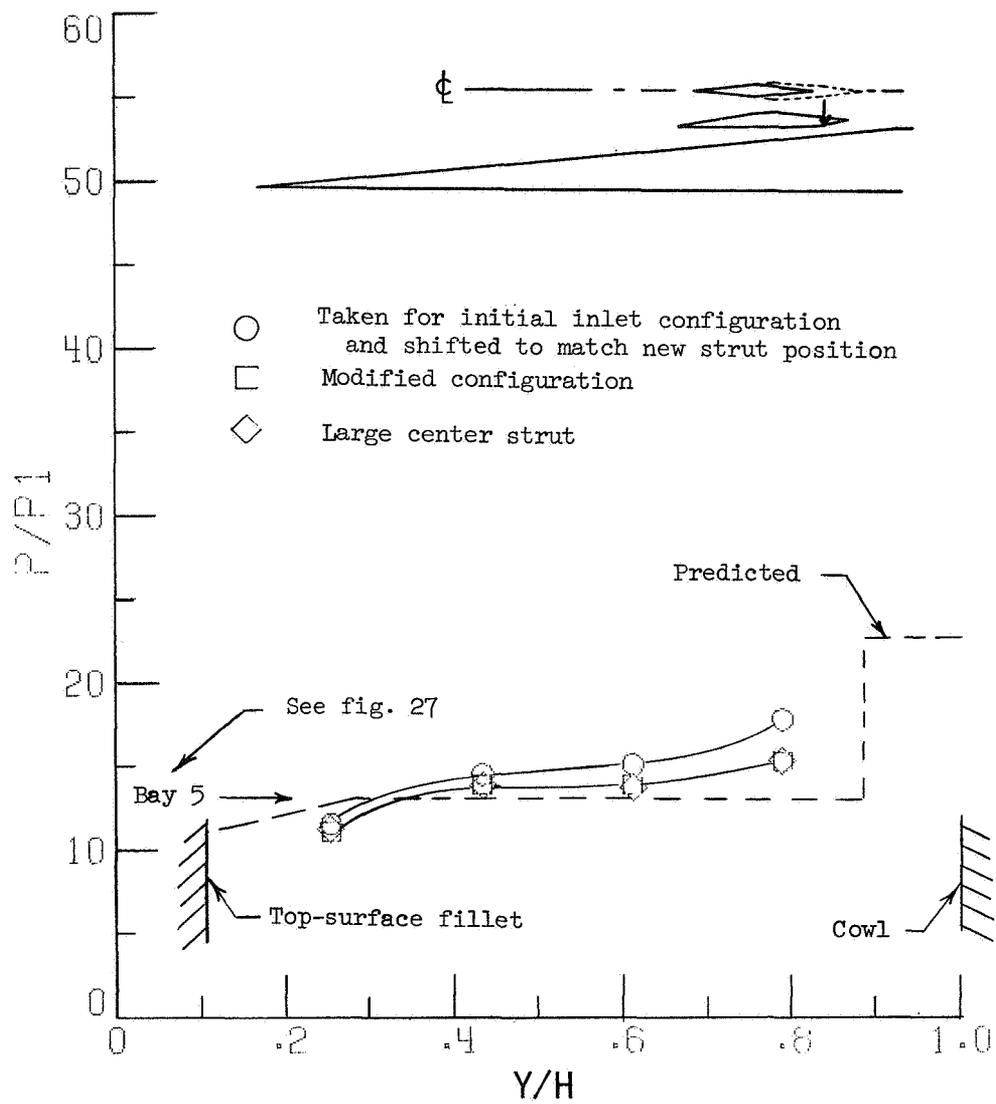


Figure 32. - Static-pressure distribution cowl. Side passage.



(a) Sidewall.

Figure 33.- Static-pressure distribution. Side passage throat.



(b) Side strut.

Figure 33.- Concluded.

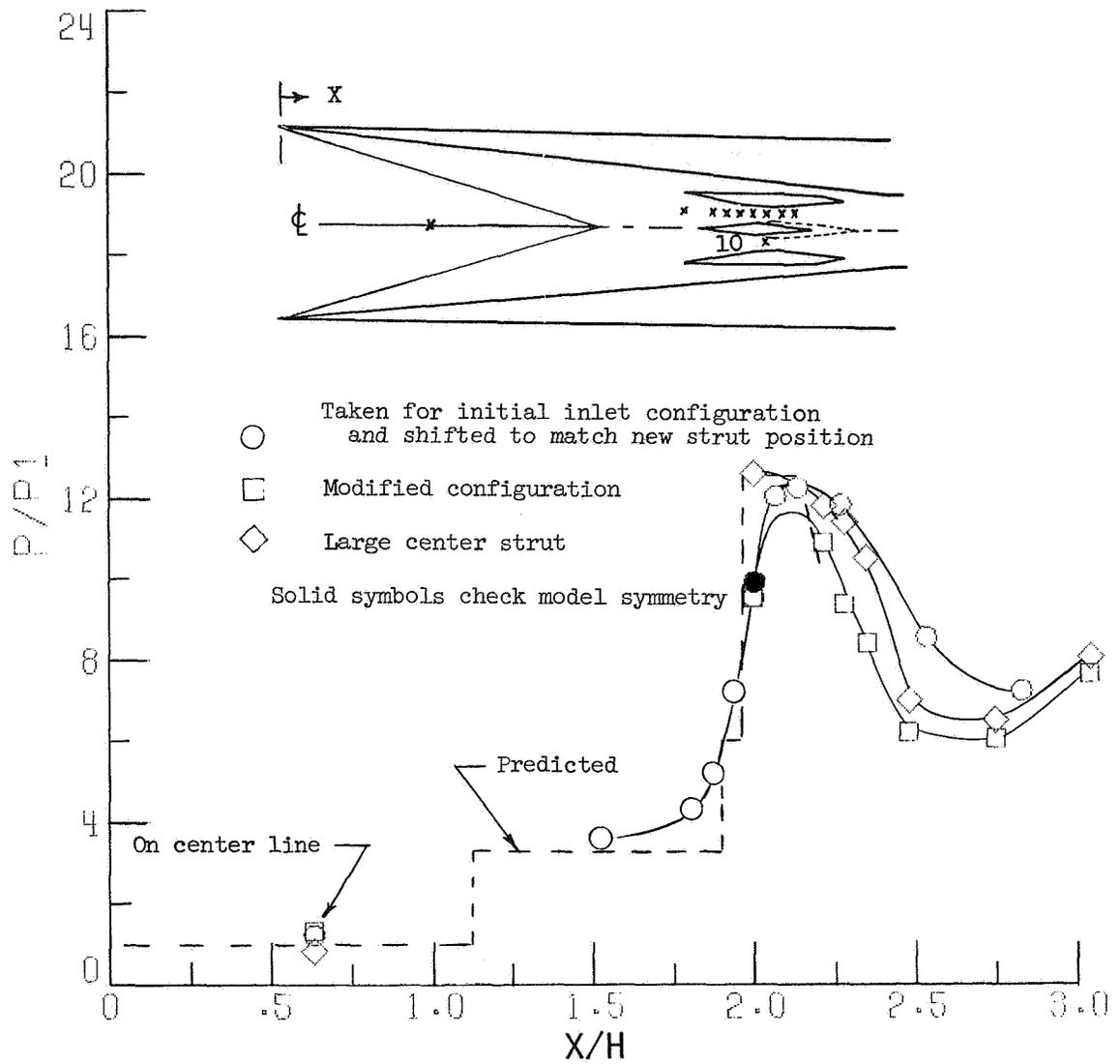


Figure 34.- Static-pressure distribution top surface. Center passage.

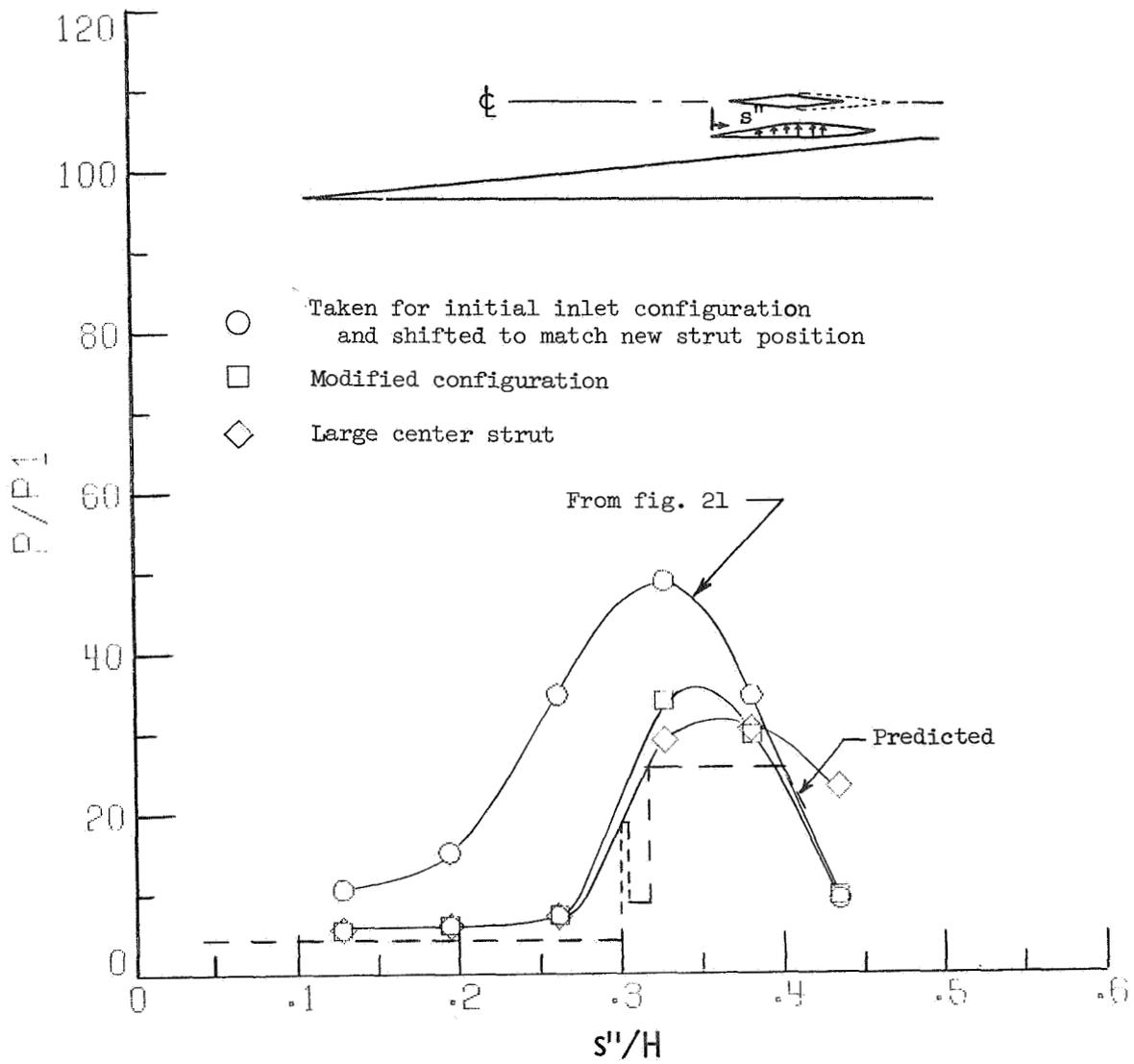


Figure 35.- Static-pressure distribution center passage. Side strut;  $Y/H = 0.43$ .

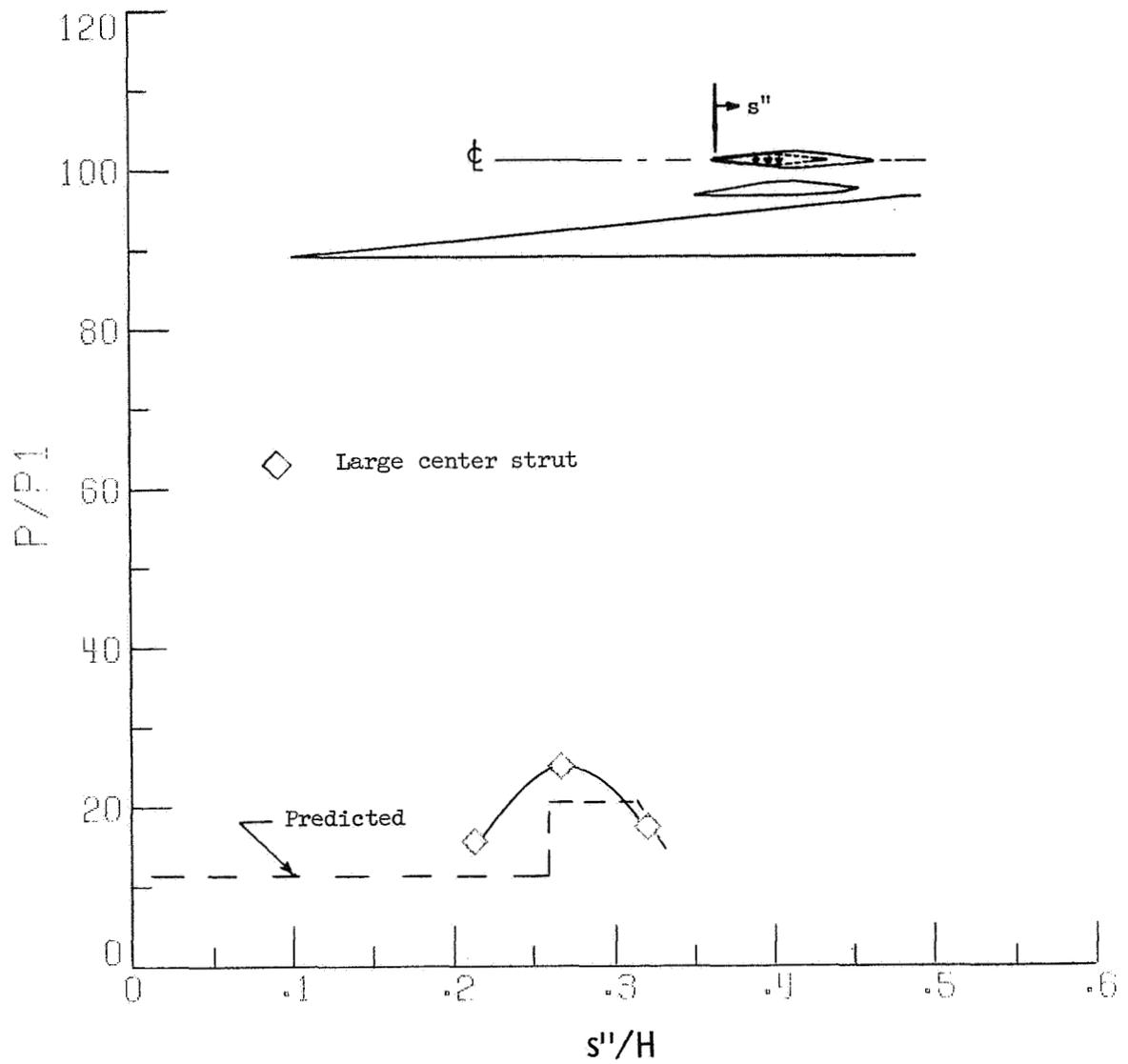


Figure 36.- Static-pressure distribution center passage. Center strut 2;  $Y/H = 0.43$ .

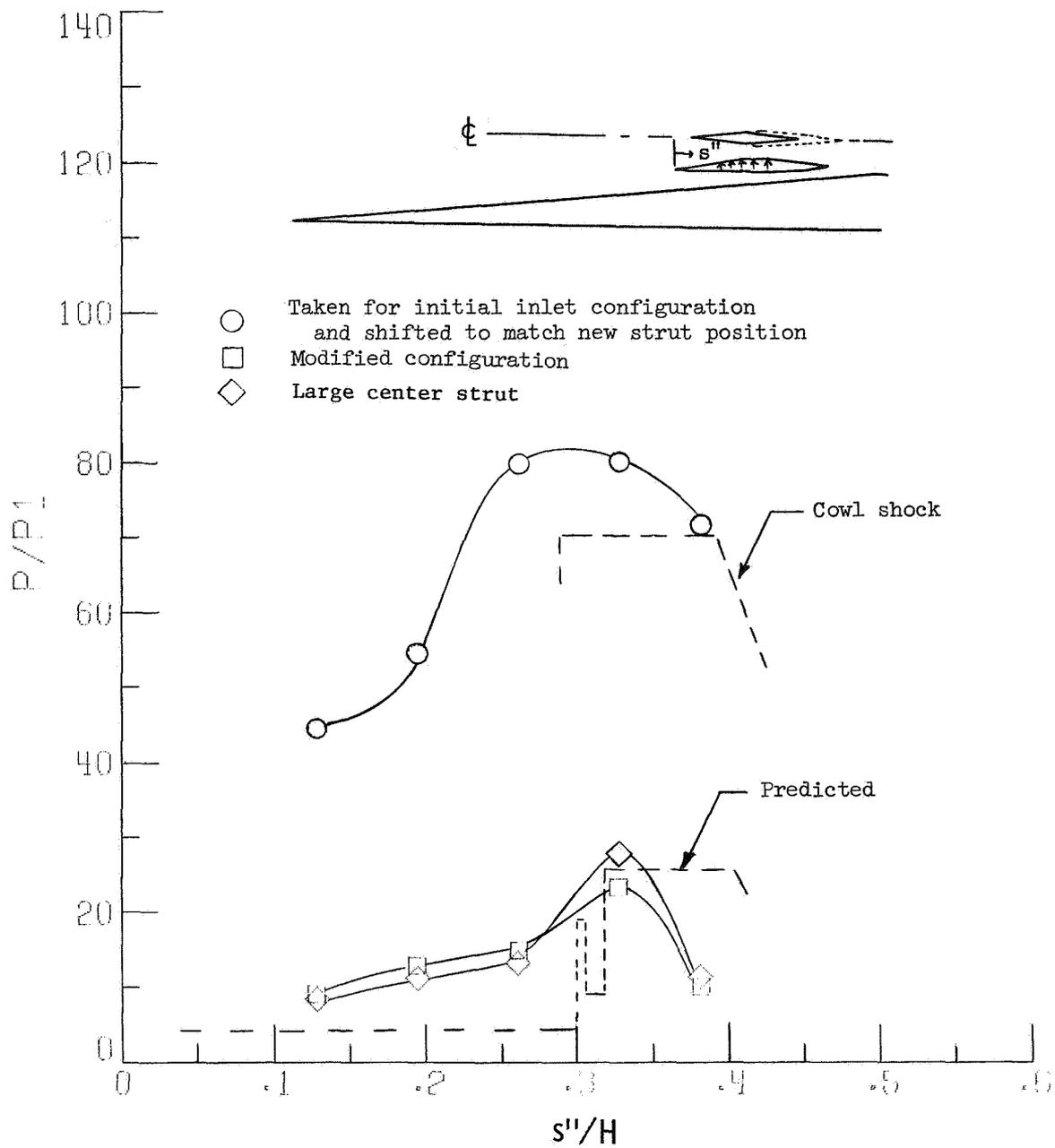


Figure 37.- Static-pressure distribution center passage. Side strut;  $Y/H = 0.88$ .

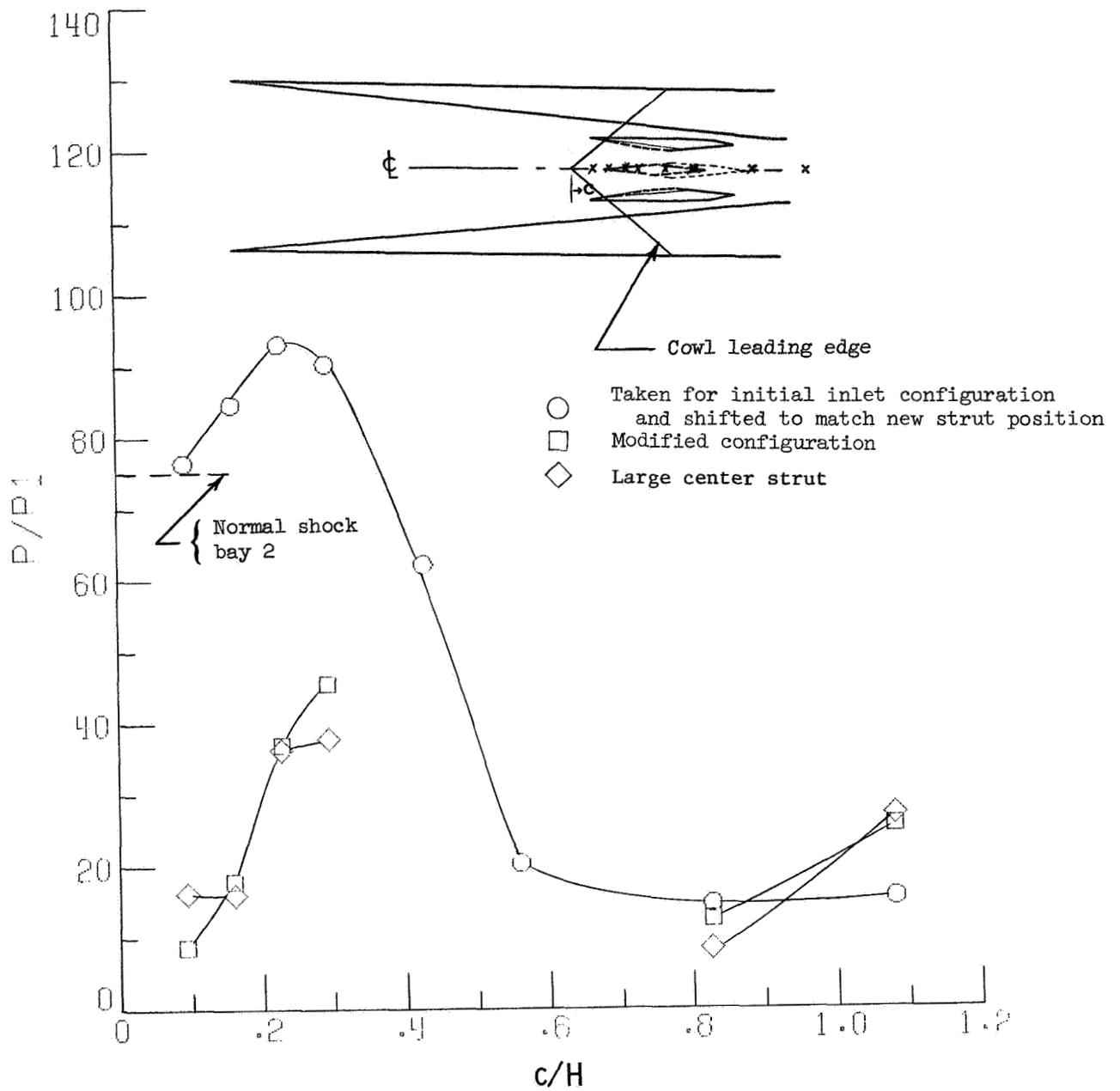
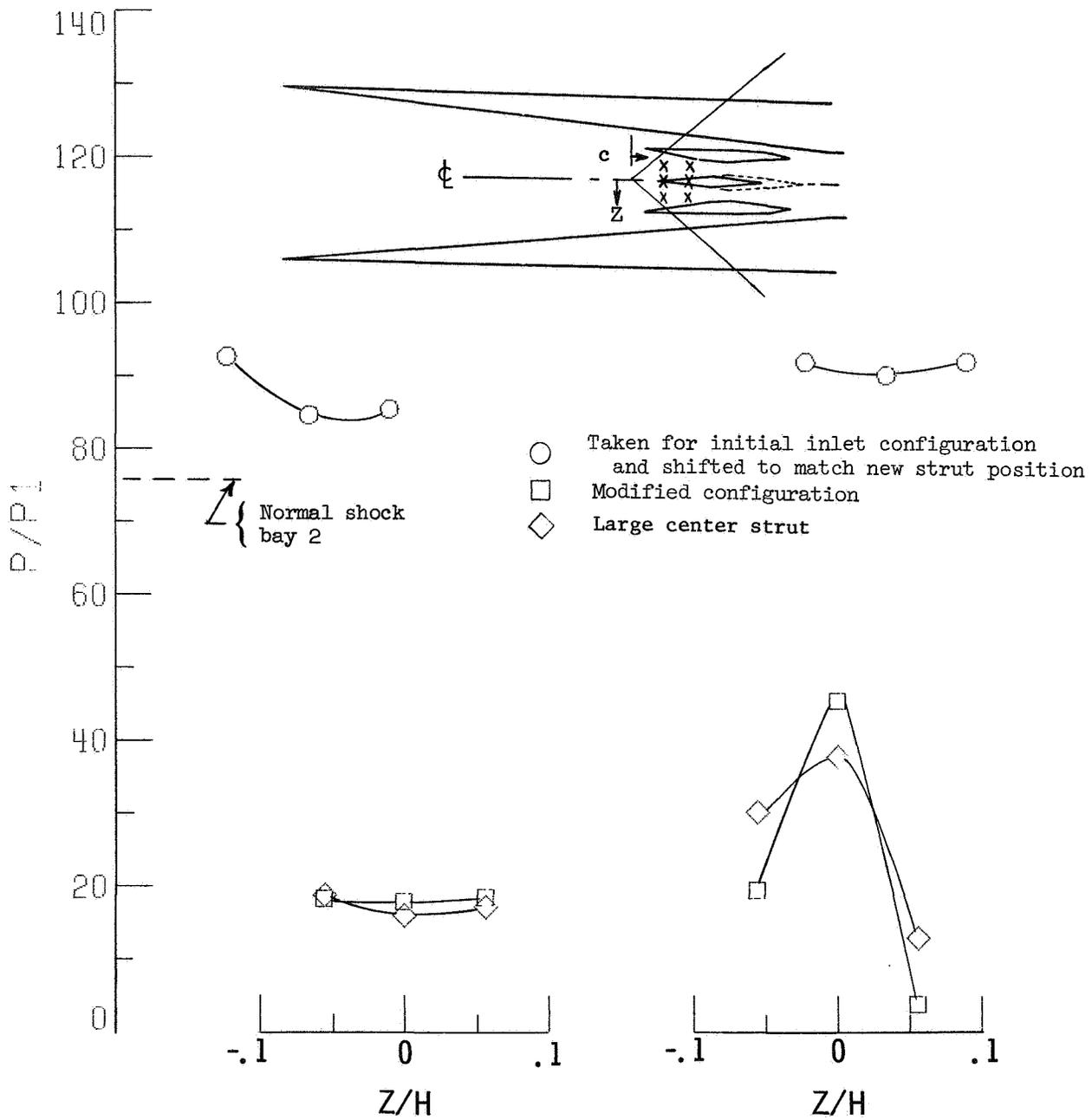


Figure 38.- Static-pressure distribution. Cowl (center line).



(a)  $c/H = 0.160$ .

(b)  $c/H = 0.293$ .

Figure 39.- Static-pressure distribution. Cowl (Z-direction).

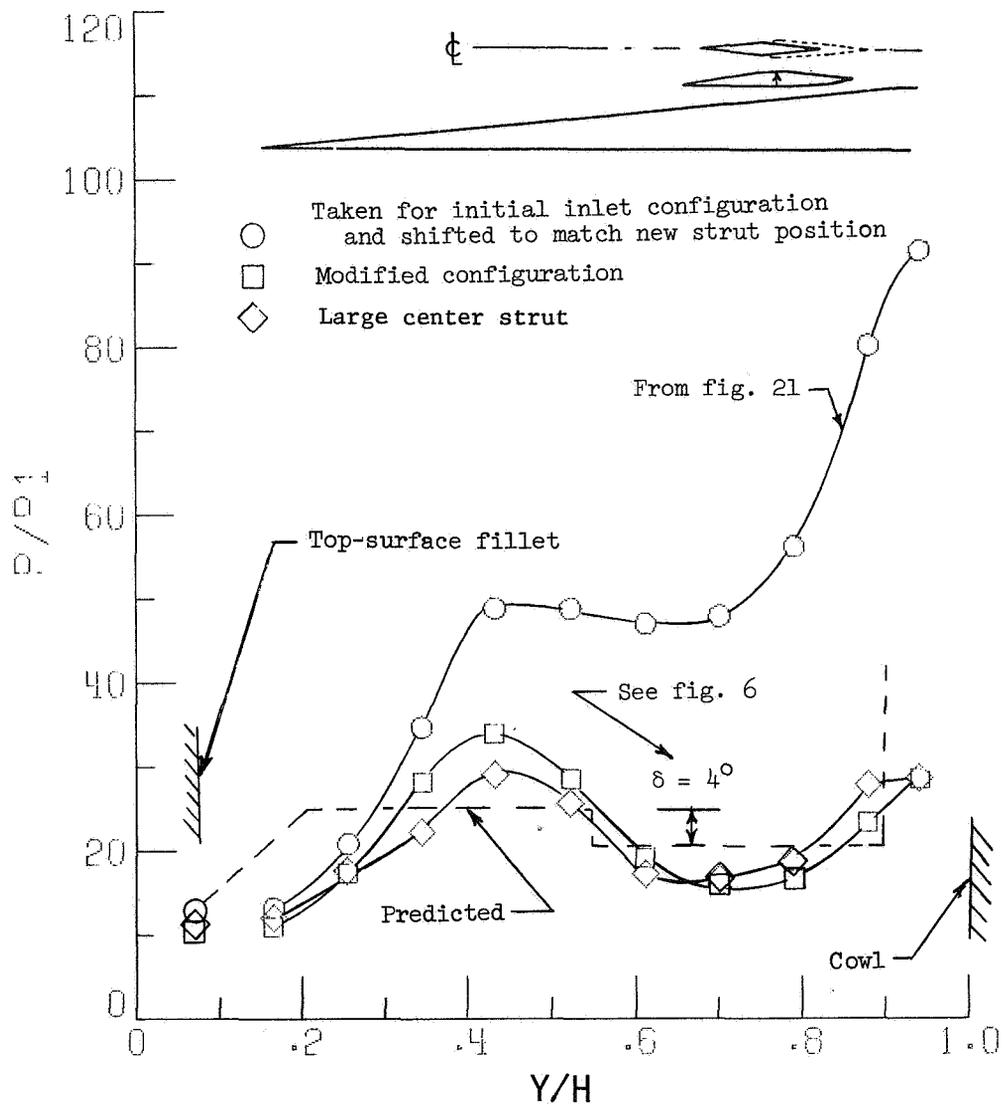


Figure 40.- Static-pressure distribution. Throat (center-passage side strut).

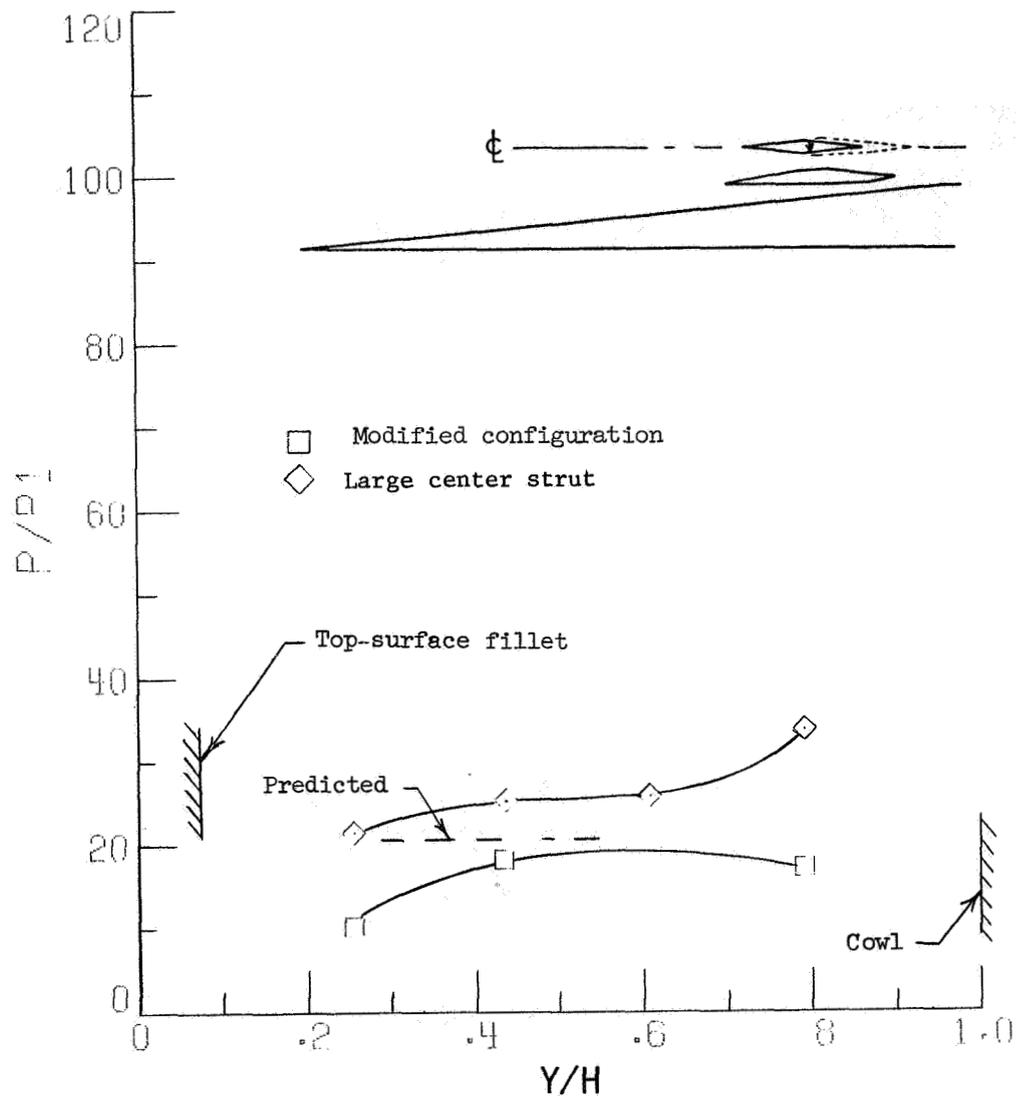
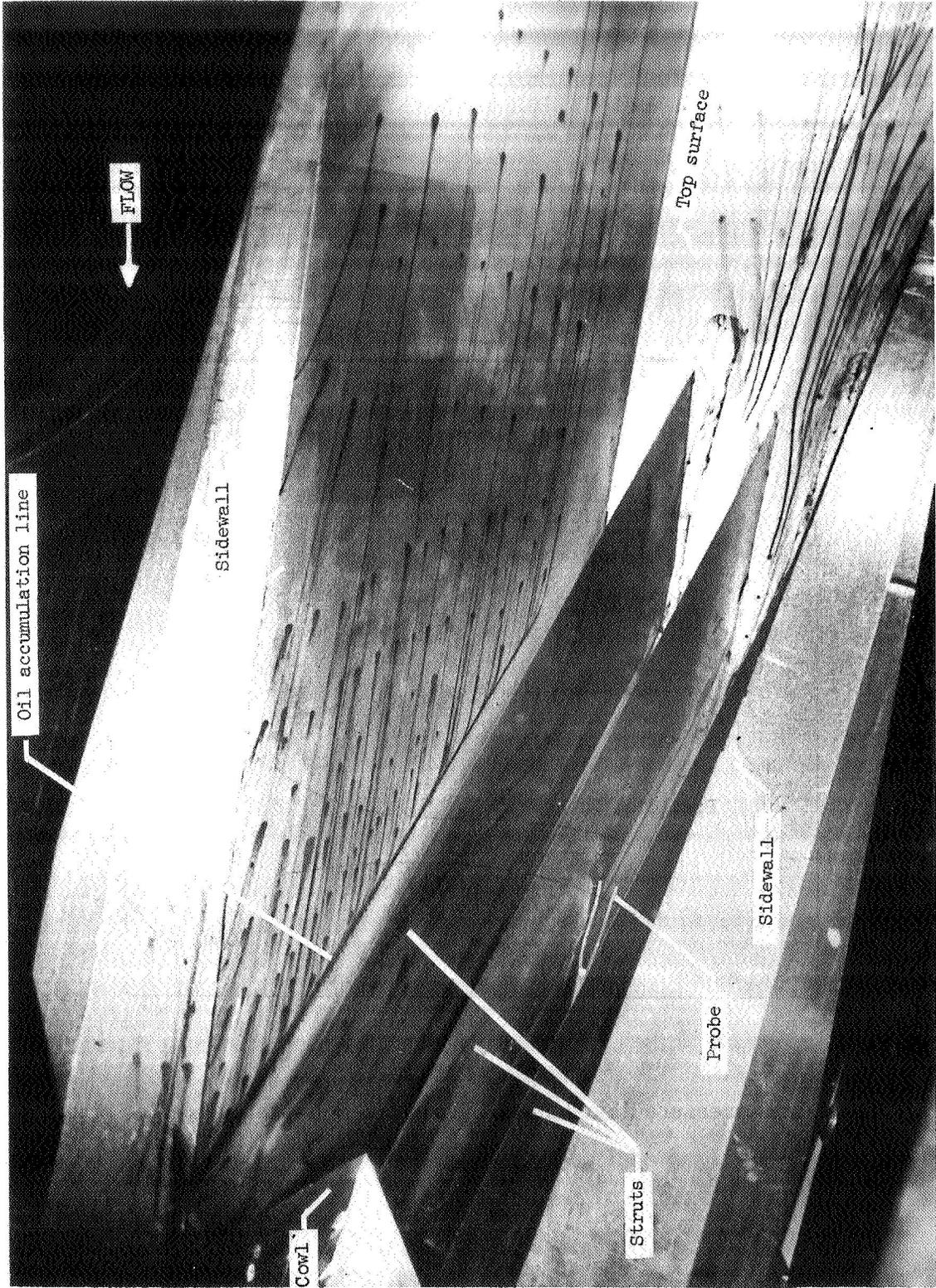
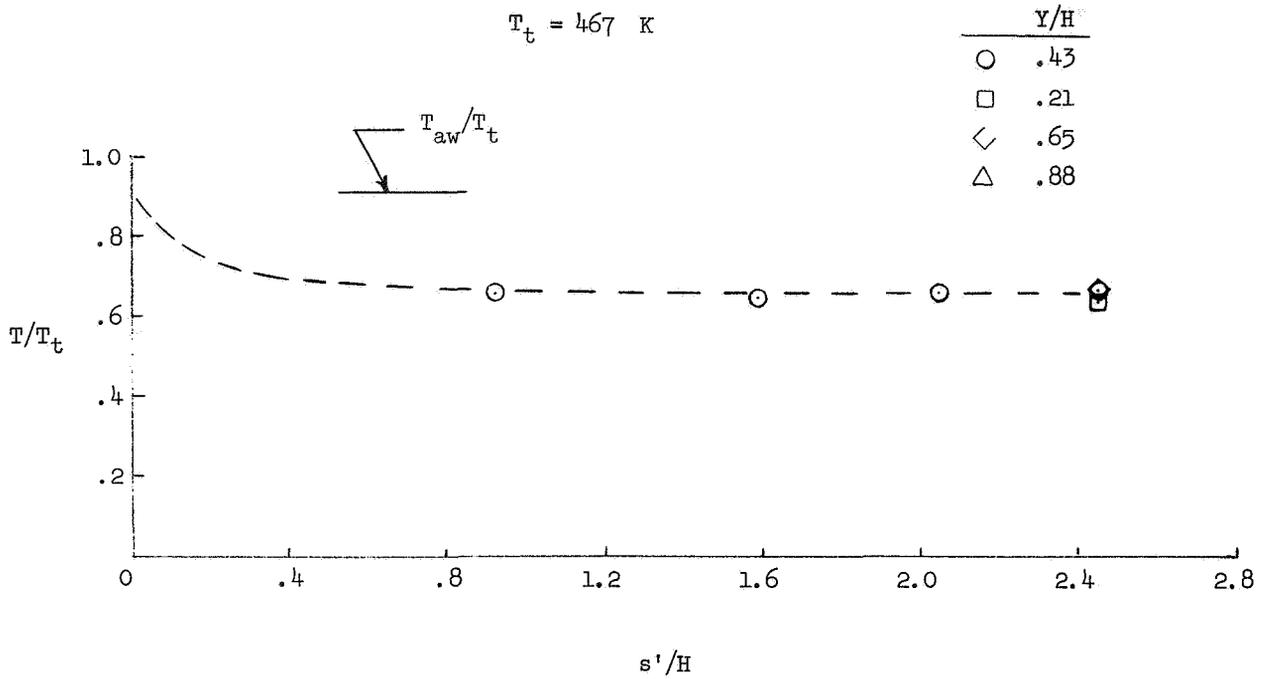


Figure 41.- Static-pressure distribution. Throat (center-passage center strut).

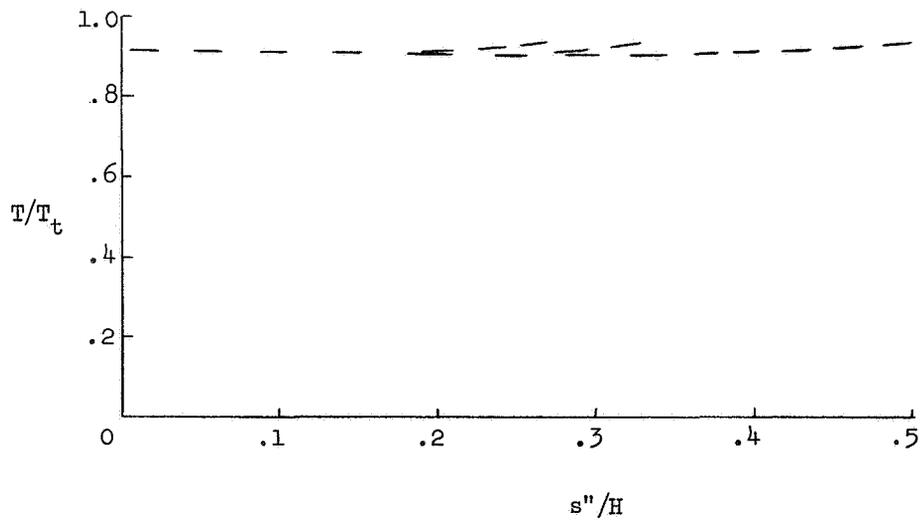


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Figure 42.- Oil-flow study.

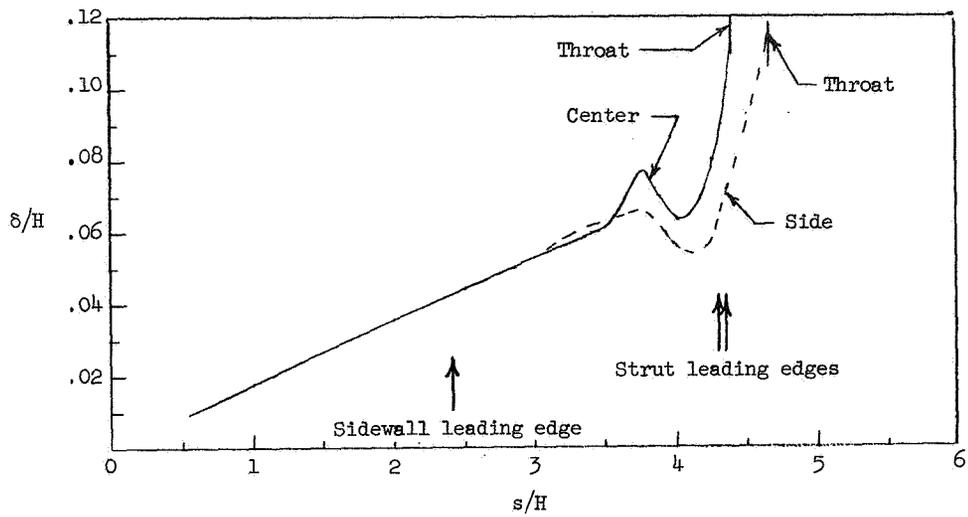


(a) Sidewall.

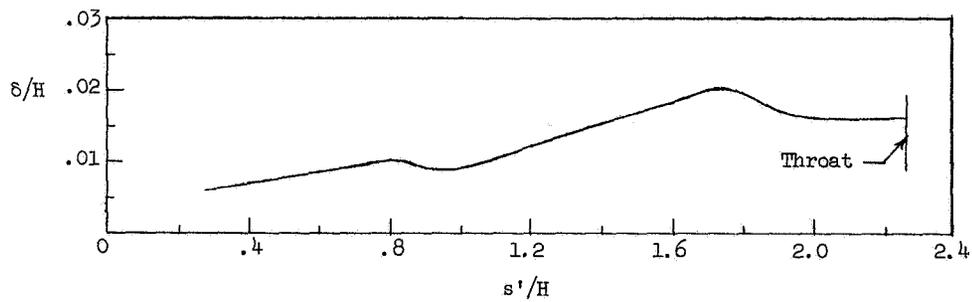


(b) Struts.

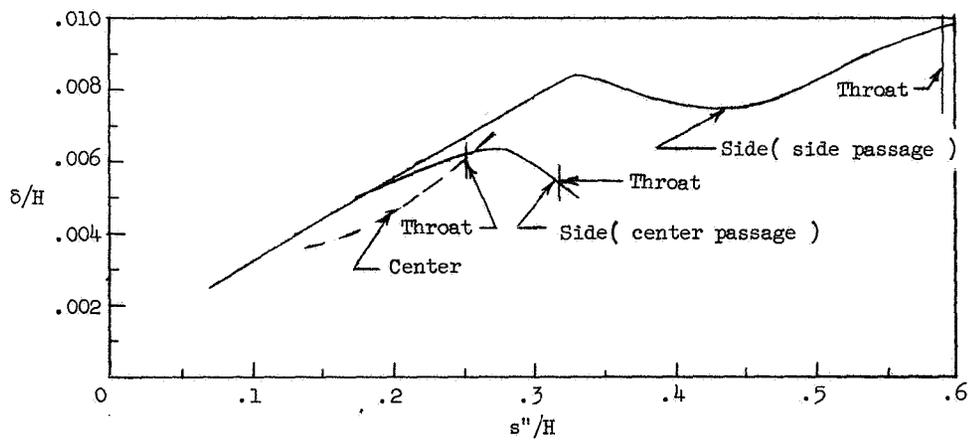
Figure 43.- Temperature distributions after 80 sec.  $M_1 = 6.0$ .



(a) Top surface.

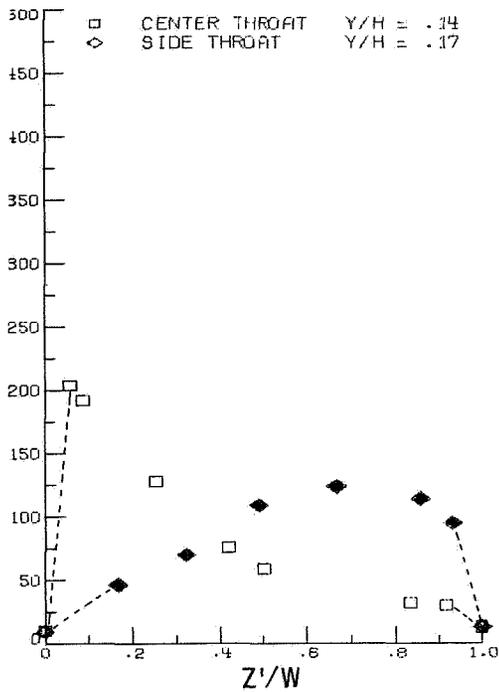


(b) Sidewall (xz-plane).

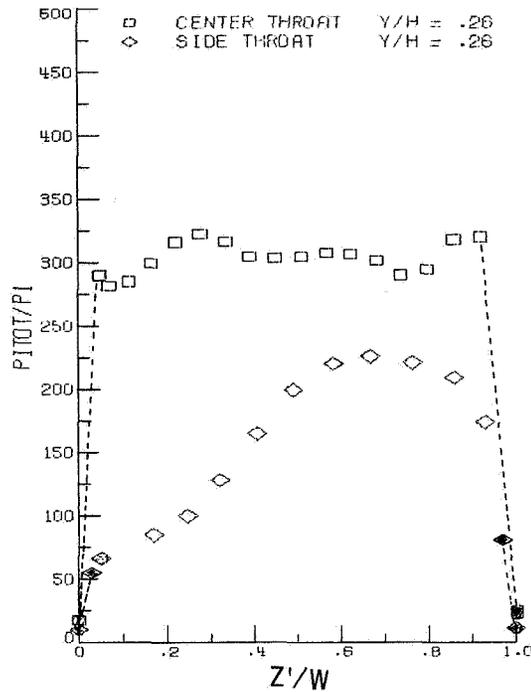


(c) Struts (xz-plane).

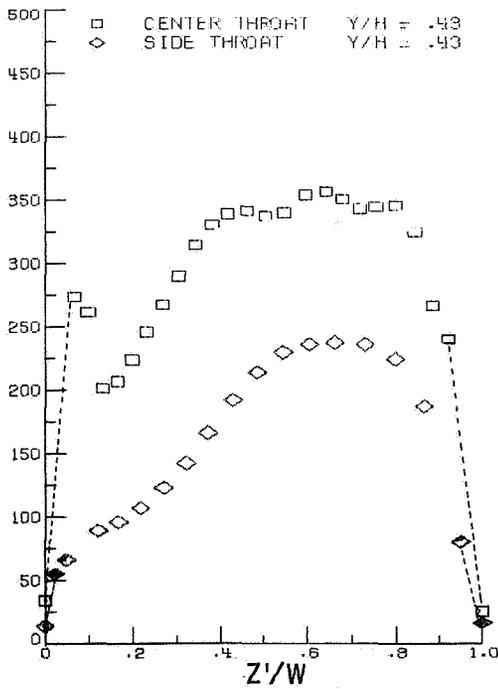
Figure 44.- Inlet boundary layers.



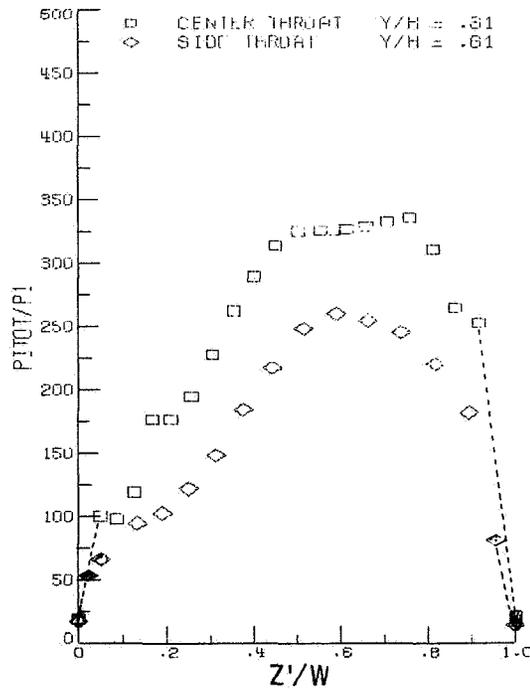
(a)  $Y/H = 0.15$ .



(b)  $Y/H = 0.26$ .

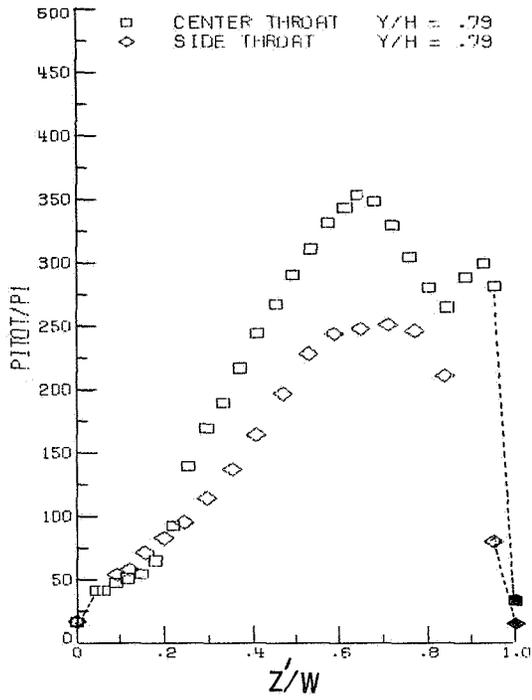


(c)  $Y/H = 0.43$ .

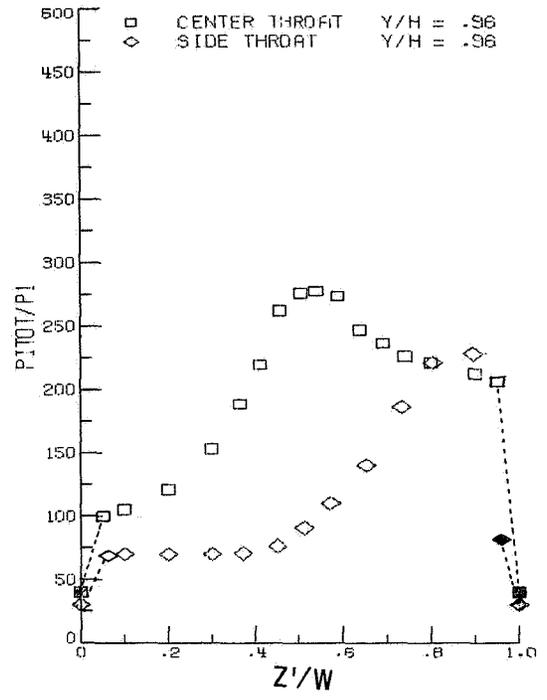


(d)  $Y/H = 0.61$ .

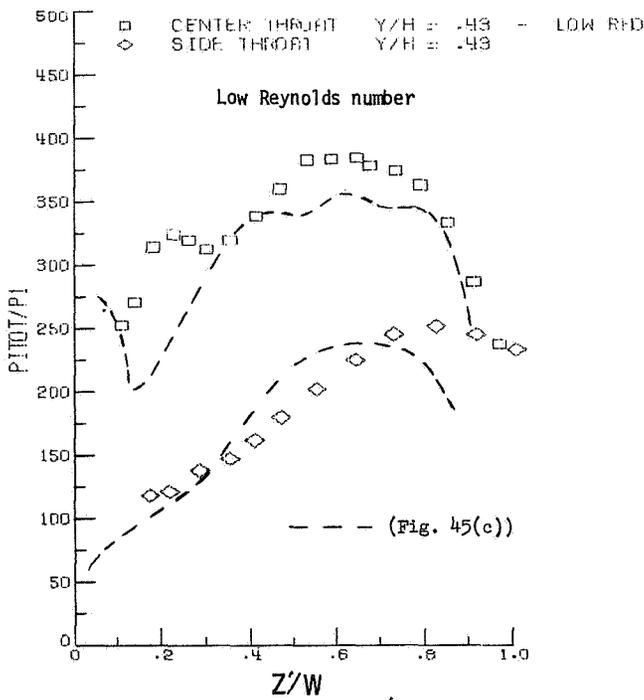
Figure 45.- Throat pitot pressure surveys. The solid symbols represent theoretical boundary-layer calculations.



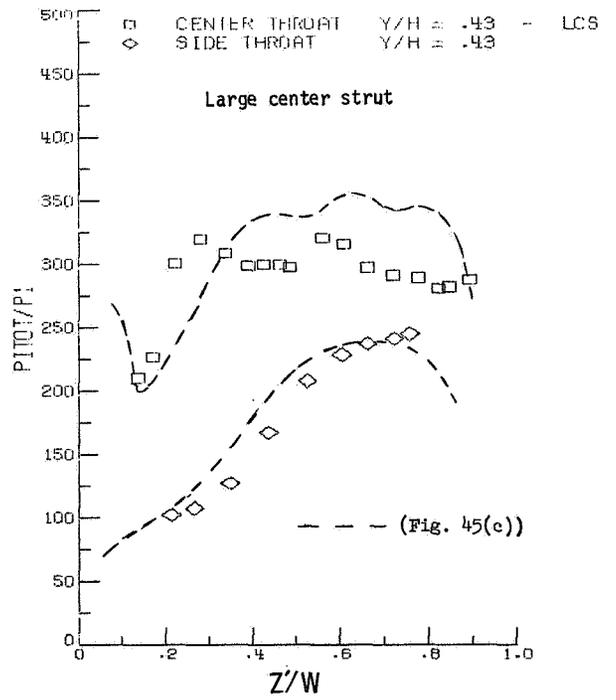
(e) Y/H = 0.79.



(f) Y/H = 0.96.

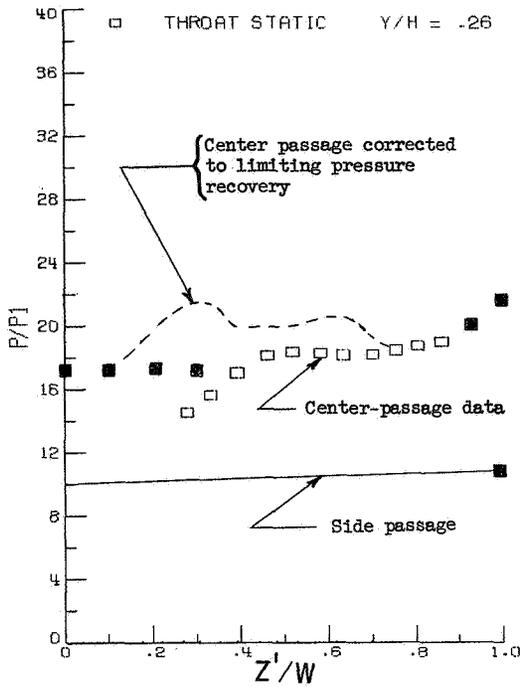


(g) Y/H = 0.43.

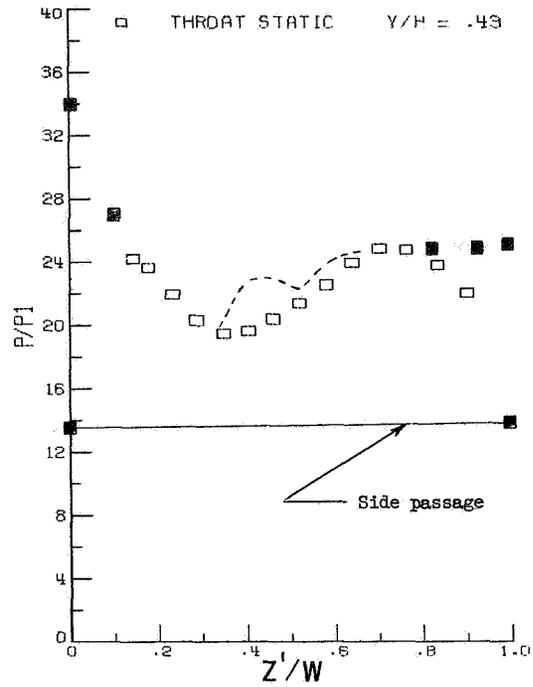


(h) Y/H = 0.43.

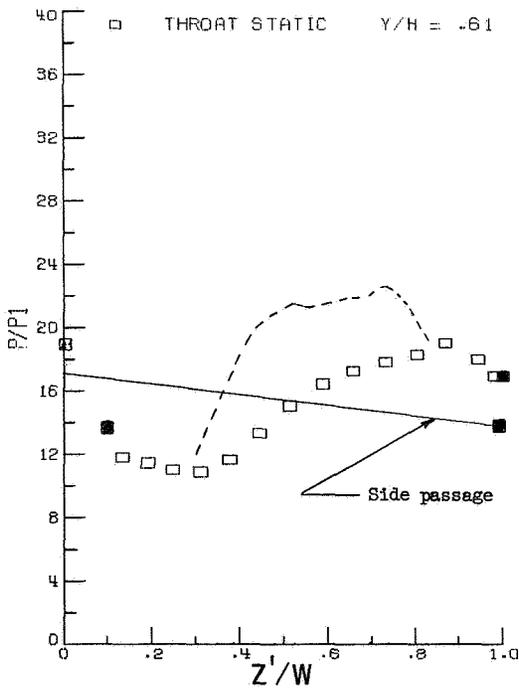
Figure 45.- Concluded.



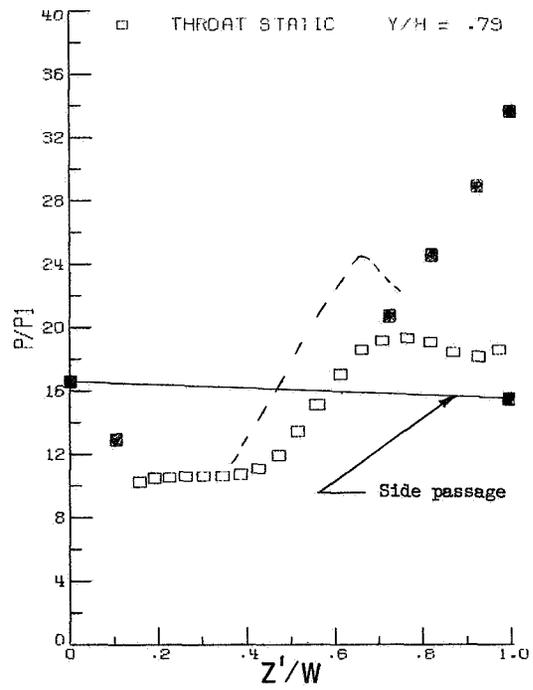
(a)  $Y/H = 0.26$ .



(b)  $Y/H = 0.43$ .

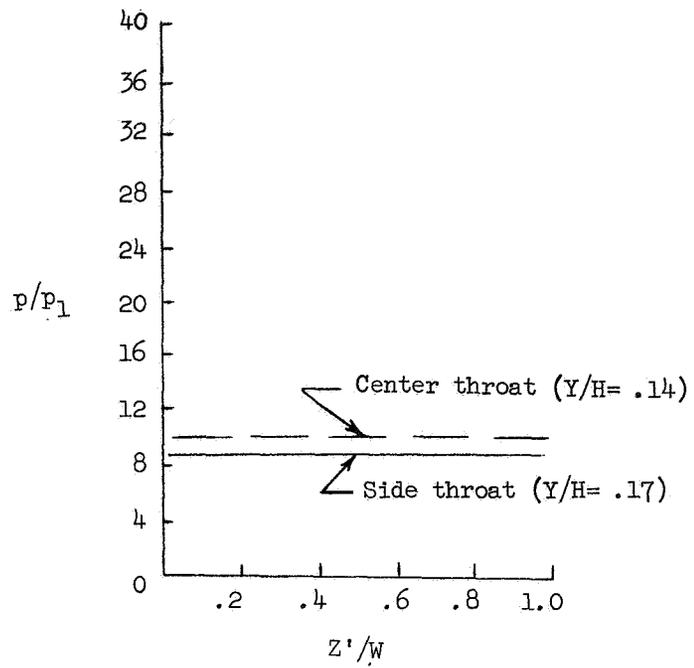


(c)  $Y/H = 0.61$ .

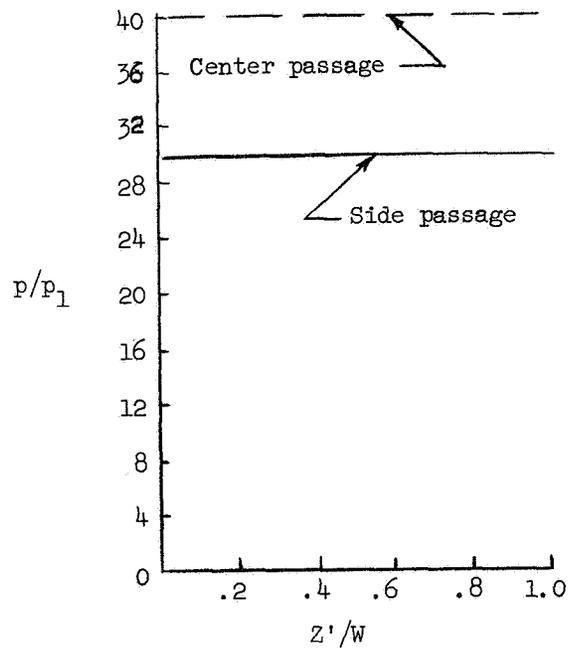


(d)  $Y/H = 0.79$ .

Figure 46.- Throat static-pressure surveys. The solid symbols represent data faired to the wall static pressure.

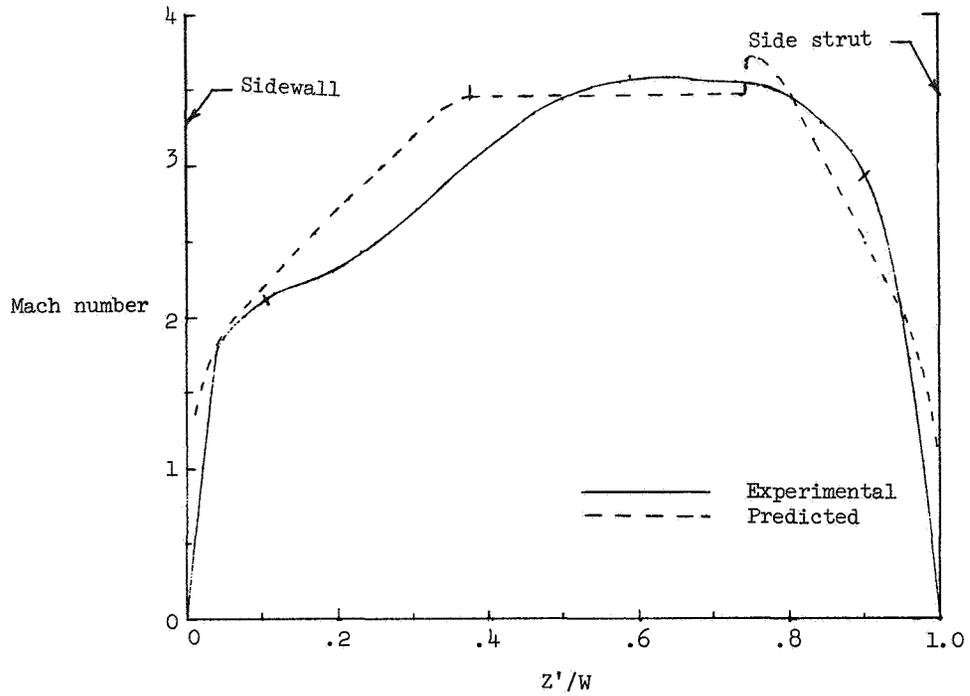


(a) Near top surface.

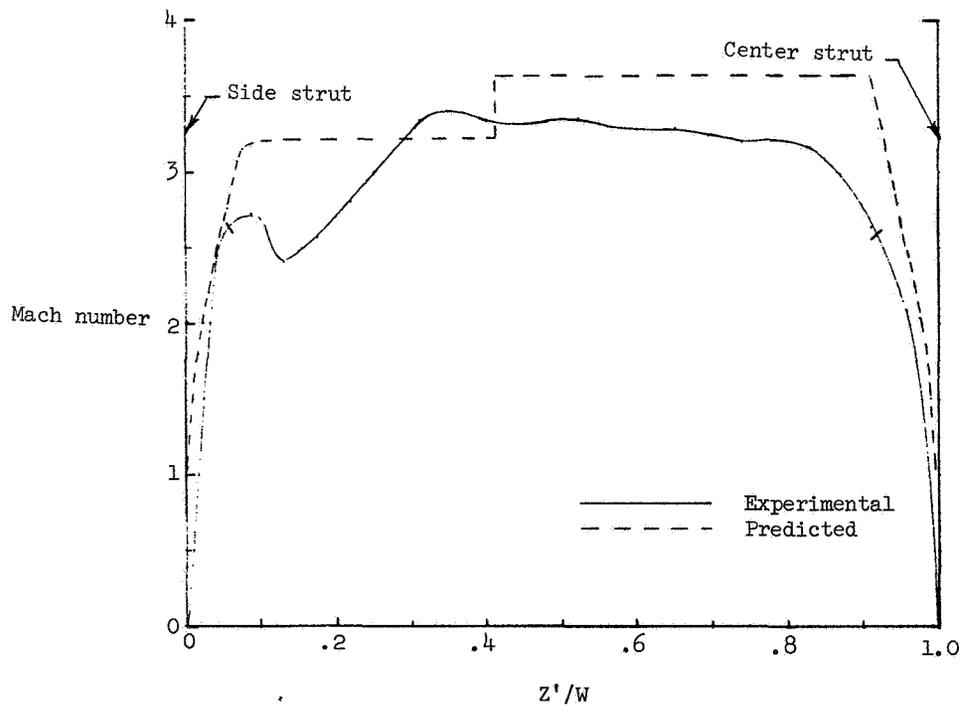


(b) Near cowl;  $Y/H = 0.96$ .

Figure 47.- Additional estimated throat static distributions.



(a) Side passage; Throat gap = 0.772 cm.



(b) Center passage; Throat gap = 1.227 cm.

Figure 48.- Mach number distribution at throat.  $Y/H = 0.43$ .

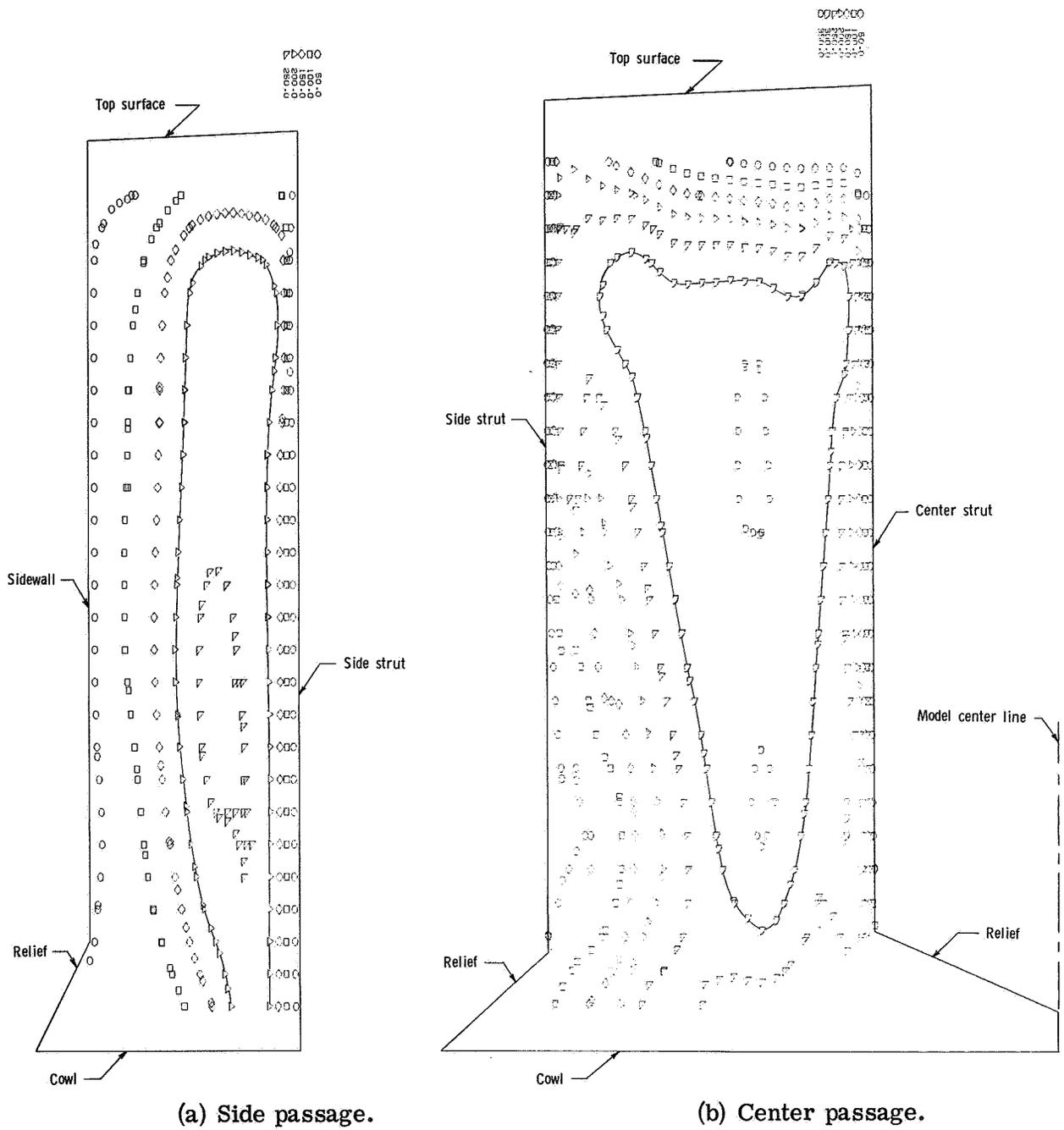
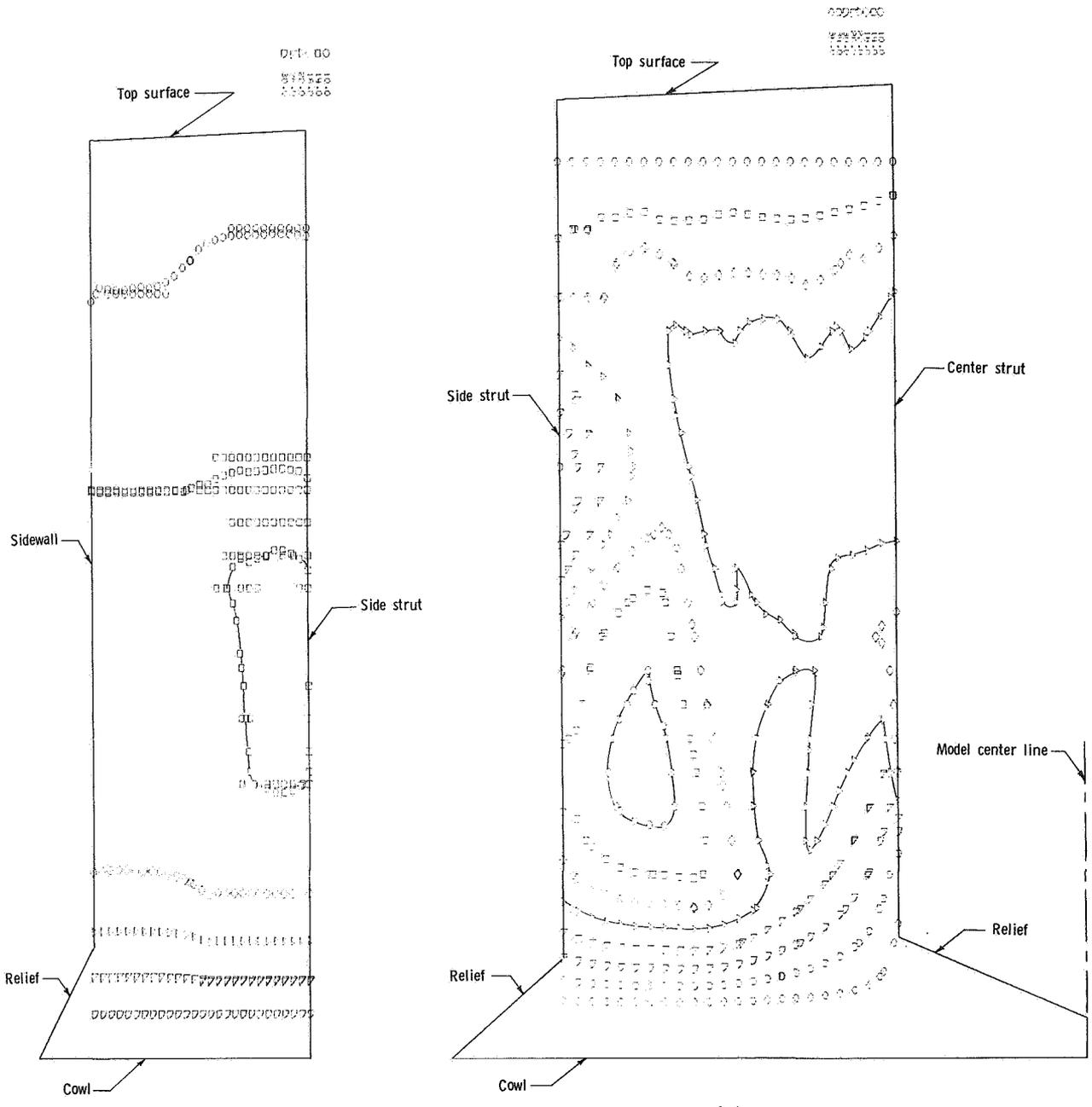


Figure 49.- Throat map of  $p_{\text{pitot}}/p_1$ .



(a) Side passage.

(b) Center passage.

Figure 50.- Throat map of  $p/p_1$ .

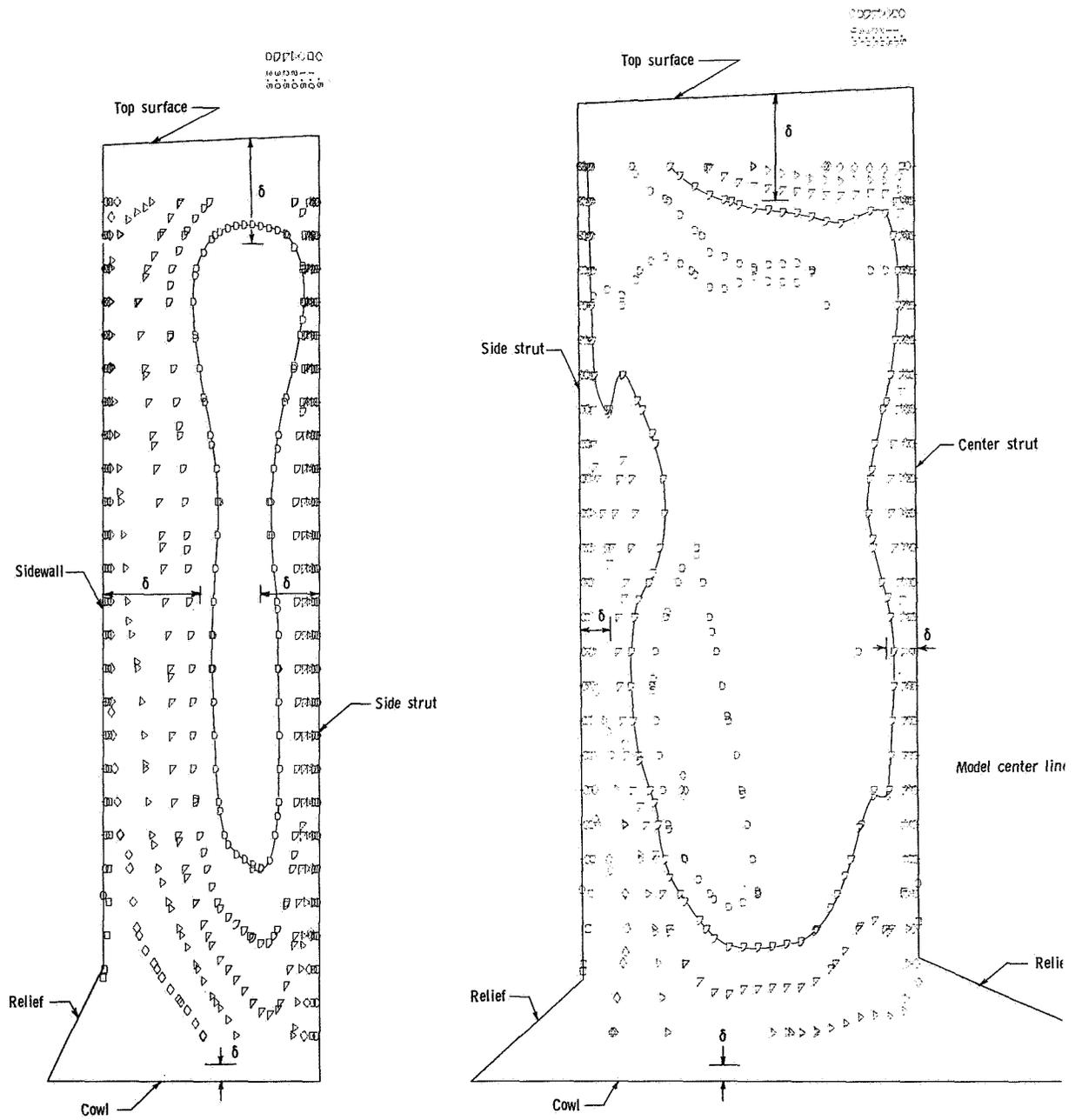
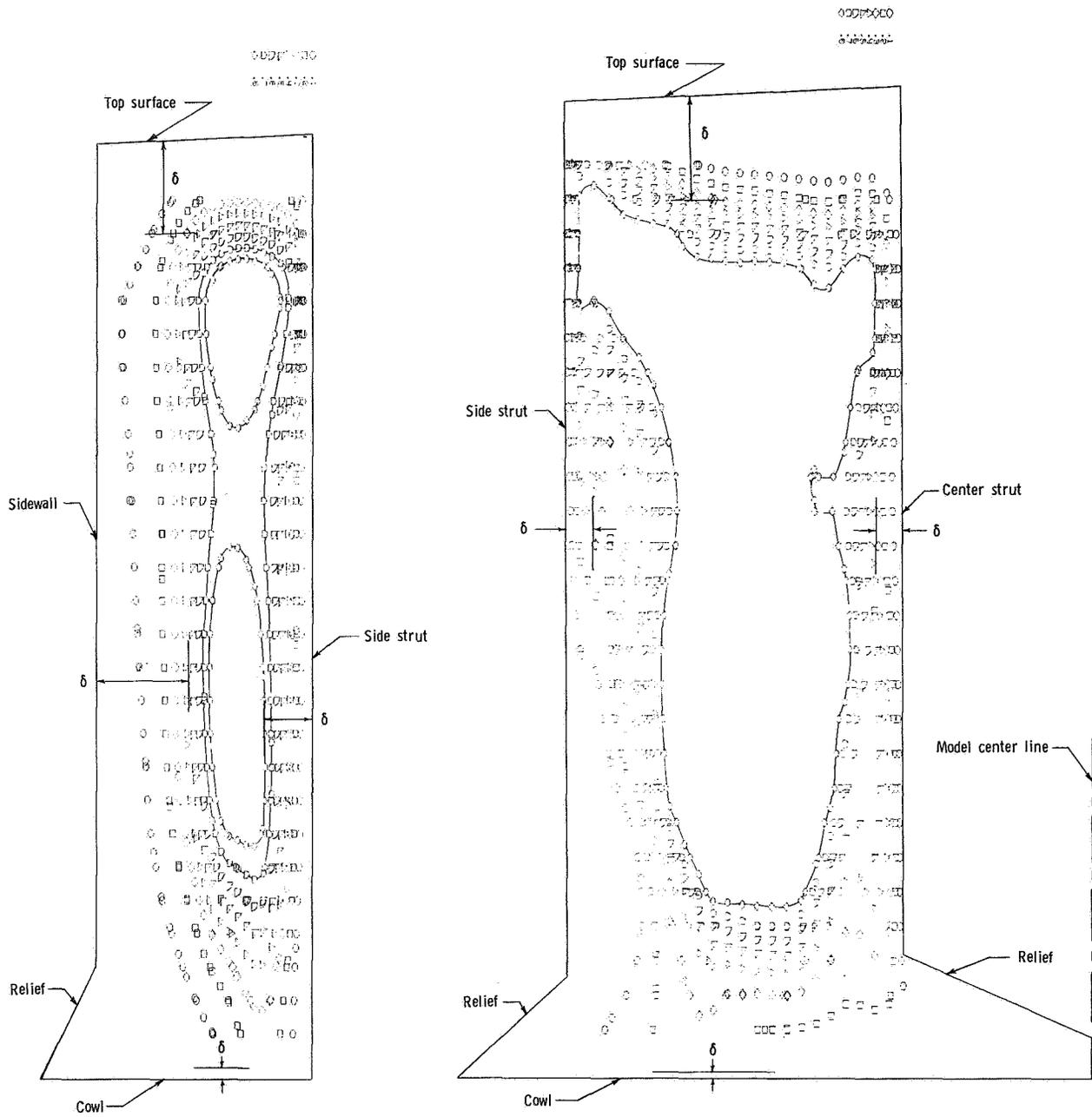


Figure 51.- Throat map of Mach number.  $M_1 = 6.0$ .



(a) Side passage.

(b) Center passage.

Figure 52.- Throat map of total-pressure recovery.

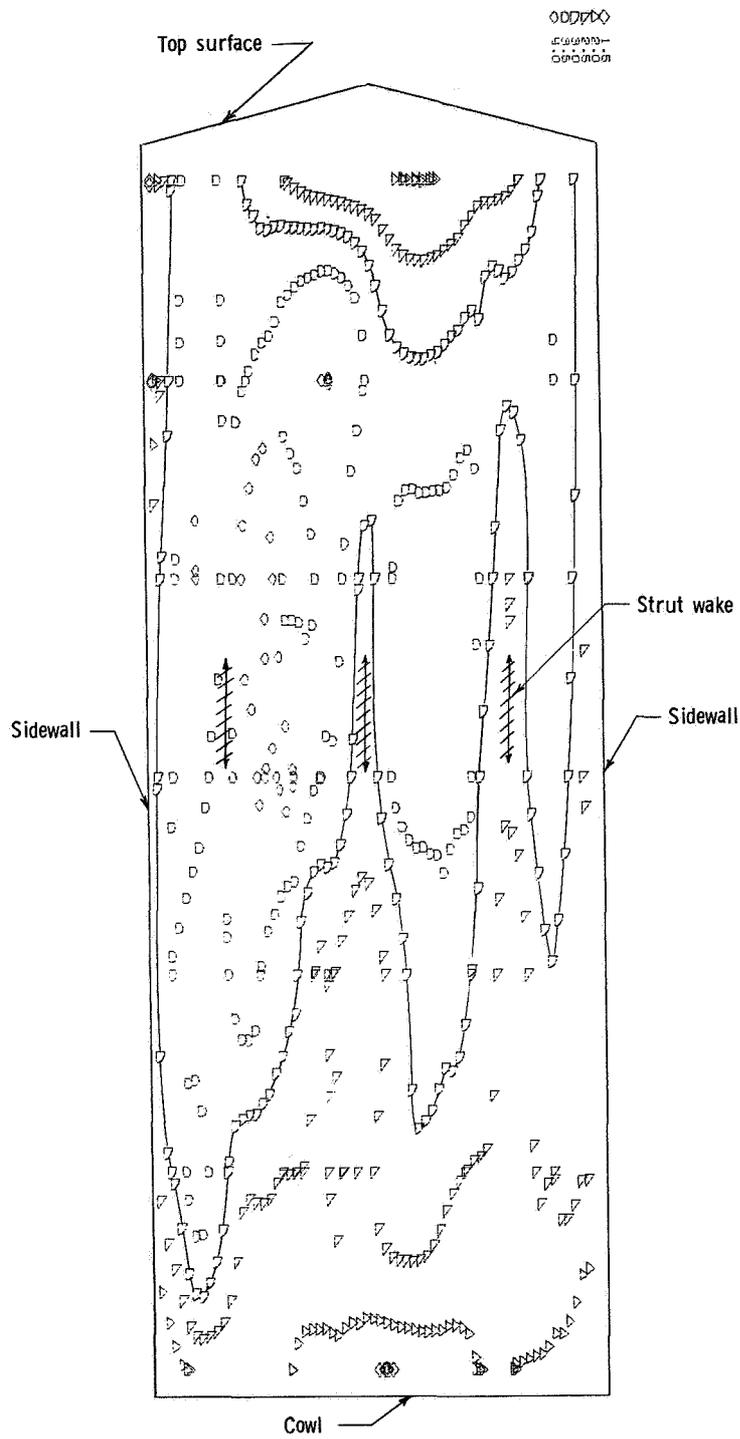


Figure 53.- Mach number distribution at capture station.  $M_1 = 6.0$ .

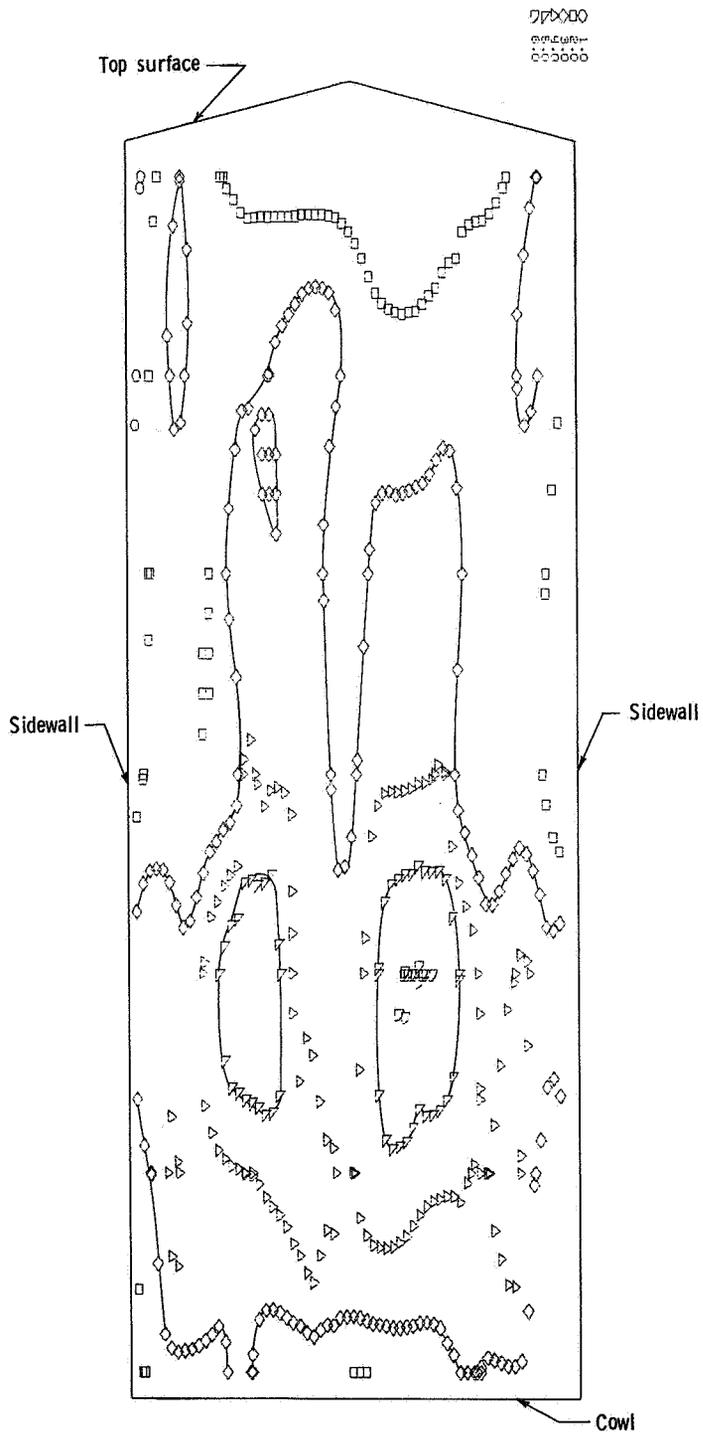


Figure 54.- Capture parameter  $\rho v / \rho_1 v_1$ .

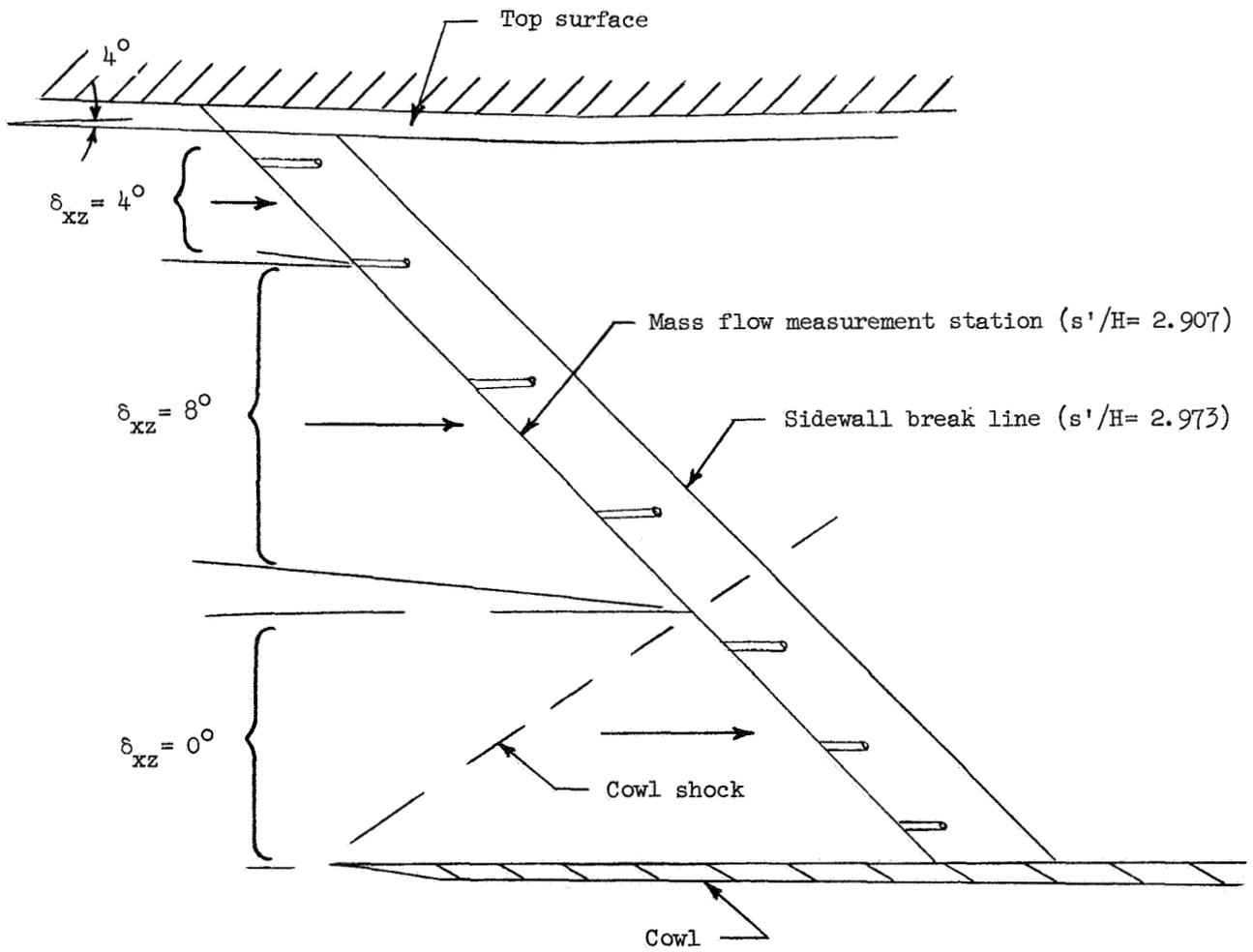
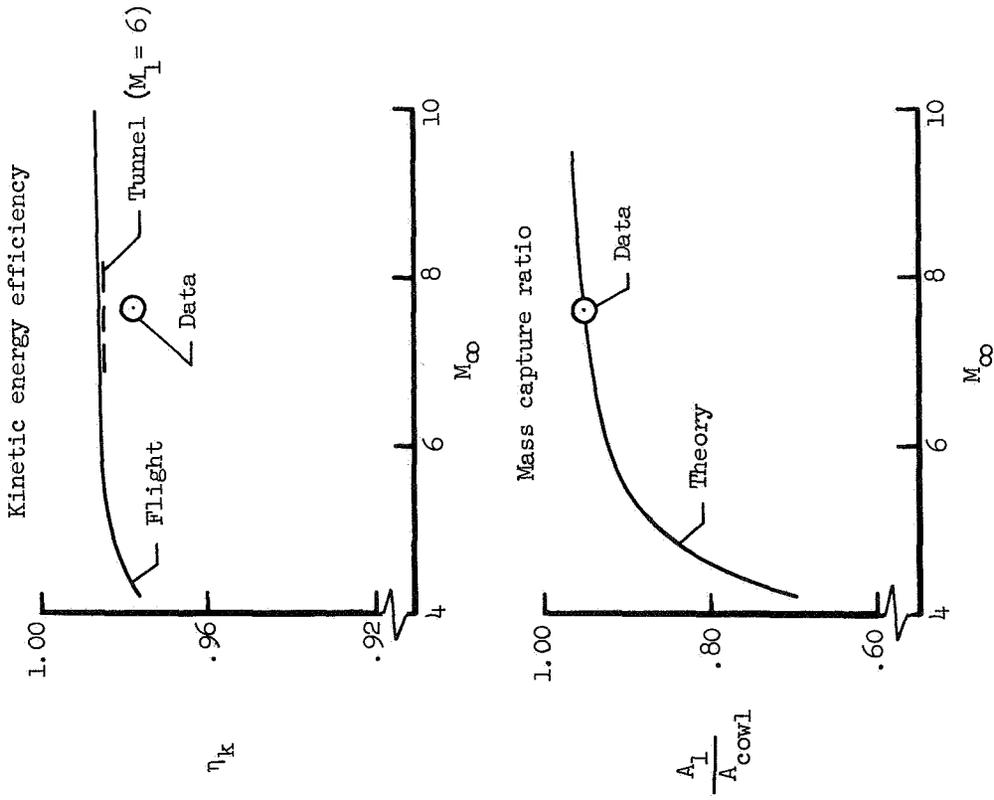


Figure 55.- Assumed flow directions used to compute capture.



	Passage		Total Inlet *
	Side	Center	
Contraction ratio	5.8	7.5	7.0
Throat Mach number	3.0	3.1	3.1
Recovery	.46	.66	.59
$\eta_k$	.965	.982	.977
Mass capture	.31	.63	.94

\* Flow split based on design

Figure 56.- Integrated performance parameters.

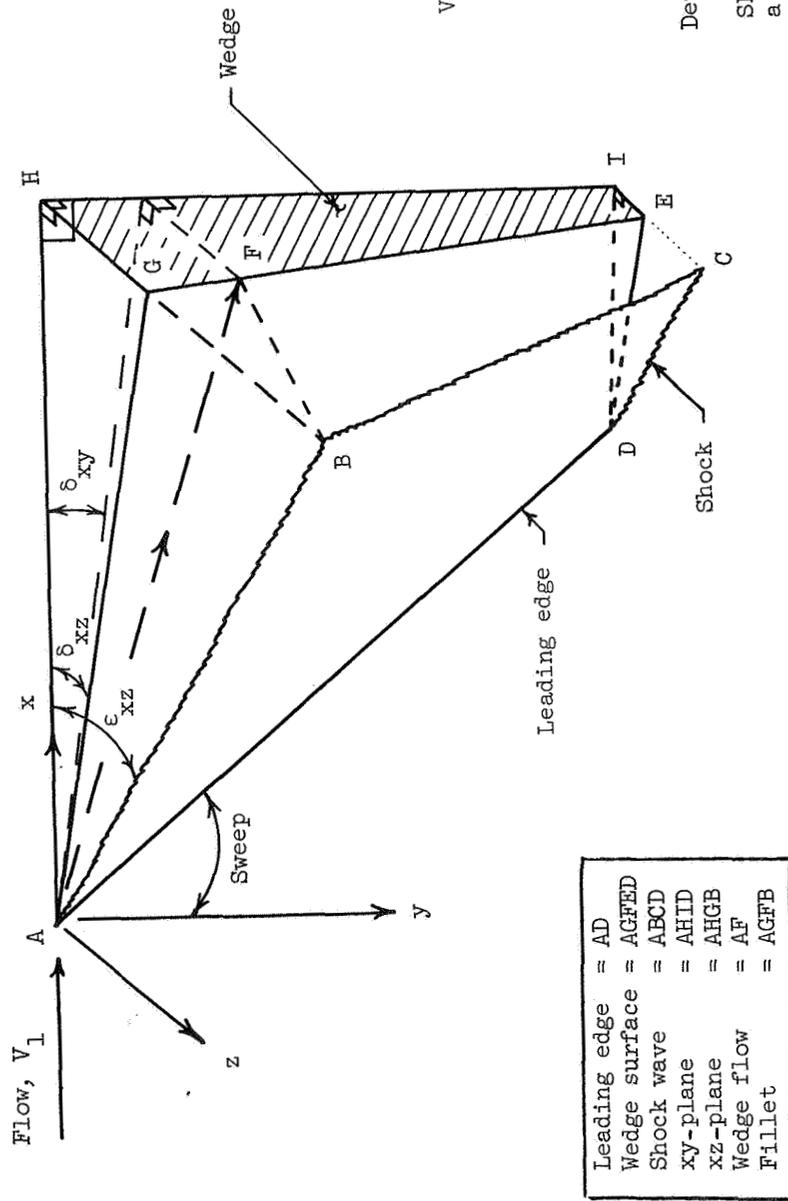


Figure 57. - Swept compression wedge.

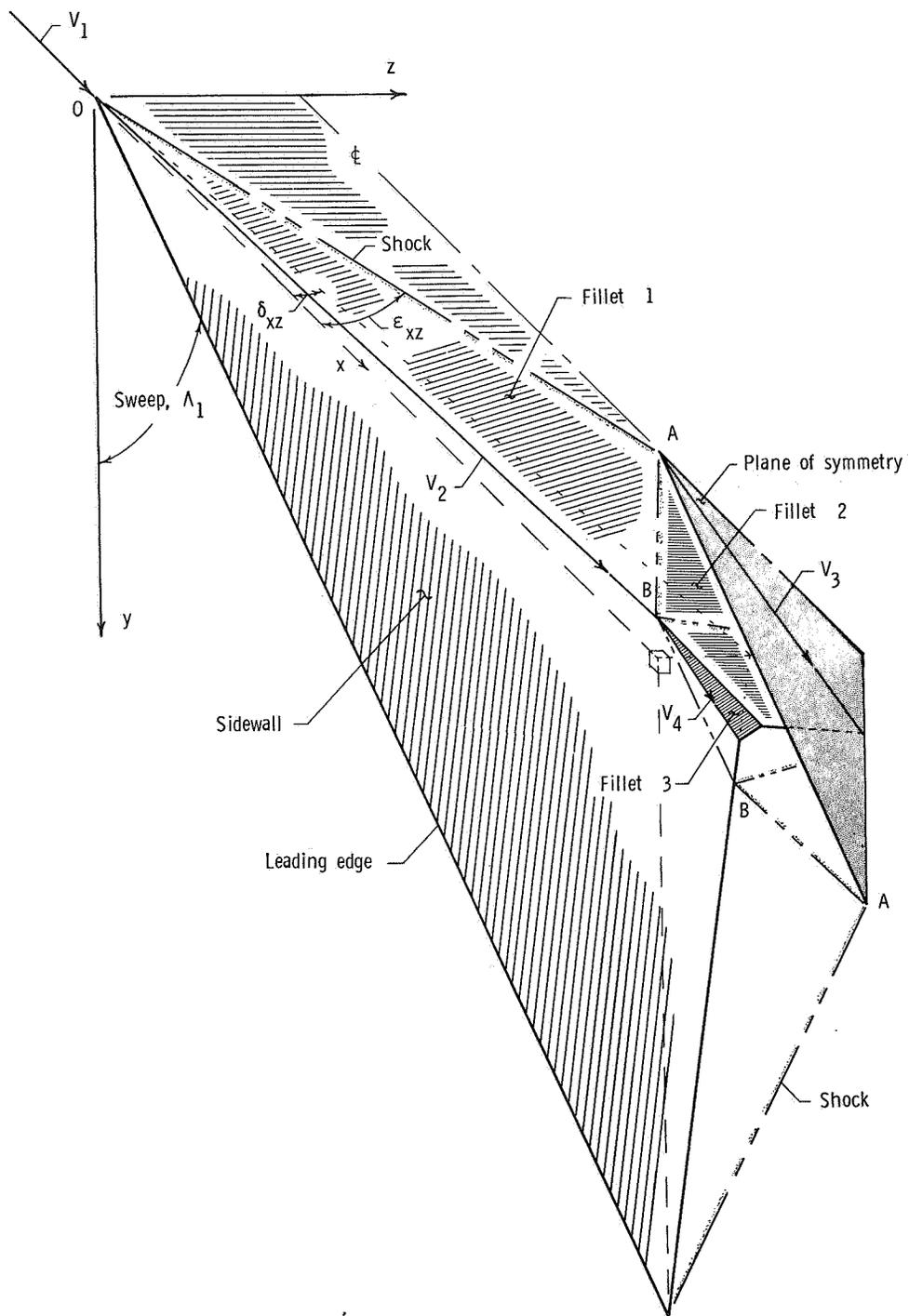


Figure 58.- Train of swept shock waves.

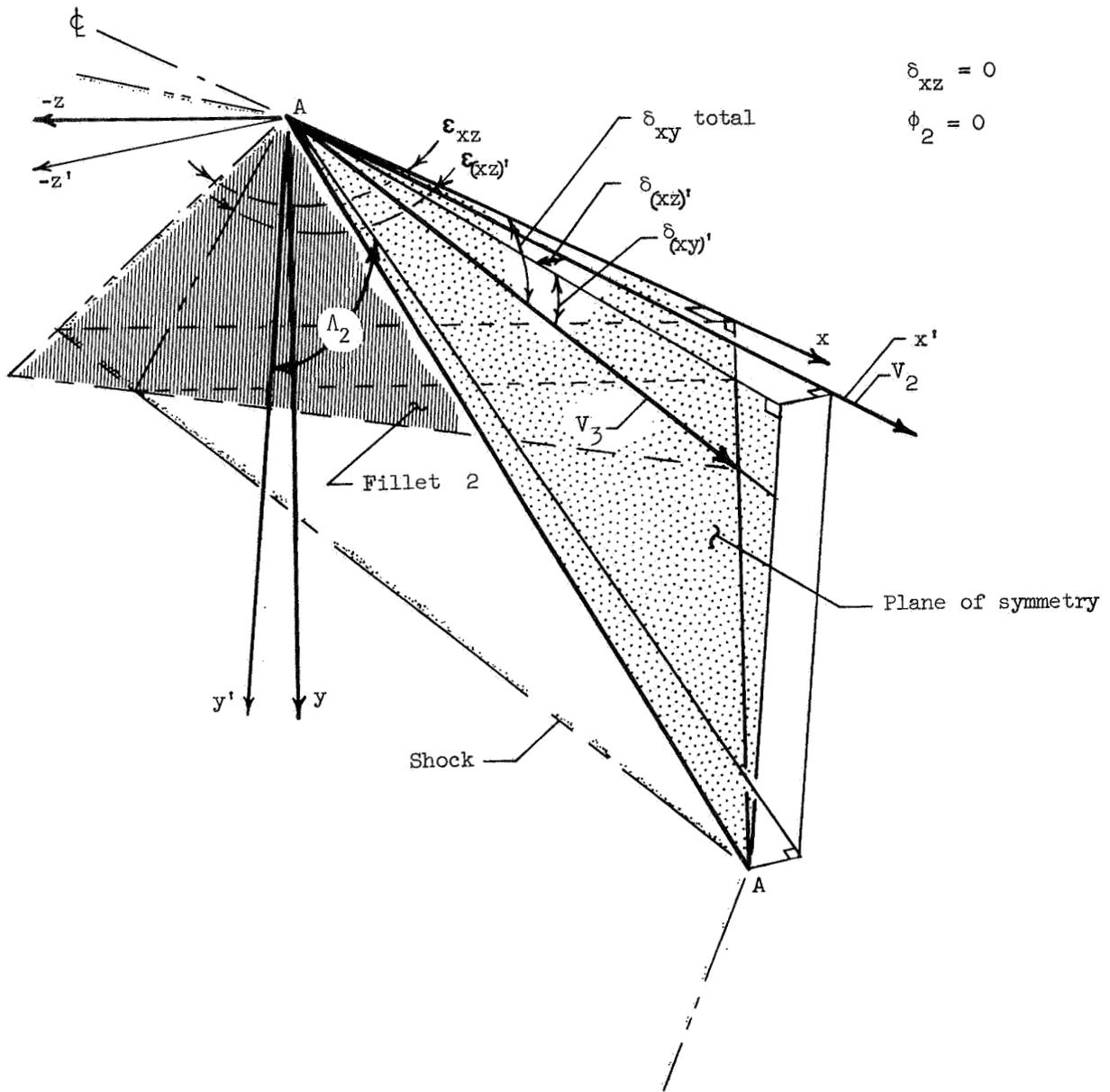
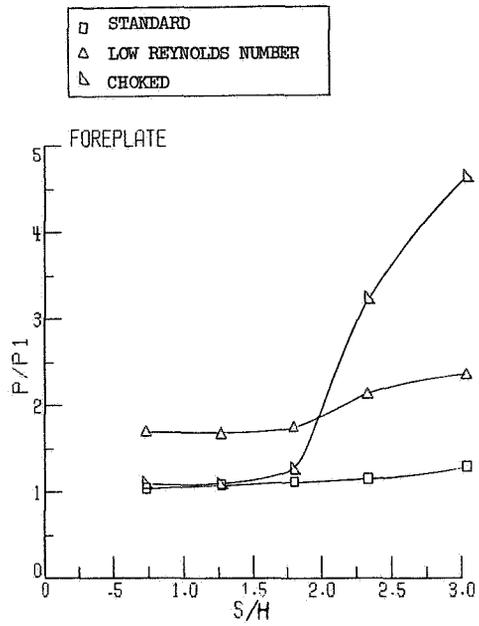
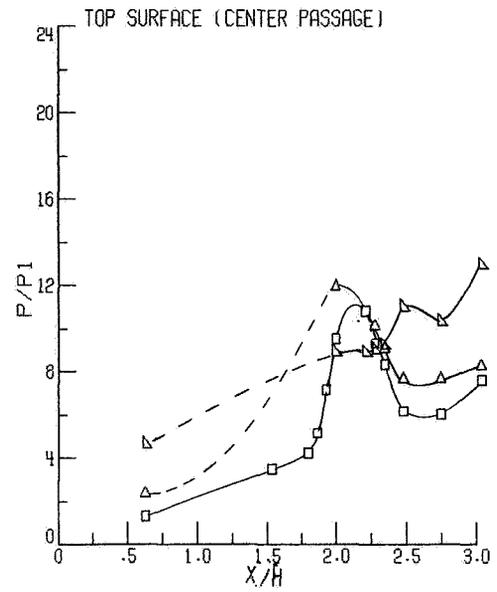


Figure 59.- First reflected shock wave.

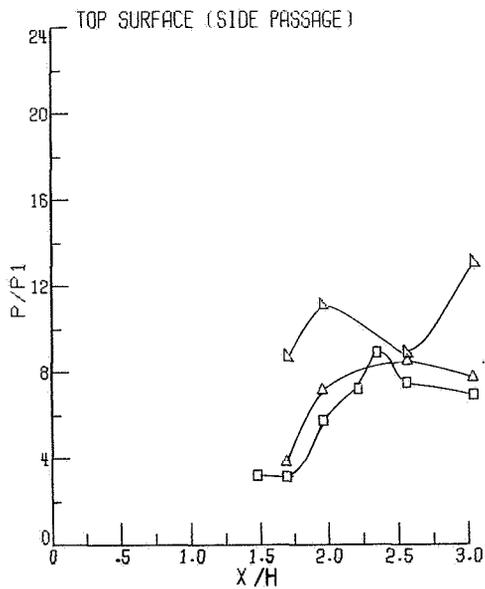




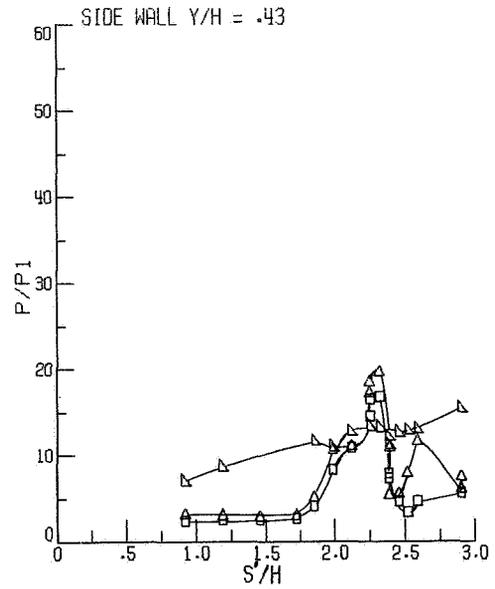
(a) Foreplate.



(b) Top surface (center passage).

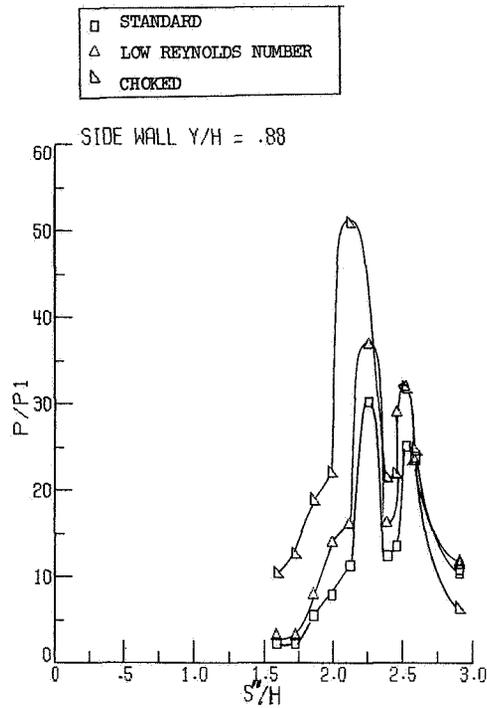


(c) Top surface (side passage).

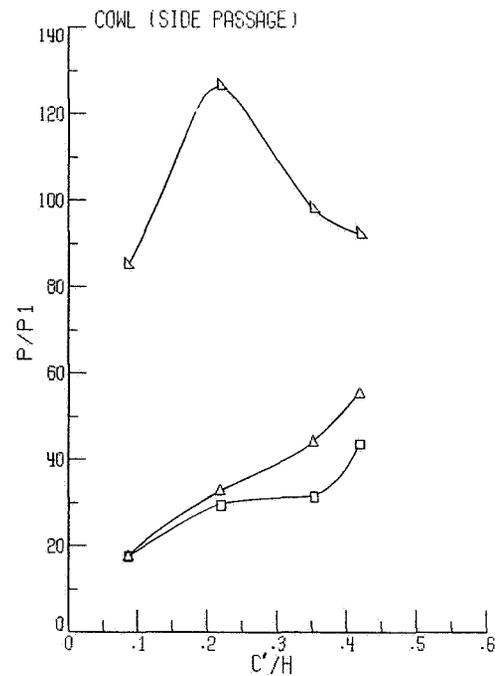


(d) Side wall;  $Y/H = 0.43$ .

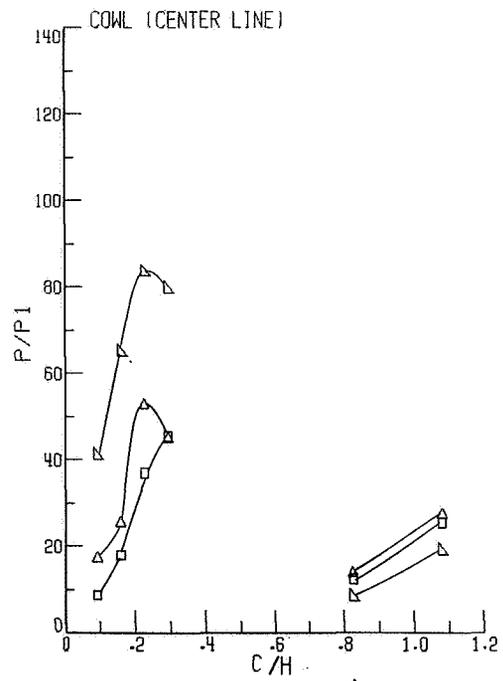
Figure 61.- Static pressure distributions for low pressure and choked inlet tests.  
 $M_1 = 6.0$ .



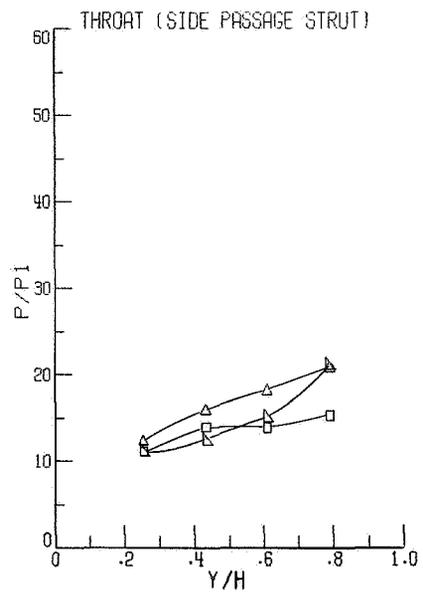
(e) Side wall;  $Y/H = 0.88$ .



(f) Cowl (side passage).

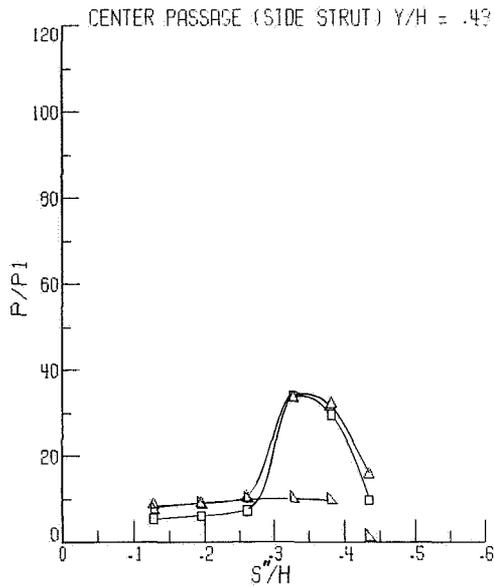
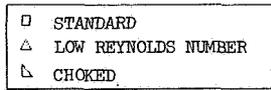


(g) Cowl (center line).

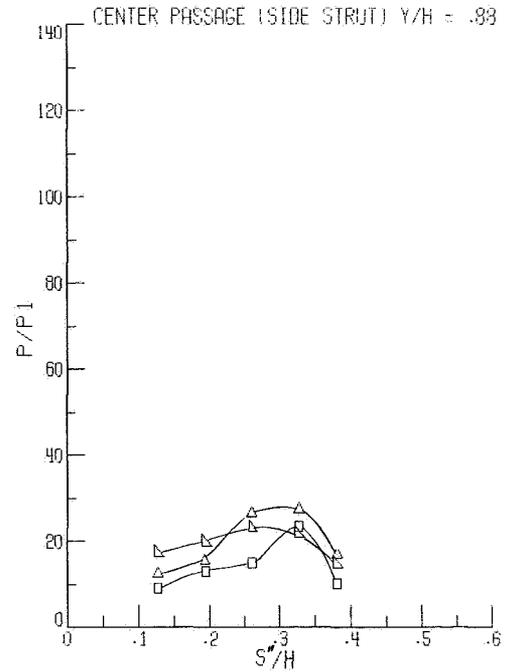


(h) Throat (side passage strut).

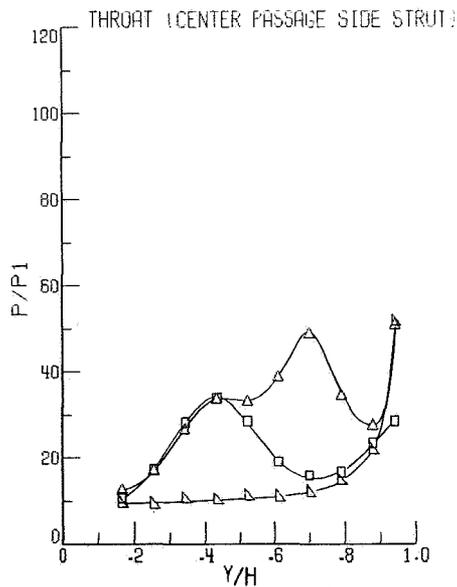
Figure 61.- Continued.



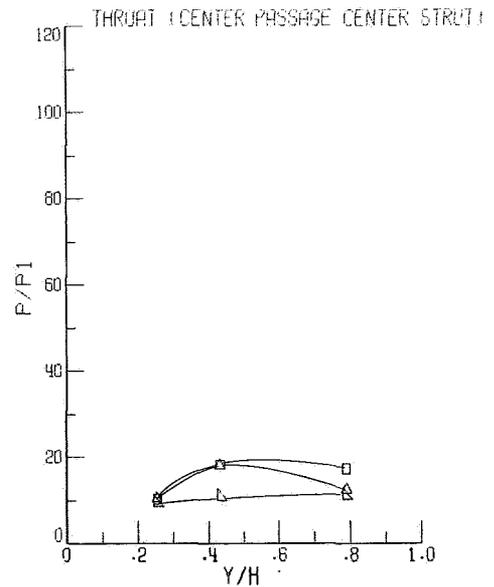
(i) Center passage (side strut);  
 $Y/H = 0.43$ .



(j) Center passage (side strut);  
 $Y/H = 0.88$ .



(k) Throat (center-passage side strut).



(l) Throat (center-passage center strut).

Figure 61.- Concluded.

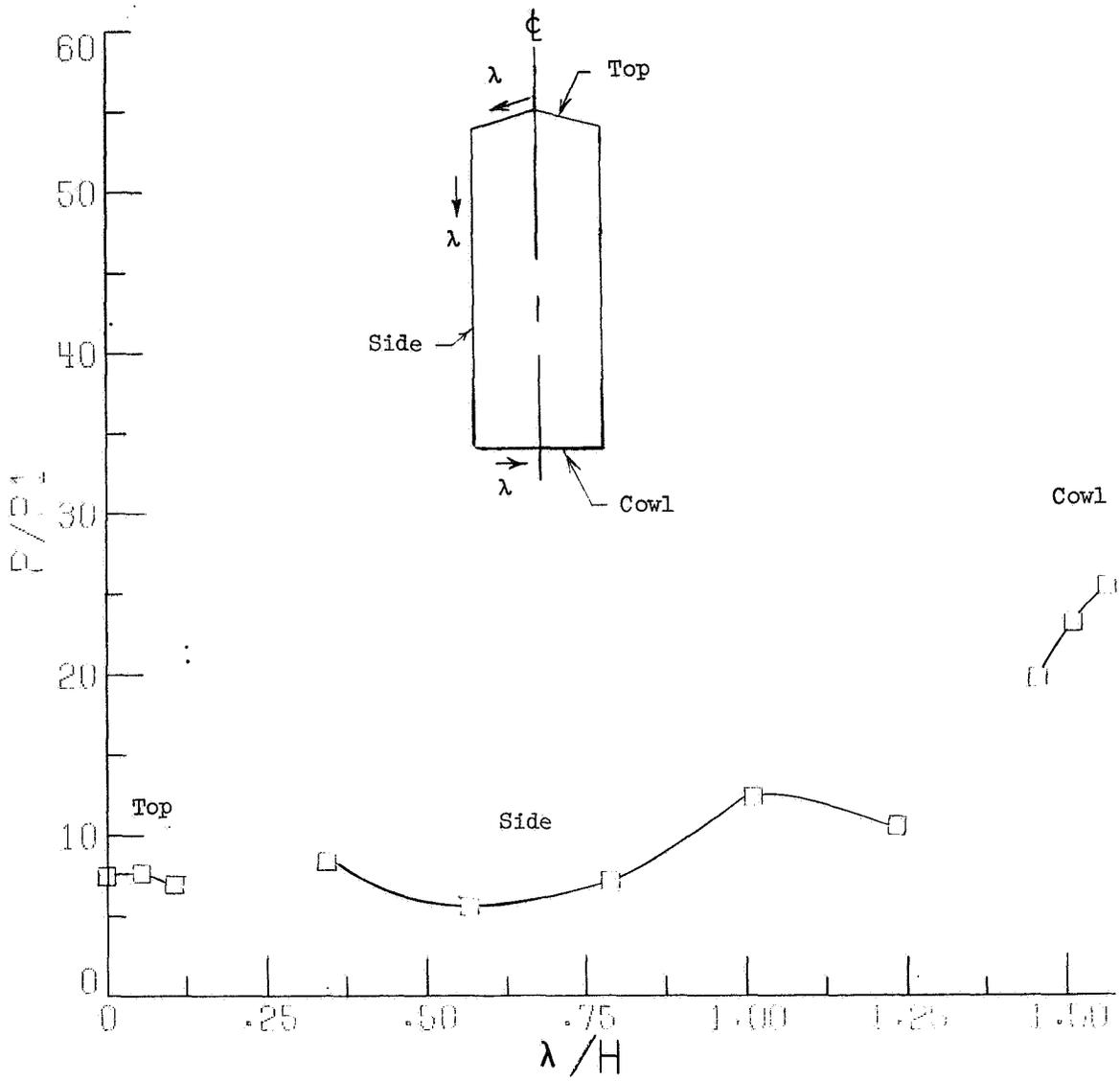
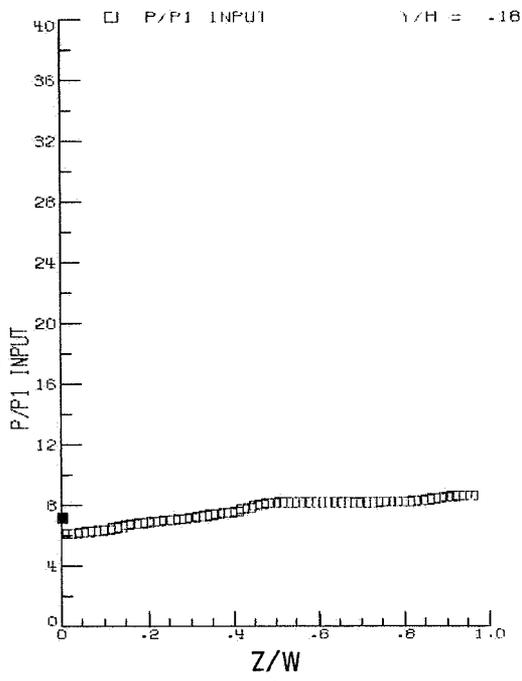
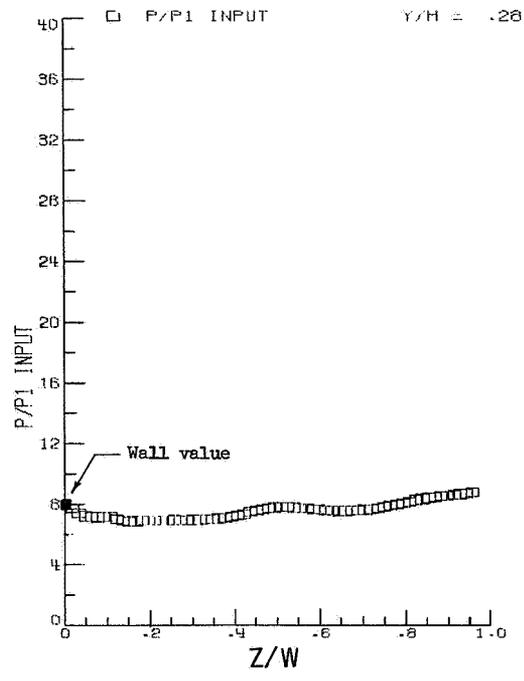


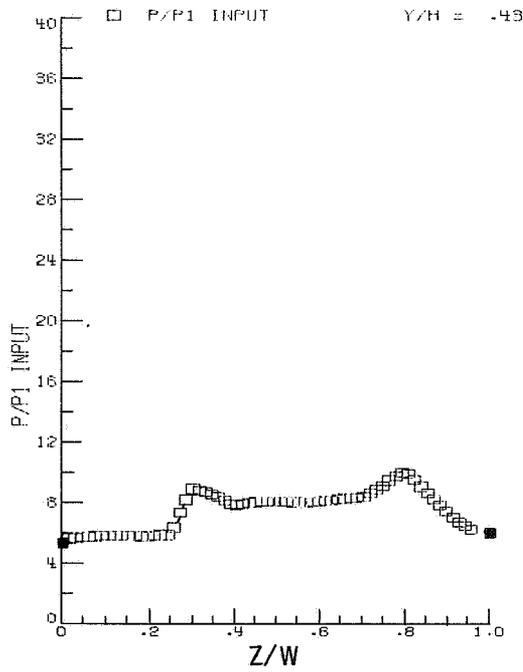
Figure 62.- Wall static-pressure distribution at capture station.



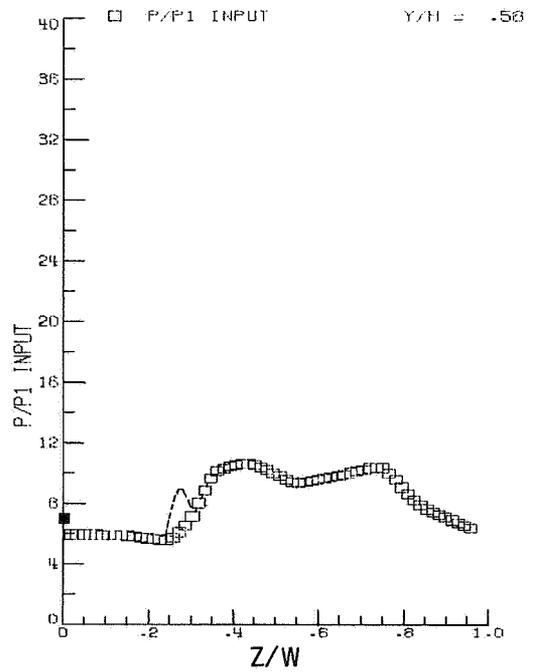
(a)  $Y/H = 0.18.$



(b)  $Y/H = 0.28.$

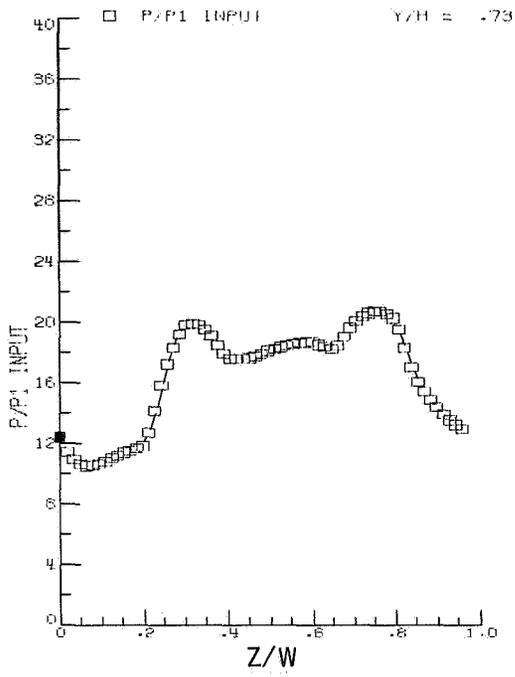


(c)  $Y/H = 0.43.$

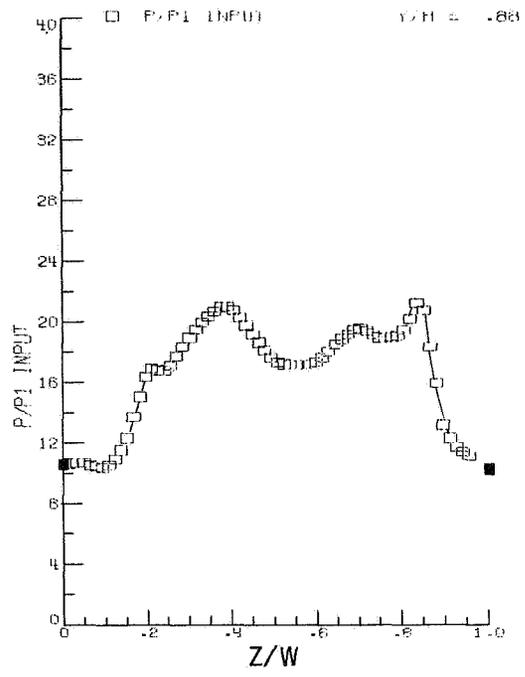


(d)  $Y/H = 0.58.$

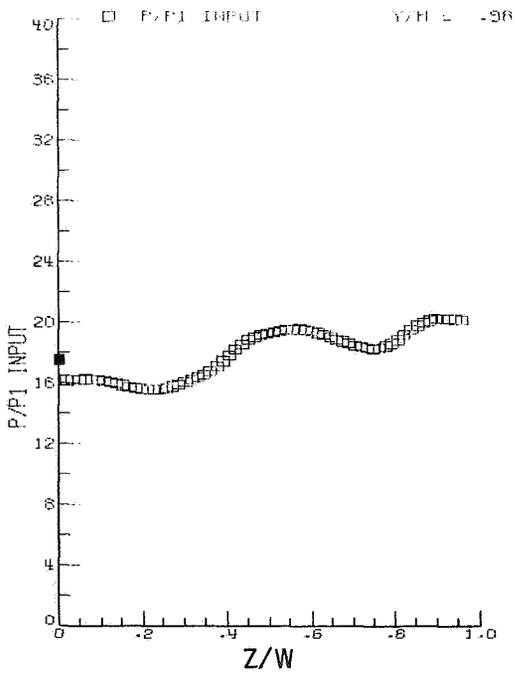
Figure 63.- Static-pressure surveys at capture station.  $M_1 = 6.0.$



(e)  $Y/H = 0.73$ .

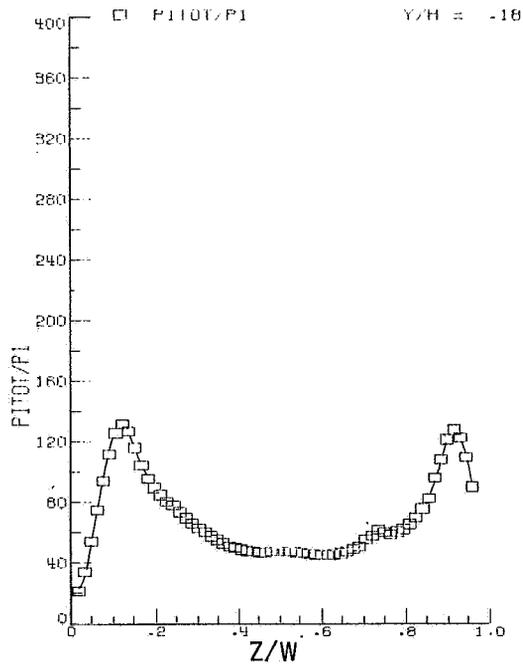


(f)  $Y/H = 0.88$ .

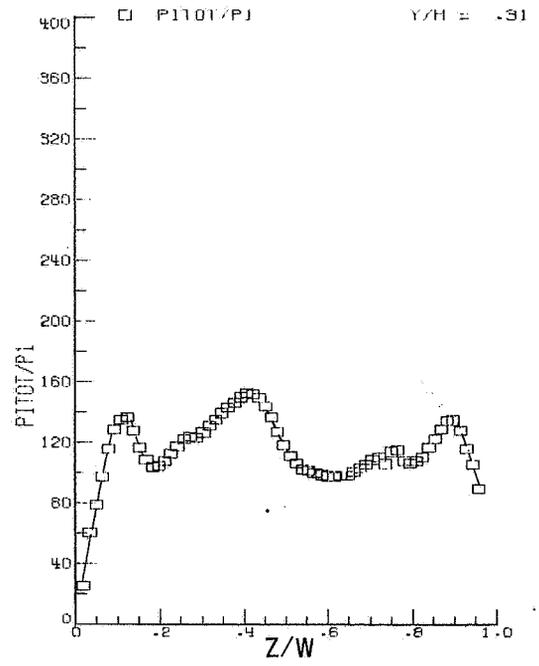


(g)  $Y/H = 0.98$ .

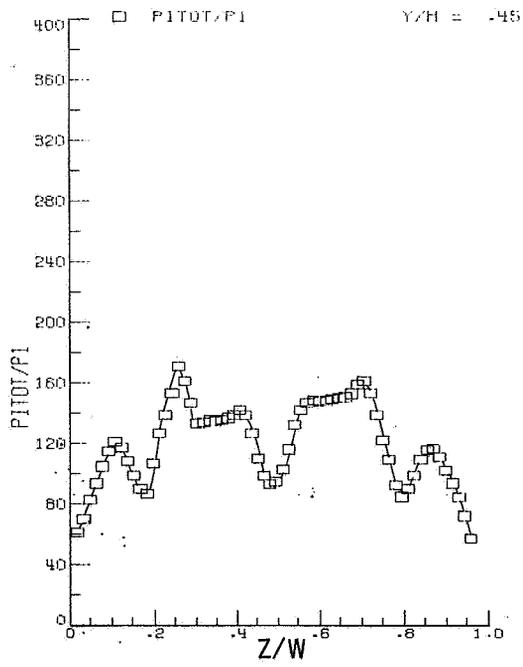
Figure 63.- Concluded.



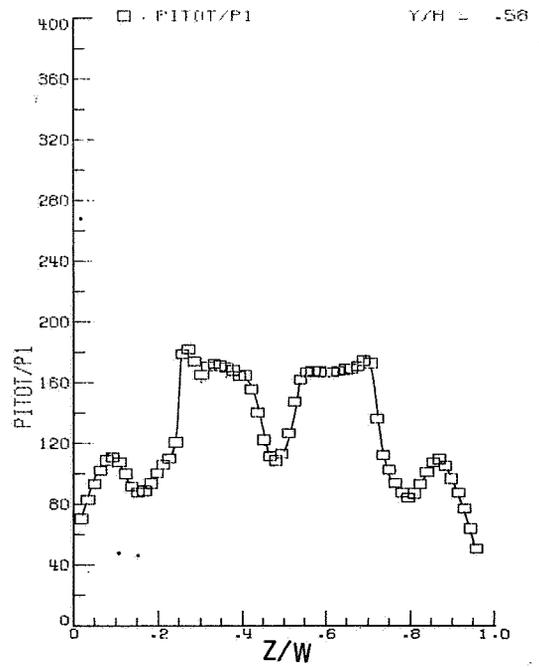
(a)  $Y/H = 0.18$ .



(b)  $Y/H = 0.31$ .

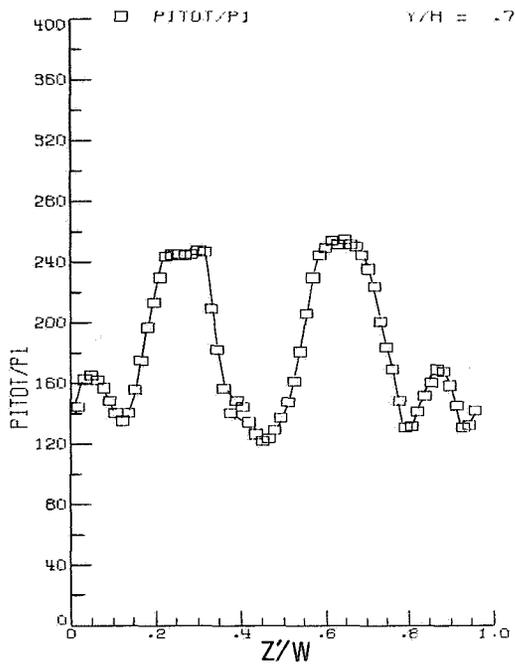


(c)  $Y/H = 0.45$ .

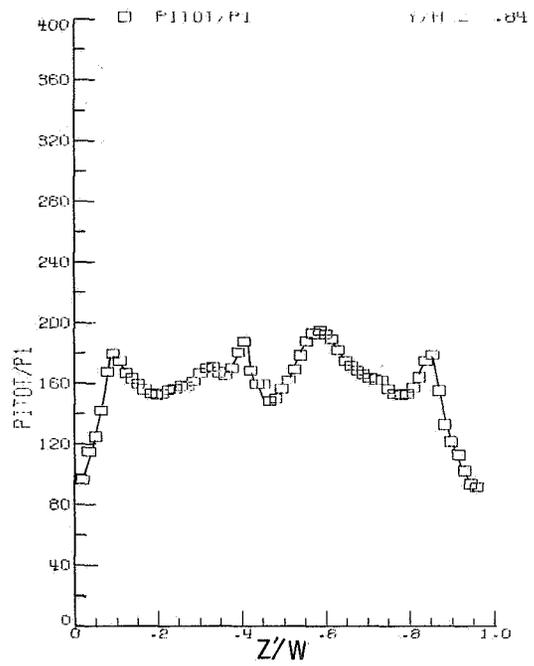


(d)  $Y/H = 0.58$ .

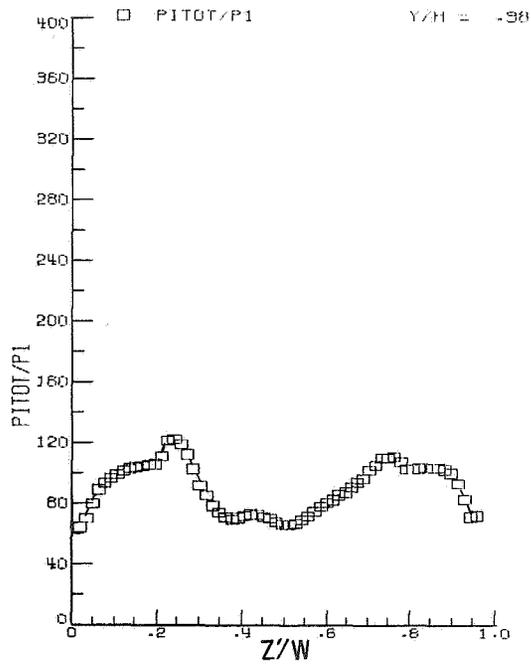
Figure 64.- Pitot-pressure surveys at capture station.  $M_1 = 6.0$ .



(e)  $Y/H = 0.71$ .



(f)  $Y/H = 0.84$ .



(g)  $Y/H = 0.98$ .

Figure 64.- Concluded.

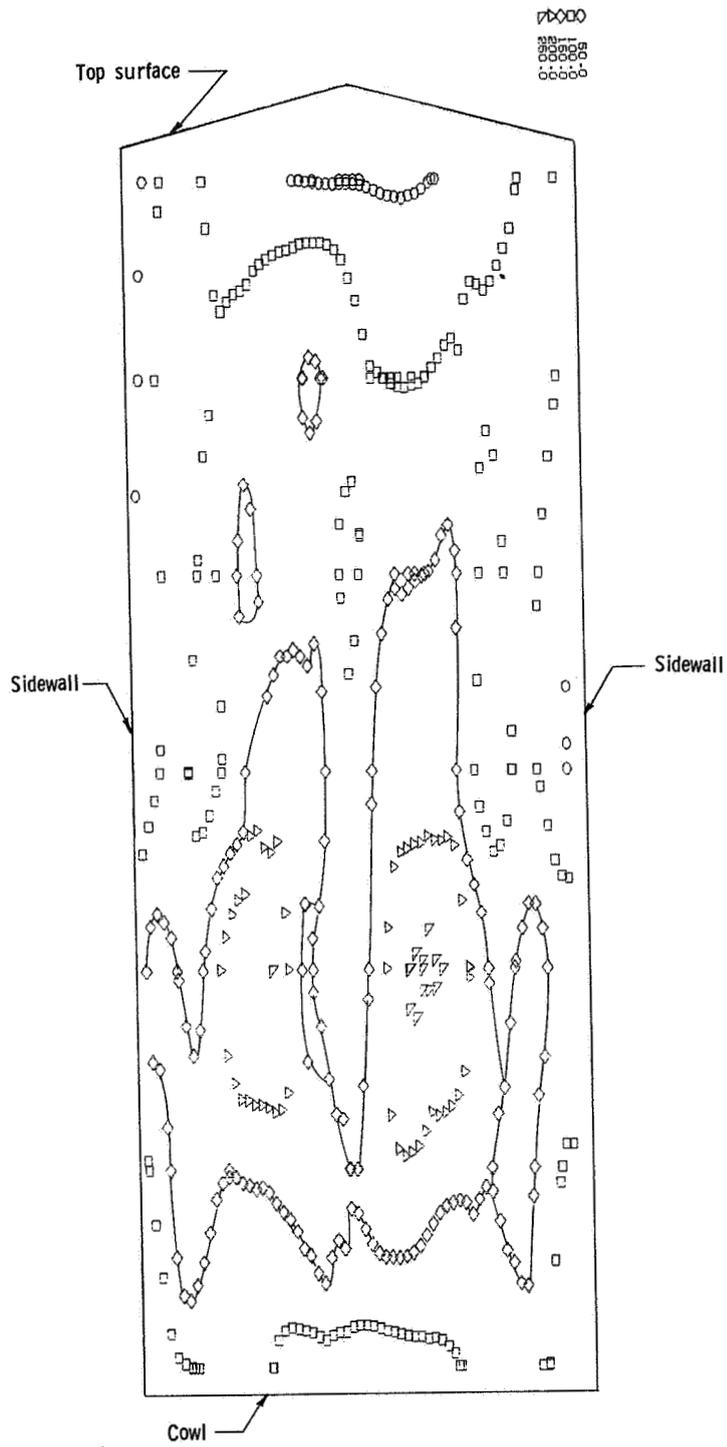


Figure 65.- Capture station.  $p_{\text{pitot}}/p_1$ .

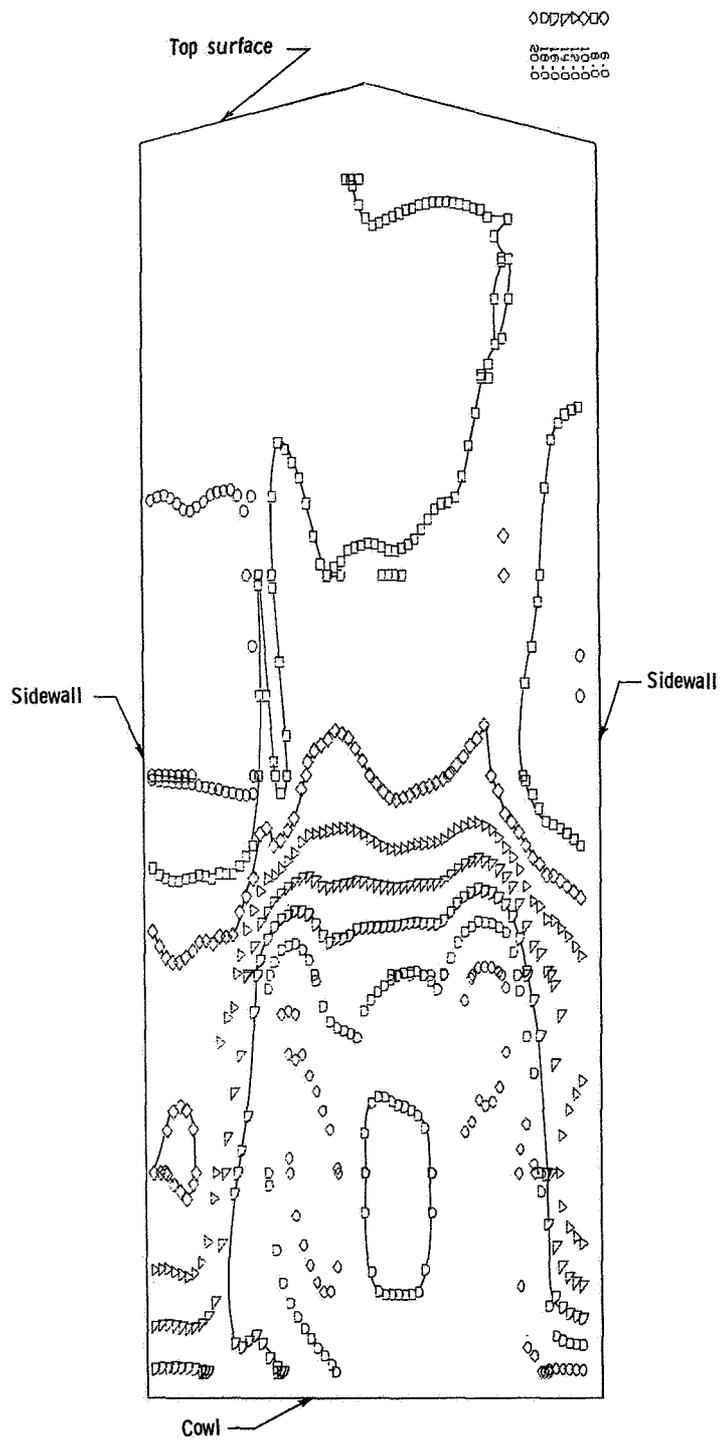


Figure 66.- Capture station.  $p/p_1$ .

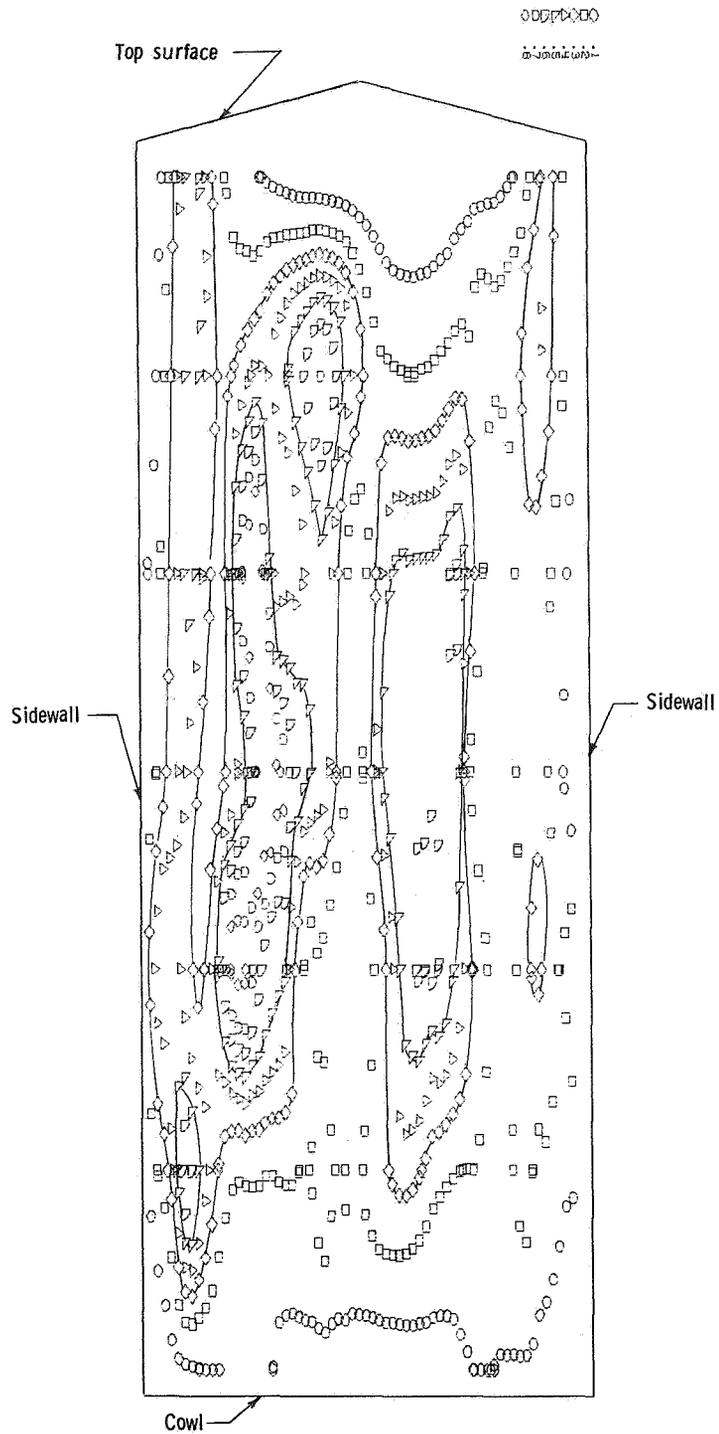


Figure 67.- Capture station total-pressure recovery.



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—NATIONAL AERONAUTICS AND SPACE ACT OF 1958

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